

Interprocedural register allocation for the WAM based on source-to-source transformations.

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- new intermediate language — Continuation Prolog
- transformation driven optimization, global analysis not required
- improved code generation for WAM and BinWAM
- minimal extension of WAM-code generation integrated into SICStus

Problems with current implementations

$e \longrightarrow "t".$

$e \longrightarrow "o", e, e.$

$$\frac{\overbrace{e([0't|Xs], Xs).}^{Xs} \quad \overbrace{e([0'o|Xs0], Xs) \leftarrow e(Xs0, Xs1), e(Xs1, Xs).}^{\begin{matrix} Xs0 \\ \xrightarrow{\hspace{1cm}} \\ Xs1 \\ \xrightarrow{\hspace{1cm}} \\ Xs \end{matrix}}}{e \longrightarrow "o", e, e.}$$

Problems in WAM:

- short lifetime of registers
- argument register bottleneck

$$\frac{\overbrace{e([0'o|\overbrace{Xs0}, Xs) \leftarrow e(\overbrace{Xs0}, \overbrace{Xs1}, e(\overbrace{Xs1}, Xs). \%}^{Xs0} \quad \overbrace{Xs1}^{Xs1}}^{Xs}}{\text{lifetime of variables disjoint}}$$

- cannot be solved by mode analysis (influence of usage, e.g. $\leftarrow e(Xs, []).$)
- cannot be solved by fold/unfold (lacks context between goals)

Continuation Prolog

```
[ e([0't|Xs],Xs) ] ←  
e([0't|Xs],Xs).  
[].  
[ e([0'o|Xs0],Xs) ] ←  
e([0'o|Xs0],Xs) ← [ e(Xs0,Xs1),  
e(Xs0,Xs1),  
e(Xs1,Xs)].  
e(Xs1,Xs).
```

- clauses: multiple heads — multiple goals, order significant

```
[a,b] ←  
[c].
```

```
← inferencediff([a,b,d], [c,d]).
```

Outline of interprocedural register allocation

contprolog

(CProg0

) ←

contprolog_ebctransformed (CProg0,CProg

) % EBC-Transformation

(Prolog→) Continuationprolog→ Transformed

Outline of interprocedural register allocation

contprolog_llprologallocated (CProg0, LLProg) ←

contprolog_ebctransformed (CProg0,CProg), % EBC-Transformation

contprolog_llprolog (CProg, LLProg). %

(Prolog→) Continuationprolog→ Transformed → Low-Level Prolog → WAM

1, 2,

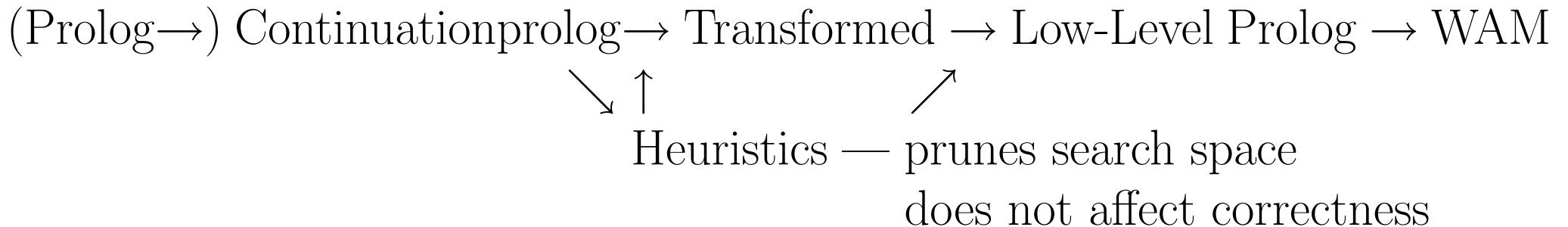
Outline of interprocedural register allocation

```
contprolog_llprologallocated_(CProg0, LLProg, Anns) ←
```

```
    contprolog_(CProg0, Anns), % Heuristics
```

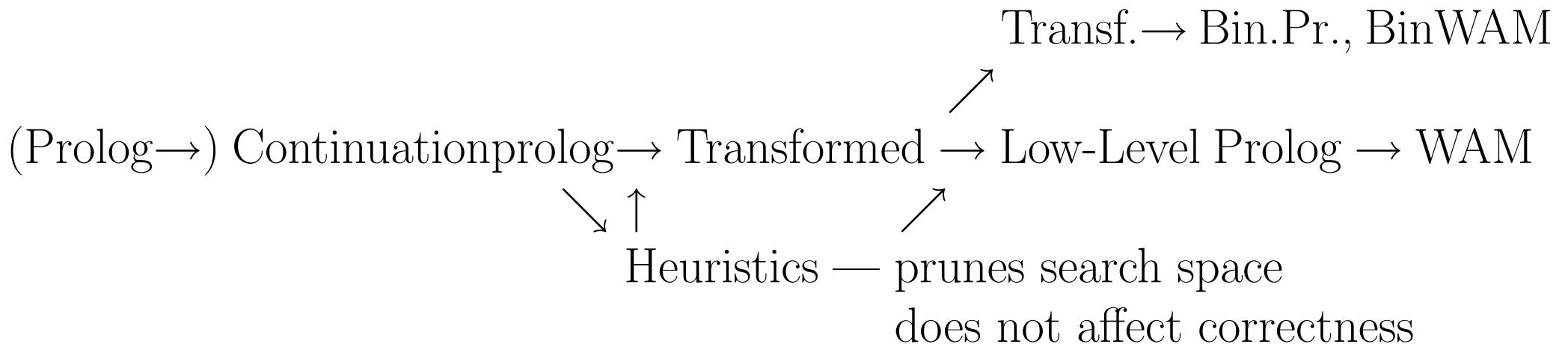
```
contprolog_ebctransformed_(CProg0,CProg, Anns), % EBC-Transformation
```

```
contprolog_llprolog_(CProg, LLProg, Anns). %
```



Outline of interprocedural register allocation

```
contprolog_llprologallocated_(CProg0, LLProg, Anns) ←  
    contprolog_(CProg0, Anns), % Heuristics  
    contprolog_ebctransformed_(CProg0,CProg, Anns), % EBC-Transformation  
    contprolog_llprolog_(CProg, LLProg, Anns). %
```



EBC- (*equality based continuation*) transformation system

Preserves operational equivalence of Continuation Prolog programs

Equations $s \doteq t$ for alternative representations

$u \cdot s\theta \cdot v$ is equivalent to $u \cdot t\theta \cdot v$

$[old(a_1, \dots a_n, b_1, \dots b_m)] \doteq [new1(a_1, \dots a_n), new2(b_1, \dots b_m)]$ a_i, b_i distinct vars

Compilation

body = $u \cdot s\theta \cdot v$ is translated into $u \cdot t\theta \cdot v$

heads All heads are rewritten.

add interface predicate (required for meta-calls and entry-points)

$[old(a_1, \dots a_n, b_1, \dots b_m)] \leftarrow [new1(a_1, \dots a_n), new2(b_1, \dots b_m)]$

Simplification $h \cdot r \leftarrow b \cdot r$ simplifies to $h \leftarrow b$

if r contains only variables not in h and b

Example: Translation of arithmetical expressions

```
%                                         % Output unifications regrouped
expr(A+B,T) —> [expr(A+B,T,Xs0,Xs)] ←
                    [ expr(A,TA,Xs0,Xs1),
                      expr(B,TB,Xs1,Xs2),
                      Xs2 = ['add'(TA,TB,Tx)|Xs3],
                      [Tx,Xs3] = [T,Xs]
                    ].
```

Example: Splitting output arguments

$$[\text{expr}(E, T, X_{S0}, X_S)] \doteq [\text{expr1}(E, X_{S0}), r(T, X_S)].$$

$\llbracket [\![\text{Tx}, \text{Xs}0] = [\![\text{T}, \text{Xs}]\!] \rrbracket \doteq \llbracket =([\![\text{Tx}, \text{Xs}0]\!]), \text{r}(\text{T}, \text{Xs}) \rrbracket$.

```
[expr(E,T,Xs0,Xs)] ← [expr1(A+B,Xs0), r(T,Xs)] ←
[expr1(E,Xs0),
r(T,Xs)
].
[expr1(A,Xs0),
r(TA,Xs1),
expr1(B,Xs1),
```

```

[=([T,Xs]), r(T,Xs)] ←
[].
Xs2 = ['add'(TA,TB,Tx)|Xs3],
      =([Tx,Xs3]),
      r(T,Xs)
].

```

Example: Splitting output arguments and simplification

$$[\text{expr}(E, T, X_{S0}, X_S)] \doteq [\text{expr1}(E, X_{S0}), r(T, X_S)].$$

$$[[T_X, X_S 0] = [T, X_S]] \doteq [=([T_X, X_S 0]), r(T, X_S)].$$

```

[expr(E,T,Xs0,Xs)] ←
[ expr1(E,Xs0),
r(T,Xs)
].
[expr1(A+B,Xs0), r(T,Xs)] ←
[ expr1(A,Xs0),
r(TA,Xs1),
expr1(B,Xs1),
r(TB,Xs2),
Xs2 = ['add'(TA,TB,Tx)|Xs3],
=([Tx,Xs3]),
r(T,Xs)
].
[=([T,Xs]), r(T,Xs)] ←
[].

```

1, 2.

Continuation Prolog to low-level Prolog.

- AND-control mapped onto stack
- only a subset can be translated
 - Predicate functors. Occur as the first element in the head.
 - Continuation functors. Occur as the second element in the head.

must be disjoint

- empty body for clauses with continuation functor in the head
- continuation functor must be the same for all clauses of the same predicate

```
[ e(Xs), r(Xs0) ] ←  
[ e(Xs1), r(Xs0), e(Xs), r(Xs1) ].
```

Example: translation into low-level Prolog

```
[expr1(A+B,Xs0)] ←  
  [ expr1(A,Xs0),  
    r(TA,Xs1),  
    expr1(B,Xs1),  
    r(TB,Xs2),  
    Xs2 = ['add'](TA,TB,Tx)|Xs3],  
    =([Tx,Xs3])  
].
```

```
expr1(A+B,Xs0) ←  
  expr1(A,Xs0),  
  'SOURCE'(+TA,+Xs1),  
  expr1(B,Xs1),  
  'SOURCE'(+TB,+Xs2),  
  Xs2 = ['add'](TA,TB,T)|Xs3],  
  'SINK'(+T,+Xs3).
```

Low level-Prolog to WAM-code

Two low level built-ins.

- 'SINK'/ n : ensure that n values are in registers
- 'SOURCE'/ n : assume that n values are in registers

```
[pop(C,P)] ←  
  [ pop(C),  
    r(P) ].
```

`pop(china, 8250).`

```
[pop(china), r(8250)] ←  
  [].
```

`pop(india, 5863).`

`... .`

```
[pop(india), r(5863)] ←  
  [].
```

`... .`

```
pop(C,P) ←  
  pop(C),  
  'SOURCE'(-,+P).
```

```
pop(china) ←  
  'SINK'(-,(8250)).
```

```
pop(india) ←  
  'SINK'(-,(5863)).
```

`... .`

```
[allocate  
,get_y_variable(0,1)  
,init([])  
,call(pop/1,1)  
,get_y_value(0,1)  
,deallocate  
,execute(true/0)].
```

```
[get_constant_x0(china)  
,put_constant(8250,1)  
,proceed].
```

```
[get_constant_x0(india)  
,put_constant(5863,1)  
,proceed].
```

Final example code

| % Prolog code | % Original WAM | % Optimized WAM | % ll-Prolog |
|---|---|---|---|
| <code>expr(I, T, Xs0,Xs) ← integer(I), !, I = T, Xs0 = Xs.</code> | <code>[builtin(integer(0),else) ,cutb ,get_x_val(1,0) ,get_x_val(2,3) ,proceed].</code> | <code>[builtin(integer(0),else) ,cutb ,proceed].</code> | <code>expr1(I, Xs0) ← integer(I), !, 'SINK'(+I, +Xs0).</code> |
| <code>expr(A+B, T, Xs0, Xs) ←</code> | <code>[get_str_x0((+)/2) ,allocate ,get_y_var(4,3) ,get_y_var(3,1) ,unify_x_var(0) ,unify_y_var(5) ,put_y_var(1,1) ,put_y_var(6,3) ,init([0,2]) ,call(expr/4,7) ,put_y_val(5,0) ,put_y_first_val(2,1) ,put_y_unsafe_val(6,2) ,put_y_first_val(0,3)</code> | <code>[get_str_x0((+)/2) ,unify_x_var(0) ,allocate ,unify_y_var(1) ,init([0]) ,call(expr1/2,2) ,get_y_first_val(0,0)%%</code> | <code>expr1(A+B, Xs0) ← 'SOURCE'(+TA,+Xs1),</code> |
| <code>expr(A,TA,Xs0,Xs1), expr(B,TB,Xs1,Xs2), Xs2 = [,call(expr/4,5) ,put_y_val(0,0) ,get_list(0) ,unify_temp_var(0) ,unify_y_local_val(4) ,get_temp_str('add'/3,0) ,unify_y_local_val(1) ,TB, ,unify_y_local_val(2) ,unify_y_local_val(3) ,deallocate ,execute(true/0)].</code> | <code>,put_y_val(1,0)%% ,call(expr1/2,1) ,get_list(1) ,unify_temp_var(2) ,unify_x_var(1) ,get_temp_str('add'/3,2) ,unify_y_local_val(0) ,unify_x_local_val(0) ,unify_x_var(0) ,deallocate ,execute('SINK'/2)].</code> | <code>expr1(B, Xs1), 'SOURCE'(+TB,+['add'(TA, TB, T) Xs]), 'SINK'(+T,+Xs).</code> | |

+ fewer instructions

+ simpler instructions (less trail checking,
fewer general unifications)

+ 30% faster

+ smaller environments (7+4 vs. 2+1 vars)

+ fewer argument registers (4 vs. 2)

Blocked goals/Constraints

- life registers in call, execute and heapmargin_call
- Simulating block

```
← block predicate(-, ...).  
predicate(I1, ...) ←  
    var(I1),  
    !,  
    blockable_predicate(I1,..., O1,...),  
    'SINK'(+O1,...).  
predicate(_I1, ...) ←  
    ... .
```

```
← block blockable_predicate(-, ?, ?, ?).  
blockable_predicate(I1,..., O1,...) ←  
    predicate(I1,...),  
    'SOURCE'(+O1,...).
```

Direct compilation of DCGs

a →
[].
a(Xs) ←
'SINK'(-,+Xs).

b(1) →
[].
b(1, Xs) ←
'SINK'(-,+Xs).

c(1,2) →
[].
c(1, Xs, 2) ←
'SINK'(-,+Xs).

```

qsorted([E|Es]) —>
{partition(Es,E,Es1,Es2)},
qsorted(Es1),
[E],
qsorted(Es2).

qsorted([]) —>
[].

```

```

qsorted([E|Es], Xs0) ←
partition(Es,E,Es1,Es2),
qsorted(Es1, Xs0),
'SOURCE'(-,+[E|Xs1]),
qsorted(Es2, Xs1).

qsorted([], Xs0) ←
'SINK'(-,+Xs0).

```

```

phrase_qsorted(Es, Xs0,Xs) ←
qsorted(Es, Xs0),
'SOURCE'(-,+Xs).

```

Benchmark results

no code duplication, number of WAM instructions reduced

| existing | | | | artificial | | | |
|----------|------------|-----------|-------------|------------|------------|-----------|-------------|
| | modif/orig | EBC/modif | tuned/modif | | modif/orig | EBC/modif | tuned/modif |
| expr | 1.53 | 1.20 | 1.30 | e | — | 1.09 | — |
| fact 10 | — | 1.06 | 2.05 | e+1 | — | 1.55 | — |
| fact 100 | — | 1.02 | 1.05 | e+2 | — | 1.99 | — |
| qsort | 1.00 | 1.02 | 1.14 | e+3 | — | 2.29 | — |
| query | — | 1.11 | 1.21 | de | — | 1.27 | — |
| serial | — | 1.00 | 1.16 | de+1 | — | 1.67 | — |
| d-divide | 1.18 | — | 1.03 | de+2 | — | 2.13 | — |
| d-log | 1.55 | — | 1.00 | de+3 | — | 2.41 | — |
| d-ops | 1.25 | — | 1.05 | | | | |
| d-times | 1.18 | — | 1.05 | | | | |
| chat | — | 1.23 | 1.31 | | | | |

□

Related Work

Mode analysis: tied to actual usage & control strategy

- depends on control strategy
- depends on actual usage
- + optimizes not steadfast programs

Aquarius Prolog: uninitialized register conversion

Output value placement: cost model to minimize tradeoffs LCO/registers

Destructive updates: HAG (Hidden Accumulator Grammar) uses back-trackable destructive assignment

- coroutining impossible
- EBC+register trailing produces same effect without destructive assignment

Limitations

Steadfastness required

```
expr((X is Expr), Code) ←  
    phrase(expr(Expr, X), Code).
```

```
expr(V, V) → {var(V)}, !. % blocking optimization
```

```
expr(I, I) → {integer(I)}, !. % blocking optimization
```

```
expr(A+B, T) → expr(A, TA), expr(B, TB), ['add'](TA, TB, T).  
expr(A-B, T) → expr(A, TA), expr(B, TB), ['sub'](TA, TB, T).  
expr(A*B, T) → expr(A, TA), expr(B, TB), ['mul'](TA, TB, T).  
expr(A/B, T) → expr(A, TA), expr(B, TB), ['div'](TA, TB, T).  
← expr((1 is Expr), Code).
```

Limitations

Steadfastness required

```
expr((X is Expr), Code) ←  
    phrase(expr(Expr, X), Code).
```

```
expr(V, V) → {var(V)}, !. % blocking optimization  
expr(V, T) → {var(V)}, !, {V = T}.  
expr(I, I) → {integer(I)}, !. % blocking optimization  
expr(I, T) → {integer(I)}, !, {I = T}.  
expr(A+B, T) → expr(A, TA), expr(B, TB), ['add'](TA, TB, T).  
expr(A-B, T) → expr(A, TA), expr(B, TB), ['sub'](TA, TB, T).  
expr(A*B, T) → expr(A, TA), expr(B, TB), ['mul'](TA, TB, T).  
expr(A/B, T) → expr(A, TA), expr(B, TB), ['div'](TA, TB, T).  
← expr((1 is Expr), Code).
```

Conclusion

- supports differences, and steadfast programs
- simulating states gets cheaper
- independent of usage of predicates — optimization of libraries possible
- supports Prolog with blocked goals, constraints

Further work

- adaptations of formalisms like EDCGs (require no analysis)
- extending the lifetime of registers
 - allocation of context arguments
 - caller/callee saved registers