Fortgeschrittene funktionale Programmierung LVA 185.A05, VU 2.0, ECTS 3.0 SS 2013 (Stand: 27.06.2013)

Jens Knoop



Technische Universität Wien Institut für Computersprachen



Table of Contents

Contents

Chap. 2

Chap. 4

Chap. 5

Chap. 6

Chap. 7

Chap. 8

Chap. 9

Chap 10

Chap. 11

Chap 12

Chap. 13

Chap. 14

Chap. 15

Chap. 16

Chap. 17

Table of Contents (1)

Part I: Motivation

► Chap. 1: Why Functional Programming Matters

- 1.1 Setting the Stage
- 1.2 Glueing Functions Together
- 1.3 Glueing Programs Together
- 1.4 Summing Up

Part II: Programming Principles

- ► Chap. 2: Programming with Streams
 - 2.1 Streams
 - 2.2 Stream Diagrams
 - 2.3 Memoization
 - 2.4 Boosting Performance

Contents

	4
	6
	7
	9
	10
	11
Chap.	12
Chap.	13
Chap.	14
Chap.	15
Chap.	16
Chap.	17

Table of Contents (2)

	Chap. 3: Programming with Higher-Order Functions:
	Algorithm Patterns
	3.1 Divide-and-Conquer
	3.2 Backtracking Search
	3.3 Priority-first Search
	3.4 Greedy Search
	3.5 Dynamic Programming
	Chap. 4: Equational Reasoning
•	Chap. 4: Equational Reasoning 4.1 Motivation
•	4.1 Motivation
•	4.1 Motivation4.2 Functional Pearls
	4.1 Motivation4.2 Functional Pearls4.3 The Smallest Free Number
	 4.1 Motivation 4.2 Functional Pearls 4.3 The Smallest Free Number 4.4 Not the Maximum Segment Sum

Contents

Table of Contents (3)

Part III: Quality Assurance	
► Chap. 5: Testing	
5.1 Defining Properties	
5.2 Testing against Abstract Models	
5.3 Testing against Algebraic Specifications	
5.4 Quantifying over Subsets	
5.5 Generating Test Data	
5.6 Monitoring, Reporting, and Coverage	
5.7 Implementation of QuickCheck	Cha
3.1 Implementation of Quickencek	Cha
	Cha

Contents

Table of Contents (4)

	Contents
Chap. 6: Verification	
6.1 Equational Reasoning – Correctness by Construction	
6.2 Basic Inductive Proof Principles	
6.2.1 Natural Induction	Chap. 4
6.2.2 Strong Induction	
6.2.3 Structural Induction	Chap. 6
6.3 Inductive Proofs on Algebraic Data Types	Chap. 7
6.4.1 Induction and Recursion	
6.3.2 Inductive Proofs on Trees	Chap. 9
6.3.3 Inductive Proofs on Lists	Chap. 10
6.3.4 Inductive Proofs on Partial Lists	Chap. 11
6.3.5 Inductive Proofs on Streams	Chap. 12
6.4 Approximation	Chap. 13
6.5 Coinduction	Chap. 14
6.6 Fixed Point Induction	Chap. 15
6.7 Other Approaches, Verification Tools	Chap. 16
	Chap. 17
	 6.1 Equational Reasoning - Correctness by Construction 6.2 Basic Inductive Proof Principles 6.2.1 Natural Induction 6.2.2 Strong Induction 6.2.3 Structural Induction 6.3 Inductive Proofs on Algebraic Data Types 6.4.1 Induction and Recursion 6.3.2 Inductive Proofs on Trees 6.3.3 Inductive Proofs on Lists 6.3.4 Inductive Proofs on Partial Lists 6.3.5 Inductive Proofs on Streams

Table of Contents (5)	
Part IV: Advanced Language Concepts	Content: Chap. 1
► Chap. 7: Functional Arrays	
 Chap. 8: Abstract Data Types 8.1 Stacks 8.2 Queues 8.3 Priority Queues 8.4 Tables 	Chap. 4 Chap. 5 Chap. 6 Chap. 7 Chap. 8 Chap. 9
► Chap. 9: Monoids	Chap. 10
 Chap. 10: Functors 10.1 Motivation 10.2 Constructor Class Functor 10.3 Applicative Functors 10.4 Kinds of Types and Type Constructors 	Chap. 11 Chap. 12 Chap. 13 Chap. 14 Chap. 14 Chap. 15 Chap. 16 Chap. 17

-

Table of Contents (6)

Chap. 11: Monads 11.1 Motivation 11.2 Constructor Class Monad 11.3 Predefined Monads 11.4 Constructor Class MonadPlus 11.5 Monadic Programming 11.6 Monadic Input/Output 11.7 A Fresh Look at the Haskell Class Hierarchy Chap. 12: Arrows

Contents

Table of Contents (7)

Part V: Applications

- Chap. 13: Parsing
 13.1 Combinator Parsing
 13.2 Monadic Parsing
- ► Chap. 14: Logical Programming Functionally
- Chap. 15: Pretty Printing
- ► Chap. 16: Functional Reactive Programming
 - 16.1 An Imperative Robot Language
 - 16.2 Robots on Wheels
 - 16.3 More on the Background of FRP

Contents

able of Contents (8)	
Part VI: Extensions and Prospectives	Contents Chap. 1
 Chap. 17: Extensions to Parallel and "Real World" Functional Programming 	
17.1 Parallelism in Functional Languages17.2 Haskell for "Real World Programming"	Chap. 4 Chap. 5 Chap. 6
Chap. 18: Conclusions and Prospectives	Chap. 7
BibliographyAppendix	Chap. 8 Chap. 9
 A Mathematical Foundations A.1 Sets and Relations A.2 Partially Ordered Sets A.3 Lattices 	Chap. 10 Chap. 11 Chap. 12 Chap. 13 Chap. 14
A.4 Complete Partially Ordered SetsA.5 Fixed Point TheoremsA.6 Cones and Ideals	Chap. 15 Chap. 16 Chap. 17

٦

Contents

Part I Motivation

Sometimes, the elegant implementation is a function. Not a method. Not a class. Not a framework. Just a function.

John Carmack

Contents 12/1355

Motivation

The preceding, a quote from a recent article by Yaron Minsky:

OCaml for the Masses
 ...why the next language you learn should be functional.
 Communications of the ACM 54(11):53-58, 2011.

The next, a quote from a classical article by John Hughes:

Why Functional Programming Matters ...an attempt to demonstrate to the "real world" that functional programming is vitally important, and also to help functional programmers exploit its advantages to the full by making it clear what those advantages are. Computer Journal 32(2):98-107, 1989.

Contents

Chapter 1

Why Functional Programming Matters

Contents Chap. 1

Chap. 14

Chap. 15

Why Functional Programming Matters

Reconsidering a position statement by John Hughes that is based on an internal 1984 memo at Chalmers University, and has slightly revised been published in:

- Computer Journal 32(2):98-107, 1989.
- Research Topics in Functional Programming. David Turner (Ed.), Addison-Wesley, 1990.
- http://www.cs.chalmers.se/~rjmh/Papers/whyfp.html

"...an attempt to demonstrate to the "real world" that functional programming is vitally important, and also to help functional programmers exploit its advantages to the full by making it clear what those advantages are."

Contents

Chap. 1

Chapter 1.1 Setting the Stage

Introductory Statement

A matter of fact:

- Software is becoming more and more complex
- Hence: Structuring software well becomes paramount
- Well-structured software is more easily to write, to debug, and to be re-used

Claim:

- Conventional languages place conceptual limits on the way problems can be modularized
- Functional languages push these limits back
- ► Fundamental: Higher-order functions and lazy evaluation

Next:

Providing evidence for this claim

Contents

(17/1355)

Background

Functional programming owes its name to the facts that

- programs are composed of only functions
 - the main program is itself a function
 - it accepts the program's input as its arguments and delivers the program's output as its result
 - it is defined in terms of other functions, which themselves are defined in terms of still more functions (eventually by primitive functions)

Contents

18/1355

Folk Knowledge: Soft Facts

... of characteristics & advantages of functional programming:

Functional programs are

- free of assignments and side-effects
- function calls have no effect except of computing their result
- $\Rightarrow\,$ functional programs are thus free of a major source of bugs
 - the evaluation order of expressions is irrelevant, expressions can be evaluated any time
 - programmers are free from specifying the control flow explicitly
 - expressions can be replaced by their value and vice versa; programs are referentially transparent
- \Rightarrow functional programs are thus easier to cope with mathematically (e.g. for proving their correctness)

1.1 19/1355 ...the commonly found previous list of characteristics and advantages of functional programming is

- essentially a negative "is-not" characterization
 - "It says a lot about what functional programming is not (it has no assignments, no side effects, no explicit specification of flow of control) but not much about what it is."

1.1

Folk Knowledge: Hard(er) Facts

Aren't there any hard(er) facts providing evidence for substantial and "real" advantages?

Yes, there are, e.g.:

- Functional programs are
 - ► a magnitude of order smaller than conventional programs
 - $\Rightarrow\,$ functional programmers are thus much more productive

Open Issue:

- ► Why?
- Can it be concluded from the advantages of the "standard catalogue," i.e., by dropping features?
 Hardly.

This is not convincing. Overall, it reminds more to a medieval monk who denies himself the pleasures of life in the hope of getting virtuous.

1.1 21/1355

Summing up: Lesson learnt

► The "standard catalogue" is not satisfying

- It does not provide any help in exploiting the power of functional languages
 - Programs cannot be written which are particularly lacking in assignment statements, or which are particularly referentially transparent
- It does not provide a yardstick of program quality, thus no model to strive for

▶ We need a positive characterization of the vital nature of

- functional programming, of its strengths
- what makes a "good" functional program, of what a functional programmer should strive for

Contents

22/1355

Towards a Positive Characterization

Structured vs. non-structured programming

...provides an analogue to compare with:

Structured programs are

- free of goto-statements ("goto considered harmful")
- blocks in structured programs are free of multiple entries and exits
- $\Rightarrow\,$ easier to mathematically cope with than unstructured programs

Note: This is essentially a negative "is-not"-characterization, too.

Contents

1.1 (23/1355)

Towards a Positive Characterization (Cont'd)

Conceptually more important:

Structured programs are:

- designed modularly in contrast to non-structured programs
- Structured programming is more efficient/productive for this reason
 - Small modules are easier and faster to write and to maintain
 - Re-use becomes easier
 - Modules can be tested independently

Note: Dropping goto-statements is not an essential source of productivity gain.

- Absence of gotos supports "programming in the small"
- Modularity supports "programming in the large"

Contents

24/1355

Thesis

- The expressiveness of a language that supports modular design depends much on the power of the concepts and primitives allowing to combine solutions of subproblems to the solution of the overall problem (keyword: glue; example: making of a chair)
- Functional programming provides two new, especially powerful glues:
 - 1. Higher-order functions (functionals)
 - 2. Lazy evaluation

They offer conceptually new opportunities for modularization and re-use (beyond the more technical ones of lexical scoping, separate compilation, etc.), and make them more easily to achieve.

 Modularization (smaller, simpler, more general) is the guideline, which should be followed by functional programmers in the course of programming

Contents

25/1355

In the following

	1.4		
 Glueing functions together 			
→ The clou: Higher-order functions			
107 The clou. The field of the functions			
 Glueing programs together 			
	Chap. 7		
\rightsquigarrow The clou: Lazy evaluation			
	Chap. 9		
	Chap. 1		
	Chap. 1		

Chapter 1.2 Glueing Functions Together

Glueing Functions Together

```
Syntax (in the flavour of Miranda<sup>TM</sup>):
```

Lists

listof X ::= nil | cons X (listof X)

Abbreviations (for convenience)

[]	means	nil						
[1]	means	cons	1	nil				
[1,2,3]	means	cons	1	(cons	2	(cons	3	nil)))

Example:

Adding the elements of a list

sum nil = 0
sum (cons num list) = num + sum list

Chap. 1 1.1 1.2 1.3 1.4 Chap. 2 Chap. 3 Chap. 4 Chap. 5 Chap. 6 Chap. 7 Chap. 8

Observation

Only the framed parts are specific to computing a sum:



...i.e., computing a sum of values can be modularly decomposed by properly combining

- a general recursion pattern and
- a set of more specific operations

(see framed parts above).

Exploiting the Observation

1. Adding the elements of a list sum = reduce add 0 where add x y = x+y

This reveals the definition of **reduce** almost immediately:

(reduce f x) nil = x (reduce f x) (cons a l) = f a ((reduce f x) l)Recall +--+ sum nil = 0 1 +--+ sum (cons num list) = sum list num

Contents

30/1355

Immediate Benefit: Re-use

Without any further programming effort we obtain implementations for other functions, e.g.:

 Computing the product of the elements of a list product = reduce multiply 1 where multiply x y = x*y
 Test, if *some* element of a list equals "true" anytrue = reduce or false
 Test, if *all* elements of a list equal "true" alltrue = reduce and true Contents

(31/1355)

Intuition

The call (reduce f a) can be understood such that in a list of elements all occurrences of cons are replaced by f nil by a Examples: reduce add 0: cons 1 (cons 2 (cons 3 nil)) \rightarrow add 1 (add 2 (add 3 0)) ->> 6 reduce multiply 1: cons 1 (cons 2 (cons 3 nil)) ->> multiply 1 (multiply 2 (multiply 3 1)) ->> 6

1.2 (32/1355)

More Applications 1(5)

Observation: reduce cons nil copies a list of elements This allows:

Concatenation of lists append a b = reduce cons b aExample: append [1,2] [3,4] ->> reduce cons [3,4] [1,2] \rightarrow (reduce cons [3,4]) (cons 1 (cons 2 nil)) \rightarrow { replacing cons by cons and nil by [3,4] } cons 1 (cons 2 [3,4]) \rightarrow cons 1 (cons 2 (cons 3 (cons 4 nil))) ->> [1.2.3.4]

1.2 (33/1355) More Applications 2(5)

6. Doubling each element of a list doubleall = reduce doubleandcons nil where doubleandcons num list = cons (2*num) list

(34/1355)

More Applications 3(5)

The function doubleandcons can be modularized further:

```
First step
                                                             1.2
    doubleandcons = fandcons double
      where double n = 2*n
             fandcons f el list = cons (f el) list
  Second step
    fandcons f = cons . f
    where "." denotes the composition of functions:
    (f \cdot g) h = f (g h)
Note: For checking correctness consider:
 fandcons f el = (cons . f) el
                = cons (f el)
which yields as desired:
 fandcons f el list = cons (f el) list
                                                             35/1355
```

More Applications 4(5)

Putting things together, we obtain:

6a. Doubling each element of a list
 doubleall = reduce (cons . double) nil

Another step of modularization using map leads us to:

```
6b. Doubling each element of a list
doubleall = map double
map f = reduce (cons . f ) nil
```

where map applies any function f to all the elements of a list.

1.2 36/1355
More Applications 5(5)

After these preparative steps it is just as well possible:

7. Adding the elements of a matrix

summatrix = sum . map sum

Homework: Think about how summatrix works.



By decomposing (modularizing) and representing a simple function (sum in the example) as a combination of

- a higher-order function and
- some simple specific functions as arguments

we obtained a program frame (reduce) that allows us to implement many functions on lists without any further programming effort!

Generalization

...to more complex data structures: Trees: treeof X ::= node X (listof (treeof X)) Example: node 1 1 (cons (node 2 nil) 3 (cons (node 3 2 (cons (node 4 nil) nil)) nil)) 4

1.1 1.2 1.3 1.4 Chap. 2 Chap. 3 Chap. 4 Chap. 5 Chap. 6

Generalization (Cont'd)

Analogously to **reduce** on lists we introduce a functional **redtree** on trees:

```
redtree f g a (node label subtrees)
= f label (redtree' f g a subtrees)
where
redtree' f g a (cons subtree rest)
= g (redtree f g a subtree) (redtree' f g a rest)
redtree' f g a nil = a
```

Note: redtree takes 3 arguments (f, g, a)

- The first one to replace node with
- The second one to replace cons with
- The third one to replace nil with

Applications 1(4)

- 1. Adding the labels of the leaves of a tree
- 2. Generating a list of all labels occurring in a tree
- 3. A function maptree on trees replicating the function map on lists

1.2 (41/1355

Applications 2(4)

 Adding the labels of the leaves of a tree sumtree = redtree add add 0 	Chap. 1 1.1 1.2 1.3 1.4 Chap. 2
Example:	
	Chap. 4
Using the tree introduced previously, we obtain:	
	Chap. 6
add 1	Chap. 7
(add (add 2 0)	
(add (add 3	Chap. 9
(add (add 4 0) 0))	Chap. 10
	Chap. 11
0))	Chap. 12
->> 10	Chap. 13

(42/1355

Applications 3(4)

Contents

2. Generating a list of all labels occurring in a tree 1.2 labels = redtree cons append nil Example: cons 1 (append (cons 2 nil) (append (cons 3 (append (cons 4 nil) nil)) nil)) ->> [1,2,3,4]

Chap. 14

Chap. 15

Applications 4(4)

3. A function maptree on trees replicating the function map on lists

maptree f = redtree (node . f) cons nil

1.2

Summing up

- The elegance of the preceding examples is a consequence of combining
 - a higher-order function and
 - ► a specific specializing function
- Once the higher order function is implemented, lots of further functions can be implemented almost without any further effort!

1.2

Summing up (Cont'd)

Lesson learnt: Whenever a new data type is introduced, implement first a higher-order function allowing to process values of this type (e.g., visiting each component of a structured data value such as nodes in a graph or tree).

1.2

- Benefits: Manipulating elements of this data type becomes easy; knowledge about this data type is locally concentrated and encapsulated.
- Look&feel: Whenever a new data structure demands a new control structure, then this control structure can easily be added following the methodology used above (to some extent this resembles the concepts known from conventional extensible languages).

Reminder to initial Thesis

- The expressiveness of a language that supports modular design depends much on the power of the concepts and primitives allowing to combine solutions of subproblems to the solution of the overall problem (keyword: glue; example: making of a chair).
- Functional programming provides two new, especially powerful glues:
 - 1. Higher-order functions (functionals)
 - 2. Lazy evaluation

They offer conceptually new opportunities for modularization and re-use (beyond the more technical ones of lexical scoping, separate compilation, etc.), and make them more easily to achieve.

 Modularization (smaller, simpler, more general) is the guideline, which should be followed by functional programmers in the course of programming. Contents

47/1355

1.2

Reminder (Cont'd)

So far, we talked about:

 Higher-order functions as glue for glueing functions together

Next we will talk about:

Lazy evaluation as glue for glueing programs together

1.2

Chapter 1.2 Glueing Programs Together

1.3

Glueing Programs Together

Recall: A complete functional program is a function from its input to its output.

► If f and g are (such) programs, then also

g . f

is a program. Applied to input as input, it yields the output

g (f input)

- ► A possible implementation using conventional glue: ~→ Communication via files
 - Possible problems
 - Temporary files can be too large
 - f might not terminate

1.3 50/1355

Functional Glue

azy evaluation	allows a	a more	elegant	approach:
----------------	----------	--------	---------	-----------

- Decomposing a problem into a
 - generator
 - selector

component, which are then glued together.

Intuition:

The generator component "runs as little as possible" until it is terminated by the selector component.

Example 1: Computing Square Roots

Computing Square Roots (according to Newton-Raphson) Given: N Wanted: squareRoot(N) Iteration formula:

a(n+1) = (a(n) + N/a(n)) / 2

Justification: If the approximations converge to some limit a, we have:

I.e., a stores the value of the square root of \mathbb{N} .

For later comparison we consider first

...a typical imperative (Fortran-) implementation:

```
С
      N is called ZN here so that it has
С
      the right type
         X = AO
         Y = A0 + 2.*EPS
С
      The value of Y does not matter so long
С
      as ABS(X-Y).GT.EPS
         IF (ABS(X-Y).LE.EPS) GOTO 200
100
         Y = X
         X = (X + ZN/X) / 2.
         GOTO 100
200
         CONTINUE
C
      The square root of ZN is now in X
```

 \rightsquigarrow essentially monolithic, not decomposable.

Contents

13

The Functional Version 1(4)

Computing the next approximation from the previous one:

1.3

54/1355

next N x = (x + N/x) / 2

Introducing function f for the above computation, we are interested in computing the sequence of approximations:

[a0, f a0, f(f a0), f(f(f a0)),...]

The Functional Version 2(4)

The function **repeat** computes this (possibly infinite) sequence of approximations. It is the generator component in this example:

Generator:

```
repeat f a = cons a (repeat f (f a))
```

Applying repeat to the arguments next N and a0 yields the desired sequence of approximations:

```
repeat (next N) a0
```

Contents

13

The Functional Version 3(4)

Note: The evaluation of repeat (next N) a0

does not terminate!

Remedy: Computing squareroot \mathbb{N} up to a given tolerance eps > 0. Crucial: The selector component implemented by:

Selector:

Still to do: Combining the components/modules: sqrt a0 eps N = within eps (repeat (next N) a0) ~> We are done!

The Functional Version 4(4)

Contents

Summing up:

- repeat: generator component: [a0, f a0, f(f a0), f(f(f a0)),...] ...potentially infinite, no limit on the length.
- within: selector component:

Note: Lazy evaluation ensures that both programs (generator and selector) run strictly synchronized.

Re-Use of Modules

Next, we want to provide evidence that

- ► generator
- ► selector

can indeed be considered modules that can easily be re-used.

We are going to start with the re-use of the module generator.

1.3 58/1355

Evidence of Generator-Modularity

Consider a new criterion for termination:

 Instead of awaiting the difference of successive approximations to approach zero (<= eps), await their ratio to approach one (<= 1+eps)

New Selector:

Still to do: (Re-)combining the components/modules:

relativesqrt a0 eps N
= relative eps (repeat (next N) a0)

→ We are done!

Contents

59/1355

13

... of the module generator in the previous example:

The generator, i.e., the "module" computing the sequence of approximations has been re-used unchanged.

Next, we want to re-use the module selector.

Example 2: Numerical Integration

Numerical Integration

Given: A real valued function f of one real argument; two end-points a und b of an interval

Wanted: The area under f between a and b

Naive Implementation:

...supposed that the function f is roughly linear between a und b.

easyintegrate f a b = (f a + f b) * (b-a) / 2

This is sufficiently precise, however, at most for very small intervals.

Contents

Illustration



Refinements 1(4)

Idea

- Halve the interval, compute the areas for both subintervals according to the previous formula, and add the two results
- Continue the previous step repeatedly

The function integrate implements this strategy:

Generator:

Reminder:

zip (cons a s) (cons b t) = cons (pair a b) (zip s t)

Refinements 2(4)

integrate is sound but inefficient (many redundant computations of f a, f b, and f mid)

The following version of integrate is free of this deficiency:

64/1355

13

Refinements 3(4)

Obviously, the evaluation of		
integrate f a b	1.3 1.4 Chap. 2	
does not terminate!		
Remedy: Computing integrate f a b up to some limit $eps > 0$.		
-	Chap. 7 Chap. 8	
Two Selectors:	Chap. 9 Chap. 1	
Variant A: within eps (integrate f a b)	Chap. 1	
Variant B: relative eps (integrate f a b)	Chap. 1 Chap. 1	

Refinements 4(4)

Summing up:

	Generator	component:
--	-----------	------------

integrate

...potentially infinite, no limit on the length.

Selector component:

within, relative ...lazy evaluation ensures that the selector function is applied eventually \Rightarrow termination!

... of the module selector in the previous example:

The selector, i.e., the "module" picking the solution from the stream of approximate solutions has been re-used unchanged.

Again, lazy evaluation is the key to synchronize the generator and selector module!

Example 3: Numerical Differentiation

Numerical Differentiation

Given: A real valued function f of one real argument; a point x

Wanted: The slope of f at point x

Naive Implementation:

...supposed that the function ${\tt f}$ between ${\tt x}$ and ${\tt x+h}$ does not "curve much"

easydiff f x h = (f (x+h) - f x) / h

This is sufficiently precise, however, at most for very small values of h.

13

Refinements

Generate a sequence of approximations getting successively "better":

Generator:

differentiate h0 f x = map (easydiff f x) (repeat halve h0) halve x = x/2

Select a sufficiently precise approximation:

Selector:

```
within esp (differentiate h0 f x)
```

Implementing the selector: Homework

```
13
69/1355
```

The Generator/Selector Principle at a Glance



Contents

1.3

The Generator/Transformer Princ. at a Glance



Chap. 15

Summary of Findings (1)

The composition pattern, which in fact is common to all three examples becomes again obvious. It consists of a

- generator (usually looping!) and
- selector (ensuring termination thanks to lazy evaluation!)

13 (72/1355)
Summary of Findings (2)

Thesis

Modularity is the key to programming in the large

Observation

- Just modules (i.e., the capability of decomposing a problem) do not suffice
- The benefit of modularly decomposing a problem into subproblems depends much on the capabilities for glueing the modules together
- The availability of proper glue is essential!

Contents

13

Summary of Findings (3)

Facts

- Functional programming offers two new kinds of glue:
 - Higher-order functions (glueing functions)
 - Lazy evaluation (glueing programs)
- Higher-order functions and lazy evaluation allow substantially new exciting modular decompositions of problems (by offering elegant composition means) as here given evidence by an array of simple, yet impressive examples
- In essence, it is the superior glue, which makes functional programs to be written so concisely and elegantly (not the absence of assignments, etc.)

Summary of Findings (4)

Guidelines

- Functional programmers shall strive for adequate modularization and generalization
 - Especially, if a portion of a program looks ugly or appears to be too complex
- Functional programmers shall expect that
 - higher-order functions and
 - lazy evaluation

are the tools for achieving this!

Chap. 1 1.1 1.2 1.3 1.4 Chap. 2 Chap. 3 Chap. 4 Chap. 5 Chap. 6 Chap. 7

Chap. 9 Chap. 10

Chap. 11

Chap. 13

Chap. 14

Chap. 15

Chapter 1.4 Summing Up 1.4

Summing Up: Lazy or Eager Evaluation

The final conclusion of John Hughes:

- In view of the previous arguments:
 - The benefits of lazy evaluation as a glue are so evident that lazy evaluation is too important to make it a second-class citizen.
 - Lazy evaluation is possibly the most powerful glue functional programming has to offer.
 - Access to such a powerful means should not airily be dropped.

Contents

14

Outlook

John Hughes identifies

- higher-order functions
- lazy evaluation

as of vital importance for the power of the functional programming style.

In Chapter 2 and in Chapter 3 we will discuss the power they provide the programmer with in more detail:

- Stream programming: thanks to lazy evaluation.
- ► Algorithm patterns: thanks to higher-order functions.

Chapter 1: Further Reading (1)

Stephen Chang, Matthias Felleisen. The Call-by-Need Lambda Calculus, Revisited. In Proceedings of the 21st European Symposium on Programming (ESOP 2012), Springer-V., LNCS 7211, 128-147, 2012.

14

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Chapter 1: Further Reading (2)

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http://research.microsoft.com/users/simonpj/
papers/haskell-retrospective/

14

Chapter 1: Further Reading (3)

- Chris Sadler, Susan Eisenbach. Why Functional Programming? In Functional Programming: Languages, Tools and Architectures. Susan Eisenbach (Ed.), Ellis Horwood, 7-8, 1987.
- Philip Wadler. The Essence of Functional Programming. In Conference Record of the 19th ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages (POPL'92), 1-14, 1992.

Part II

Programming Principles

Contents

1.4

Chap. 9 Chap. 10 Chap. 11

Chap. 13

Chap. 14

Chap. 15

Chapter 2 Programming with Streams

Chap. 2

Motivation

Streams = Infinite Lists
 Programming with streams Applications Streams plus lazy evaluation yield new modularization principles Generator/selector Generator/filter Generator/transformer
 as instances of the Generator/Prune Paradigm Pitfalls and remedies Foundations Well-definedness Proving properties of programs with streams

Chap. 2 84/1355

Chapter 2.1 Streams

2.1 2.2

Streams

Jargon

Stream ... synonymous to infinite list and lazy list.

Streams

- (combined with lazy evaluation) allow to solve many problems elegantly, concisely, and efficiently
- are a source of hassle if applied inappropriately

More on this in this chapter.



Streams

Streams could be introduced in terms of a new polymorphic data type **Stream** such as:

data Stream a = a :* Stream a

Convention

For pragmatic reasons, however, we will model streams as ordinary lists waiving the usage of the empty list [].

This is motivated by:

Convenience/adequacy because many pre-defined (polymorphic) functions on lists can be reused this way, which otherwise would have to be defined from scratch on the new data type Stream

2.1 87/1355

First Examples of Streams

 Built-in streams in Haskell 	
[2] ->> [2,3,4,5,6,7,	
[3,5] ->> [3,5,7,9,11,	2.1 2.2
 User-defined streams in Haskell 	2.3 2.4
The infinite lists of "twos"	
2,2,2,	
In Haskell this can be realized:	
 using list comprehension: [2,2] 	
(co-) recursively: twos = 2 : twos	Chap.
Illustration	Chap.
twos ->> 2 : twos	Chap.
->> 2 : 2 : twos	Chap. 1
->> 2 : 2 : 2 : twos	Chap. 3
->>	Chap.
twos represents an infinite list: synonymously a stream	Chap -

Corecursive Definitions

Definitions of the form	
ones = 1 : ones	2.1 2.2
	2.3 2.4
twos = 2 : twos	
threes = 3 : threes	
defining the streams of "ones," "twos," and "threes" look	
like recursive definitions.	
However, they lack a base case.	Chap.
	Chap.
Definitions of the above form are called	Chap.
► corecursive	Chap.
Corecursive definitions always yield infinite objects.	Chap.
Corecursive definitions always yield infinite objects.	Chap.
	Chap.
	Chap.

More corecursively defined Streams

2.1

- The stream of natural numbers nats nats = 0 : map (+1) nats
- The stream of even natural numbers evens evens = 0 : map (+2) evens
- The stream of odd natural numbers odds odds = 1 : map (+2) odds

More Streams

The stream of natural numbers theNats = 0 : zipWith (+) ones theNats The stream of powers of an integer powers :: Int -> [Int] powers $n = [n^x | x < [0..]]$ The prelude function iterate iterate :: $(a \rightarrow a) \rightarrow a \rightarrow [a]$ iterate f x = x : iterate f (f x)The function iterate generates the stream [x, f x, (f . f) x, (f . f . f) x,...

Application: powers can be defined in terms of iterate powers n = iterate (*n) 1

2.1 91/1355

More Applications of iterate

		p. 1
ones	= iterate id 1	p. 2
	2.1 2.2 2.3	
twos	= iterate id 2 2.3 2.4	
		p. 3
threes	= iterate id 3	
nats	= iterate (+1) 0	
	Chap	
evens	= iterate (+2) 0	
	Chap	
odds	= iterate (+2) 1	p. 11
	Chap	p. 12
powers	= iterate (*n) 1 Chap	p. 13
	Chap	p. 14

Chap. 15

Functions on Streams

head :: $[a] \rightarrow a$ head $(x:_) = x$

Application

head twos \rightarrow head (2 : twos) \rightarrow 2

Note: Normal-order reduction (resp. its efficient implementation variant lazy evaluation) ensures termination in this example. It excludes the infinite sequence of reductions:

```
head twos
  ->> head (2 : twos)
  ->> head (2 : 2 : twos)
  ->> head (2 : 2 : 2 : twos)
  ->> ...
```

```
2.1
93/1355
```

Reminder

"...whenever there is a terminating reduction sequence of an expression, then normal-order reduction terminates." (Church/Rosser-Theorem)

 Normal-order reduction corresponds to leftmostoutermost evaluation

```
Recall: Let
ignore :: a -> b -> b
ignore a b = b
```

Then, both in

- ignore twos 42
- twos 'ignore' 42

the leftmost-outermost operator is given by the call ignore.

```
2.1
94/1355
```

Functions on Streams (Cont'd)

addFirstTwo :: [Integer] -> Integer addFirstTwo (x:y:zs) = x+y

Application

addFirstTwo twos ->> addFirstTwo (2:twos) ->> addFirstTwo (2:2:twos) ->> 2+2->> 4

2.1

Functions yielding Streams

Contents

```
    User-defined stream-yielding functions

  from :: Int -> [Int]
  from n = n : from (n+1)
  fromStep :: Int -> Int -> [Int]
  fromStep n m = n : fromStep (n+m) m
  Applications
  from 42 ->> [42, 43, 44,...
  fromStep 3 2 ->> 3 : fromStep 5 2
                ->> 3 : 5 : fromStep 7 2
                ->> 3 : 5 : 7 : fromStep 9 2
                ->> ...
```

2.1 96/1355

Primes: The Sieve of Eratosthenes 1(3)

Intuition

- 1. Write down the natural numbers starting at 2.
- 2. The smallest number not yet cancelled is a prime number. Cancel all multiples of this number.
- 3. Repeat Step 2 with the smallest number not yet cancelled.

Illustration

Ste	р 1	:													
2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
Ste	Step 2 ("with 2"):														
2	3		5		7		9		11		13		15		17
Ste	Step 2 ("with 3"):														
2	3		5		7				11		13				17
Ste	p 2	("	wit	h 5	"):										
2	3		5		7				11		13				17

2.1 97/1355

Primes: The Sieve of Eratosthenes 2(3) The stream of primes: primes :: [Int] primes = sieve [2..] sieve :: [Int] -> [Int] sieve (x:xs) = x : sieve [y | y < -xs, mod y x > 0]

2.1 98/1355

Primes: The Sieve of Eratosthenes 3(3) Illustration: By stepwise evaluation primes 2.1 ->> sieve [2..] ->> 2 : sieve [y | y <- [3..], mod y 2 > 0] ->> 2 : sieve (3 : [y | y <- [4..], mod y 2 > 0] ->> 2 : 3 : sieve [z | z <- [y | y <- [4..], mod y 2 > 0], mod z 3 > 0->> ... ->> 2 : 3 : sieve [z | z <- [5, 7, 9..], mod z 3 > 0->> ... ->> 2 : 3 : sieve [5, 7, 11,... ->> ...

Pitfalls in Applications

Implementing a prime number test (naively):

Let

member :: [a] \rightarrow a \rightarrow Bool member [] y = False member (x:xs) y = (x==y) || member xs y

Then

member primes 7 ... yields "True" (as expected!)

But

member primes 6 ...does not terminate!

Homework: Why fails the above implementation? How can primes be embedded into a calling context allowing us to decide if some argument is prime or not?

2.1 (100/135)

Random Numbers 1(2)	
Generating a sequence of (pseudo-) random numbers:	Contents
nextRandNum :: Int -> Int nextRandNum n = (multiplier*n + increment) 'mod' modulus	Chap. 1 Chap. 2 2.1 2.2 2.3 2.4
randomSequence :: Int -> [Int] randomSequence = iterate nextRandNum	Chap. 3 Chap. 4 Chap. 5
Choosing	Chap. 6
seed= 17489increment= 13849multiplier= 25173modulus= 65536	Chap. 7 Chap. 8 Chap. 9
we obtain the following sequence of (pseudo-) random numbers	Chap. 10 Chap. 11
[17489, 59134, 9327, 52468, 43805, 8378,	Chap. 12 Chap. 13
ranging from 0 to 65536, where all numbers of this interval occur with the same frequency.	Chap. 14 Chap. 15 Chap. 15

Random Numbers 2(2)

Often one needs to have random numbers within a range from p to q inclusive, $p{<}q.$

This can be achieved by scaling the sequence.

scale :: Float -> Float -> [Int] -> [Float]
scale p q randSeq = map (f p q) randSeq
where f :: Float -> Float -> Int -> Float
 f p q n = p + ((n * (q-p)) / (modulus-1))

Application

scale 42.0 51.0 randomSequence

2.1 (102/135)

Principles of Modularization

...related to streams:

► The Generator/Selector Principle

...e.g. computing the square root, the *n*-th Fibonacci number

- The Generator/Filter Principle
 ...e.g. computing all even Fibonacci numbers
- The Generator/Transformer Principle ...e.g. "scaling" random numbers
- Other combinations of generators, filters, and selectors

2.1 103/135

The Fibonacci Numbers 1(5)

The sequence of Fibonacci Numbers

0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89,...

is defined in terms of the function

 $fib: \mathbb{IN} \to \mathbb{IN}$ $fib(n) =_{df} \begin{cases} 0 & \text{if } n = 0\\ 1 & \text{if } n = 1\\ fib(n-1) + fib(n-2) & \text{otherwise} \end{cases}$

2.1 104/135

The Fibonacci Numbers 2(5)

We have already learned that a naive implementation like

fib :: Integer \rightarrow Integer fib 0 = 0 fib 1 = 1 fib n = fib (n-1) + fib (n-2)

...that directly exploits the recursive pattern of the underlying mathematical function is

inacceptably inefficient and slow!

2.1 105/135

The Fibonacci Numbers 3(5)

Westertien, Destancias confection								
Illustration: By stepwise evaluation								
		Chap. 2 2.1						
fib 0 ->>	0 1 call of fib	2.2						
		2.4						
fib 1 ->>	1 1 call of fib							
		Chap. 4						
fib 2 ->>	fib 1 + fib 0							
->>	1 + 0	Chap. 6						
	1 3 calls of fib	Chap. 7						
-//		Chap. 8						
		Chap. 9						
fib 3 ->>	fib 2 + fib 1	Chap. 10						
->>	(fib 1 + fib 0) + 1	Chap. 11						
->>	(1 + 0) + 1	Chap. 12						
->>	2 5 calls of fib	Chap. 13						
		Chap. 14						

Chap. 15

The Fibonacci Numbers 4(5)

The Fibonacci Numbers 5(5)

...tree-like recursion (with exponential growth!)

2.1 108/135
Reminder: Complexity 1(3)

Cp. Peter Pepper. Funktionale Programmierung in OPAL, ML, Haskell und Gofer. 2nd Edition (In German), 2003, Chapter 11.

Reminder: \mathcal{O} Notation

Let f : α → IR⁺ be a function with some data type α as domain and the set of positive real numbers as range. Then the class O(f) denotes the set of all functions which "grow slower" than f:

$$\mathcal{O}(f) =_{df} \{ h \mid h(n) \le c * f(n) \text{ for some positive} \\ \text{ constant } c \text{ and all } n \ge N_0 \}$$

2.1 (109/135)

Reminder: Complexity 2(3)

Examples of typical cost functions:

Code	Costs	Intuition: <i>input a thousandfold</i>
		<i>as large</i> means:
$\mathcal{O}(c)$	constant	equal effort
$\mathcal{O}(\log n)$	logarithmic	only tenfold effort
$\mathcal{O}(n)$	linear	also a thousandfold effort
$\mathcal{O}(n \log n)$	"n log n"	tenthousandfold effort
$\mathcal{O}(n^2)$	quadratic	millionfold effort
$\mathcal{O}(n^3)$	cubic	billiardfold effort
$\mathcal{O}(n^c)$	polynomial	gigantic much effort (for big c)
$\mathcal{O}(2^n)$	exponential	hopeless

(110/135

2.1

Reminder: Complexity 3(3)

...and the impact of growing inputs in practice in hard numbers:

n	linear	quadratic	cubic	exponential
1	$1~\mu$ s	$1~\mu$ s	$1~\mu$ s	$2 \ \mu s$
10	$10~\mu s$	100 μ s	1 ms	1 ms
20	20 μ s	400 μ s	8 ms	1 s
30	$30 \ \mu s$	900 μ s	27 ms	18 min
40	40 μ s	2 ms	64 ms	13 days
50	50 μ s	3 ms	125 ms	36 years
60	60 μ s	4 ms	216 ms	36 560 years
100	$100 \ \mu s$	10 ms	1 sec	$4 * 10^{16}$ years
1000	1 ms	1 sec	17 min	very, very long

2.1

(111/135)

Remedy

Streams can (often) help!

2.1 2.2

Chap 15

(112/135

Fik	Fibonacci Numbers Reconsidered 1(2)								
lde	ea								
0	1	1	2	3	5	8	13	Sequence of Fib. Numbers	
1	1	2	3	5	8	13	21	Remainder of the S. of F. N.	2.1 2.2 2.3 2.4
									Chap. 3
1	2	3	5	8	13	21	34	Remain. of the rem. of the	Chap. 4
								sequ. of Fibonacci Numbers	
T٢	nis c	an	effi	cien	tly t	oe ir	npleme	ented as a (corecursive) stream:	Chap. 6 Chap. 7
f	ibs	::	: [Int	ege	r]			Chap. 8
					0		With ((+) fibs (tail fibs)	Chap. 9
						-			Chap. 10
	-) -> [a] -> [b] -> [c]	Chap. 11
Z	ipW	litł	ı f	(x	:xs) (y:ys)	= f x y : zipWith f xs ys	Chap. 12
Z	ipW	litł	n f	_		_		= []	Chap. 13
	-						, ,		Chap. 14

...reminds to Münchhausen's famous trick of "sich am eigenen Schopfe aus dem Sumpf zu ziehen!"

(113/135)

Fibonacci Numbers Reconsidered 2(2)

fibs ->> 0 : 1 : 1 : 2 : 3 : 5 : 8 : 13 : 21 : 34	2.2
take 10 fibs ->> [0,1,1,2,3,5,8,13,21,34]	2.3 2.4 Chap. 3
	Chap. 4
where	
tala Interna N [a] N [a]	Chap. 6
take :: Integer -> [a] -> [a]	Chap. 7
take 0 _ = []	Chap. 8
take _ [] = []	Chap. 9
take n (x:xs) n>0 = x : take (n-1) xs	Chap. 10
take	Chap. 11
= error "PreludeList.take: negative argument"	Chap. 12
error rieraderio. bake. negative argument	Chap 13

(114/135

Summing up

We get a conceptually new implementation of the Fibonacci function using corecursive streams:

```
fib :: Int -> Integer
fib n = last (take n fibs)
```

Even shorter:

fib :: Int -> Integer
fib n = fibs!!(n-1)

Remark:

Note the application of the

Generator/Selector Principle

in this example.

2.1 (115/135)

Naive Evaluation (no sharing)

...stepwise evaluation (with add instead of zipWith (+)):
fibs

- ->> Replace the call of fibs by the body of fibs 0 : 1 : add fibs (tail fibs)
- ->> Replace both calls of fibs by the body of fibs
 - 0 : 1 : add (0 : 1 : add fibs (tail fibs))
 - (tail (0 : 1 : add fibs (tail fibs)))
- ->> Application of tail
 - 0 : 1 : add (0 : 1 : add fibs (tail fibs)) (1 : add fibs (tail fibs))

->> ...

- Observation: The computational effort remains exponential this (naive) way!
- Clou: Lazy evaluation common subexpressions will not be computed multiple times (in the example this holds for tail and fibs)!

2.1 (116/135

```
The Benefit of Lazy Evaluation (sharing) 1(3)
 fibs ->> 0 : 1 : add fibs (tail fibs)
      ->> Introduc. abbrev. allows sharing of results
          0 : tf (tf reminds to "tail of fibs")
                                                      2.1
          where tf = 1 : add fibs (tail fibs)
      ->> 0 : tf
          where tf = 1 : add fibs tf
      ->> Introducing abbreviations allows sharing
          0:tf
          where tf = 1 : tf2 (tf2 reminds to "tail
                               of tail of fibs")
                     where tf2 = add fibs tf
      ->> Unfolding of add
          0:tf
          where tf = 1 : tf2
                     where tf2 = 1 : add tf tf2
                                                      (117/135)
```

```
The Benefit of Lazy Evaluation (sharing) 2(3)
 ->> Repeating the above steps
     0:tf
     where tf = 1 : tf2
                                                      2.1
                where tf2 = 1 : tf3 (tf3 reminds to
                     "tail of tail of tail of fibs")
                      where tf3 = add tf tf2
 ->> 0 : tf
     where tf = 1 : tf2
                where tf2 = 1 : tf3
                      where tf3 = 2 : add tf2 tf3
 ->> tf is only used at one place and can thus be
     eliminated
     0:1:tf2
     where tf2 = 1 : tf3
                 where tf3 = 2 : add tf2 tf3
                                                      (118/135
```

```
The Benefit of Lazy Evaluation (sharing) 3(3)
 ->> Finally, we obtain successsively longer
     prefixes of the stream of Fibonacci numbers
     0:1:tf2
                                                       2.1
     where tf2 = 1 : tf3
                 where tf3 = 2 : tf4
                             where tf4 = add tf2 tf3
 ->> 0 : 1 : tf2
     where tf2 = 1 : tf3
                 where tf3 = 2 : tf4
                       where tf4 = 3 : add tf3 tf4
     Note: eliminating where-clauses corresponds
     to garbage collection of unused memory by an
     implementation
 ->> 0 : 1 : 1 : tf3
                 where tf3 = 2 : tf4
                       where tf4 = 3 : add tf3 tf4
                                                      (119/135)
```

Pitfall

In practice, the ability of dividing/recognizing common structures is limited.

This is demonstrated by the below variant of the Fibonacci function that artificially lifts fibs to a functional level:

```
fibsFn :: () -> [Integer]
fibsFn x =
0 : 1 : zipWith (+) (fibsFn ()) (tail (fibsFn ()))
```

This function again exposes

exponential run-time and storage behaviour!

Crucial:

Memory leak: The memory space is consumed so fast that the performance of the program is significantly impacted.

2.1 120/135

Illustration

```
fibsFn ()
->> 0 : 1 : add (fibsFn ()) (tail (fibsFn ()))
->> 0 : tf
where
tf = 1 : add (fibsFn ()) (tail (fibsFn ()))
```

The equality of tf and tail(fibsFn()) remains undetected. Hence, the following simplification is not done:

```
->> 0 : tf
where tf = 1 : add (fibsFn ()) tf
```

In a special case like here, this is possible, but there is no general means for detecting such equalities!

2.1 (121/135)

Chapter 2.2 Stream Diagrams

2.1 2.2 Problems on streams can often be considered and visualized as

processes.

In the following, we consider two examples:

- The stream of Fibonacci numbers
- ► The communication stream of a client/server application

2.2 (123/135)

Fibonacci Numbers

... as a stream diagram:



2.1 2.2 (124/135)

The Client/Server Application		
Interaction of a server and a client (e.g. Web server/Web		
browser):		
<pre>client :: [Response] -> [Request] server :: [Request] -> [Response]</pre>	Chap. 2 2.1 2.2 2.3 2.4	
reqs = client resps		
resps = server reqs	Chap. 4 Chap. 5	
Implementation	Chap. 6	
type Request = Integer	Chap. 7 Chap. 8	
type Response = Integer	Chap. 9	
client ys = 1 : ys (issues 1 as first request and	Chap. 10	
then each integer it receives	Chap. 11 Chap. 12	
from the server)	Chap. 13	
server xs = map (+1) xs (adds 1 to each request it	Chap. 14	
receives)	Chap. 15	
	(125/135)	

The Client/Server Application (Cont'd)

Ilustration: By stepwise evaluation	
	2.1 2.2
- $1 + roand$	2.3 2.4
->> 1 : server reqs	
	Chap. 4
->> Introducing abbreviations	
	Chap. 6
	Chap. 7
where tr = server reqs	
->> 1 : tr	Chap. 9
where tr = 2 : server tr	Chap. 10
->> 1 : tr	Chap. 11
where $tr = 2 : tr2$	Chap. 12
where $tr2 = server tr$	Chap. 13
	Chap. 14

Chap. 15

126/135

The Client/Server Application (Cont'd)

In particular, we obtain:

take 10 reqs ->> [1,2,3,4,5,6,7,8,9,10]

2.2 (127/135)

The Client/Server Application ... as a stream diagram:



2.1 2.2 (128/135)

Pitfall

Suppose, the client wants to check the first response:

where

ok y = True (Obviously a trivial predicate)

The evaluation of:

...does not terminate!

The problem: Deadlock! Neither the client nor the server can be unfolded! Pattern matching is too "eager."

2.2 (129/135)

Remedy: Lazy Patterns 1(3)

Ad-hoc Remedy:

- Replacing of pattern matching by an explicit usage of the selector function head.
- Moving the conditional inside of the list.

2.2 (130/135) Remedy: Lazy Patterns 2(3)

Systematic remedy: Lazy patterns

- ▶ Syntax: Preceding tilde (~)
- Effect: Like using an explicit selector function; pattern-matching is defered

Note: Even when using a lazy pattern the conditional must still be moved. But: The selector functions is avoided!

In practice, this can be very many selector functions that are saved this way making the programs "more" declarative and readable.

2.2 (131/135)

Remedy: Lazy Patterns 3(3)

```
Illustration: By stepwise evaluation
reqs ->> client resps
->> 1 : if ok y then y : ys
            else error "Faulty Server"
            where y:ys = resps
->> 1 : (y:ys)
            where y:ys = resps
->> 1 : resps
```

132/135

2.2

Chapter 2.3 Memoization

(133/135

2.3

Motivation

Memoization

 is a means for improving the performance of (functional) programs by avoiding costly recomputations

that benefits from

stream programming.

23 (134/135)

Memoization

The concept of

 memoization goes back to Donald Michie: 'Memo' Functions and Machine Learning. Nature, 218, 19-22, 1968.

Idea

 Replace, where possible, the (costly) computation of a function according to its body by looking up its value in a table, a so-called memo table.

Means

A memo function is used to replace a costly to compute function by a (memo) table look-up. Intuitively, the original function is augmented by a cache storing argument/result pairs.

Memo Functions, Memo Tables

A memo function is

 an ordinary function, but stores for some or all arguments it has been applied to the corresponding results in a memo table.

A memo table allows

to replace recomputation by table look-up.

Correctness of the overall approach:

 Referential transparency of functional programming languages (in particular, absence of side effects!).

23 (136/135)

Memo Functions, Memo Tables (Cont'd)

A memo function memo associated with a function f

memo :: (a -> b) -> (a -> b)

has to be defined such that the following equality holds:

memo f x = f x

2.3 137/135

A Concrete Approach with Memo Lists

Memo List: The (generic) memo function/table
flist = [f x x <- [0]]
where f is a function on integers.
Application: Each call of f is replaced by a look-up in flist.

2.3 138/135 Example 1: Computing Fibonacci Numbers
Computing Fibonacci numbers with memoization:
 fiblist = [fibm x | x <- [0..]]
 fibm 0 = 0
 fibm 1 = 1
 fibm n = fiblist !! (n-1) + fiblist !! (n-2)</pre>

Compare this with the naive implementation of fib:

Note:

fibm n = fib n

23

139/135

Example 2: Computing Powers
Computing powers (2⁰, 2¹, 2², 2³,...) with memoization:
 powerlist = [powerm x | x <- [0..]]
 powerm 0 = 1
 powerm i = powerlist !! (i-1) + powerlist !! (i-1)</pre>

Compare this with the naive implementation of power:

power 0 = 1power i = power (i-1) + power (i-1)

Observation:

Looking-up the result of the second call instead of recomputing it requires only 1 + n calls of power instead of 1 + 2ⁿ

 \rightsquigarrow Significant performance gain!

23 (140/135)

Summing up

The function memo :: $(a \rightarrow b) \rightarrow (a \rightarrow b)$:

- is essentially the identity on functions but
- memo keeps track on the arguments, it has been applied to and the corresponding results Motto: look-up a result that has been computed previously instead of recomputing it!

Memo functions

 are not part of the Haskell standard, but there are nonstandard libraries

23 141/135

Summing up (Cont'd)

Important design decision

when implementing memo functions: how many argument/result pairs shall be traced? (e.g. a memo function memo1 for one argument/result pair)

Example:

```
mfibsFn :: () -> [Integer]
mfibsFn x
= let mfibs = memo1 mfibsFn in
0 : 1 : zipWith (+) (mfibs ()) (tail (mfibs ()))
```

```
23
(142/135)
```

Summing up (Cont'd)

More on memoization, its very idea and application, e.g. in:

 Chapter 19, Memoization Anthony J. Field, Peter G. Harrison. Functional Programming. Addison-Wesley, 1988.

 Chapter 12.3, Memoization Max Hailperin, Barbara Kaiser, Karl Knight. Concrete Abstractions – An Introduction to Computer Science using Scheme. Brooks/Cole Publishing Company, 1999.

23 143/135

Summing up (Cont'd)

- (Introduced streams without memoization)
 P. J. Landin. A Correspondence between ALGOL60 and Church's Lambda-Notation: Part I. Communications of the ACM, 8(2):89-101, 1965.
- (Extended Landin's streams with memoization) Daniel P. Friedman, David S. Wise. CONS should not Evaluate its Arguments. In Automata, Languages and Programming, 257-281, 1976.
- (Extended Landin's streams with memoization) Peter Henderson, James H. Morris. A Lazy Evaluator. In Conference Record of the 3rd ACM Symposium on Principles of Programming Languages (POPL'76), ACM, 95-103, 1976.

23 (144/135)
Chapter 2.4 Boosting Performance

2.4

Motivation

Recomputating values unnecessarily is a major source of inefficiency.

 Avoiding recomputations of values is a major source of improving the performance of a program.

Two techniques that can (often) help achieving this are:

- Stream programming
- Memoization

Avoiding Recomputations using Stream Prog.

Computing Fibonacci numbers using stream prog.: fibs :: [Integer]

fibs = 0 : 1 : zipWith (+) fibs (tail fibs)

take 10 fibs ->> [0,1,1,2,3,5,8,13,21,34]
fibs!!5 ->> 5

147/135

2.4

Avoiding Recomputations using Memoization

Computing Fibonacci numbers with memoization:

```
fiblist = [ fibm x | x <- [0..]]
fibm 0 = 0
fibm 1 = 1
fibm n = fiblist!!(n-1) + fiblist!!(n-2)
take 10 fiblist ->> [0,1,1,2,3,5,8,13,21,34]
fiblist!!5 ->> 5
```

Computing powers with memoization: powerlist = [powerm x | x <- [0..]] powerm 0 = 1 powerm i = powerlist!!(i-1) + powerlist!!(i-1) take 9 powerlist ->> [1,2,4,8,16,32,64,128,256] powerlist!!5 ->> 32

Summing up

Stream programming and memoization are

no silver bullets

for improving performance by avoiding recomputations.

- If, however, they hit they can
 - significantly boost performance: from taking too long to be feasible to be completed in an instant!

Obvious candidates

 problems that naturally wind up repeatedly computing the the solution to identical subproblems, e.g. tree-recursive processes.

Homework: Compare the performance of the straightforward implementations of fib and power with their "boosted" versions using stream programming and memoization.

Silver Bullets exist Sometimes

Though not in general, it is worth noting that sometimes there is a silver bullet solving a problem:

The computation of the Fibonacci numbers is again a striking example.

We can prove (cf. Chapter 6) the following theorem that allows a recursion-free direct computation of the Fibonacci numbers, i.e.,

$$(\mathit{fib}_i)_{i\in |\mathsf{N}_0|} = 0, 1, 1, 2, 3, 5, 8, 13, 21, 34, \ldots$$

Theorem

$$\forall n \in IN_0. \ fib(n) = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^n - \left(\frac{1-\sqrt{5}}{2}\right)^n}{\sqrt{5}}$$

24 (150/135)

Conclusion

The usage of streams (and lazy evaluation) is advocated by:

- Higher abstraction: limitations to finite lists are often more complex, and – at the same time – unnatural.
- Modularization: streams together with lazy evaluation allow for elegant possibilities of decomposing a computational problem. Most important is the
 - Generator/Prune Paradigm
 - of which the
 - Generator/selector
 - Generator/filter
 - Generator/transformer principle

and combinations thereof are specific instances of.

- Boosting performance: by avoiding recomputations. Most important are
 - Stream programming
 - Memoization

Chapter 2: Further Reading (1)

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2.4 (152/135)

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2.4 153/135

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Chapter 2: Further Reading (5)

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2.4 156/135

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- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 17, Lazy programming; Chapter 17.6, Infinite lists; Chapter 17.7, Why infinite lists? Chapter 20.6, Avoiding recomputation: memoization)

2.4 158/135

Chapter 3

Programming with Higher-Order Functions: Algorithm Patterns

Chap. 3

Motivation

Programming with higher-order functions

- Many powerful and general algorithmic principles can be encapsulated in a suitable higher-order function (HOF).
- This allows to design a collection or a class of algorithms (instead of designing an algorithm for only a particular application).

Conceptually,

this emphasises the essence of the underlying algorithmic principle.

Pragmatically,

this makes these algorithmic principles easily re-usable.

Chap. 3

Motivation (Cont'd)

In this chapter, we demonstrate this reconsidering an array of well-known and well-established top-down and bottom-up design principles of algorithms.

In detail:

- Top-down: starting from the initial problem, the algorithm works down to the solution by considering alternatives.
 - Divide-and-conquer
 - Backtracking search
 - Priority-first search
 - Greedy search
- Bottom-up: starting from small problem instances, the algorithm works up to the solution of the initial problem by combining solutions of smaller problem instances to solutions of larger ones.
 - Dynamic programming

Chap. 3

Chapter 3.1 Divide-and-Conquer

3.1

Divide and Conquer

Given:

Let P be a problem specification.

Solving *P* – The Idea:

- If the problem is simple/small (enough), solve it directly or by means of some basic algorithm.
- Otherwise, divide the problem into smaller subproblems applying the division strategy recursively until all subproblems are simple enough to be directly solved.
- Combine all the solutions of the subproblems into a single solution of the initial problem.

3.1 163/135



Implementing Divide-and-Conquer as HOF (1)

The	Initial	Setting:
-----	---------	----------

- A problem with
 - problem instances of kind p

and solutions with

solution instances of kind s

Objective:

- A higher-order function (HOF) divideAndConquer
 - solving suitably parameterized problem instances of kind p utilizing the "divide and conquer" principle.

3.1

Implementing Divide-and-Conquer as HOF (2)

The ingredients of divideAndConquer:

- indiv :: p -> Bool: The function indiv yields True, if the problem instance can/need not be divided further (e.g., it can directly be solved by some *basic* algorithm).
- solve :: p -> s: The function solve yields the solution instance of a problem instance that cannot be divided further.
- divide :: p -> [p]: The function divide divides a problem instance into a list of subproblem instances.
- combine :: p -> [s] -> s: Given the original problem instance and the list of the solutions of the subproblem instances derived from, the function combine yields the solution of the original problem instance.

3.1 166/135

Implementing Divide-and-Conquer as HOF (3)

The HOF-Implementation:

divideAndConquer indiv solve divide combine initPb

3.1

Typical Applications of Divide-and-Conquer

.

Typical Applications:	
 Application areas such as 	3.1 3.2
Numerical analysis	3.3
5	3.4 3.5
 cryptography 	
image processing	Chap. 4
•	Chap. 6
 Quicksort 	Chap. 7
 Mergesort 	
C C C C C C C C C C C C C C C C C C C	Chap. 9
 Binomial coefficients 	Chap. 10
►	Chap. 11
	Chap. 12
	Chap. 13
	Chap. 14

Chap. 15 168/135

Divide-and-Conquer for Quicksort

```
quickSort :: Ord a => [a] \rightarrow [a]
                                                        3.1
quickSort 1st
= divideAndConquer indiv solve divide combine 1st
where
  indiv ls
                         = length ls \leq 1
                          = id
  solve
  divide (1:1s)
                         = [[x | x < -1s, x < = 1],
                             [x | x < -1s, x > 1]
  combine (1:_) [11,12] = 11 ++ [1] ++ 12
```

Chap. 15 169/135

Pitfall

Not every problem that can be modeled as a "divide and conquer" problem is also (directly) suitable for it.

Consider:

fib :: Integer -> Integer

fib n

- = divideAndConquer indiv solve divide combine n
 where
 - indiv n = (n == 0) || (n == 1)solve n

| n == 1 = 1
| otherwise = error "solve: problem divisible"
divide n = [n-2,n-1]

combine _ [11,12] = 11 + 12

...shows exponential runtime behaviour due to recomputations!

3.1 170/135

Illustration

The divide-and-conquer computation of the Fibonacci numbers (recomputing the solution to many subproblems!):



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 179. 3.1 171/135

Chapter 3.2 Backtracking Search

3.2

Backtracking Search

Given:

Let P be a problem specification.

Solving P – The Idea

 Search for a particular solution of the problem by a systematic trial-and-error exploration of the solution space.

Main Problem Characteristics for Applicability

- A set of all possible situations or nodes constituting the search (node) space; these are the potential solutions that need to be explored.
- A set of legal moves from a node to other nodes, called the successors of that node.
- An initial node.
- A goal node, i.e, the solution.

Illustrating Backtracking Search

General stages in a backtracking algorithm:



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 162. 3.2 174/135

Illustrating Backtracking Search (Cont'd)

Intuitively

- When exploring the graph, each visited path can lead to the goal node with an equal chance.
- Sometimes, however, there can be a situation, in which it is known that the current path will not lead to the solution.
- In such cases, one backtracks to the next level up the tree and tries a different alternative.

Note

- The above process is similar to a depth-first graph traversal; this is illustrated in the preceding figure.
- Not all backtracking algorithms stop when the first goal node is reached
- Some backtracking algorithms work by selecting all valid solutions in the search space.

32

mplementing Backtracking Search as HOF (1)			
The Initial Setting:			
 A problem with problem instances of kind p 	Chap. 3 3.1 3.2 3.3 3.4 3.5		
and solutions with			
solution instances of kind s			
	Chap. 6		
	Chap. 7		
Objective:			
A higher-order function (HOF) searchDfs			
solving suitably parameterized problem instances of kind			
p utilizing the "backtracking" principle.			
	Chap. 13		
	Chap. 14		

Chap. 15 176/135

Implementing Backtracking Search as HOF (2)

Often:

• The search space is large.

Hence, the graph representing the search space

- should not be stored explicitly, i.e., in its entirety in memory (using explicit graphs)
- but be generated on-the-fly as computation proceeds (using implicit graphs)

This reqires:

- An appropriate type node that represents node information
- ➤ a successor function succ of type node -> [node] that generates the list of successors of a node.

32

Implementing Backtracking Search as HOF (2)

Assumptions:

- an acyclic implicit graph
- all solutions shall be computed (not only the first one)

Note: The HOF can be adjusted to terminate after finding the first solution.

The ingredients of searchDfs:

- node: A type representing node information.
- succ :: node -> [nodes]: The function succ yields the list of successors of a node.
- goal :: node -> Bool: The function goal determines if a node is a solution.

```
Implementing Backtracking Search as HOF (3)
The HOF-Implementation:
 searchDfs ::
   (Eq node) => (node -> [node]) -> (node -> Bool)
                                                         32
                 -> node -> [node]
 searchDfs succ goal x
   = (search' (push x emptyStack) )
    where
      search' s
       stackEmpty s = []
       | goal (top s) = top s : search' (pop s)
       | otherwise
           = let x = top s
              in search' (foldr push (pop s) (succ x))
```

Chap. 15 179/135 The Abstract Data Type Stack (1)

The user-visible interface specification of the Abstract Data Type (ADT) Stack:

push	::	a -> Stack a -> Stack a
рор	::	Stack a -> Stack a
top	::	Stack a -> a
emptyStack	::	Stack a
stackEmpty	::	Stack a -> Bool

3.2
The Abstract Data Type Stack (2) A user-invisible implementation of Stack as an algebraic data type (using data): data Stack a = EmptyStk | Stk a (Stack a) push x s = Stk x spop EmptyStk = error "pop from an empty stack" $pop (Stk _ s) = s$ top EmptyStk = error "top from an empty stack" $top (Stk x _) = x$ emptyStack = EmptyStk stackEmpty EmptyStk = True stackEmpty _ = False

> Chap. 15 181/135

3.2

The Abstract Data Type Stack (3) A user-invisible implementation of Stack as an algebraic data type (using newtype): newtype Stack a = Stk [a] 3.2 push x (Stk xs) = Stk (x:xs) pop (Stk []) = error "pop from an empty stack" pop (Stk (:xs)) = Stk xstop (Stk []) = error "top from an empty stack" $top (Stk (x:_)) = x$ emptyStack = Stk [] stackEmpty (Stk []) = True stackEmpty (Stk _) = False

> Chap. 15 182/135

Typical Applications of Backtrackting Search

Typical Applications:	
 Application areas such as game strategies 	3.1 3.2 3.3 3.4 3.5
▶	
The eight-tile problem (8TP)	
► The <i>n</i> -queens problem	
Towers of Hanoi	
The knapsack problem	Cha _l Cha _l
	Cha
	Cha
	Cha
	Cha

Chap. 15 183/135

The Eight-Tile Problem



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 160. 3.2 184/135

A Backtracking Search for 8TP (1)

Modeling the board:

type Position = (Int,Int)
type Board = Array Int Position

The initial board (initial configuration):

The final board (goal configuration):

g8T :: Board g8T = array (0,8) [(0,(2,2)),(1,(1,1)),(2,(1,2)), (3,(1,3)),(4,(2,3)),(5,(3,3)), (6,(3,2)),(7,(3,1)),(8,(2,1))]

A Backtracking Search for 8TP (2)

Computing the distance of board fields (Manhattan distance = horizontal plus vertical distance):

mandist :: Position -> Position -> Int mandist (x1,y1) (x2,y2) = abs (x1-x2) + abs (y1-y2)

Computing all moves (board fields are adjacent iff their Manhattan distance equals 1):

...the list of configurations reachable in one move is obtained by placing the space at position i and indicating that tile i is now where the space was. 3.2 186/135 A Backtracking Search for 8TP (3)

Modeling nodes in the search graph:

```
data Boards = BDS [Board]
```

...corresponds to the intermediate configurations from the initial configuration to the current configuration in reverse order.

The successor function:

```
succ8Tile :: Boards -> [Boards]
succ8Tile (BDS(n@(b:bs)))
= filter (notIn bs) [BDS(b':n) | b' <- allMoves b]
where
notIn bs (BDS(b:_))</pre>
```

= not (elems b) (map elems bs))

...computes all successors that have not been encountered before; the **notIn**-test ensures that only nodes are considered that have not been encountered before.

A Backtracking Search for 8TP (4)

The goal function:

```
goal8Tile :: Boards -> Bool
goal8Tile (BDS (n:_)) = elems n == elems g8T
```

Putting things together:

A depth-first search producing the first sequence of moves (in reverse order) that lead to the goal configuration:

Chapter 3.3 Priority-first Search

3.3

Priority-first Search

Given:

Let P be a problem specification.

Solving P – The Idea

Similar to backtracking search, i.e., search for a particular solution of the problem by a systematic trial-and-error exploration of the solution space but order the candidate nodes according to the most promising node (priority-first search/best-first search).

Note: In contrast to plain backtracking search, which proceeds unguided and can thus be considered blind, priority-first search/best-first search benefits from (hopefully correct) information pointing it towards "more promising" nodes.

Priority-first Search (Cont'd)

Main Problem Characteristics for Applicability

- A set of all possible situations or nodes constituting the search (node) space; these are the potential solutions that need to be explored.
- A comparison criterion for comparing and ordering candidate nodes wrt their (expected) "quality" to investigate "promising" nodes before "less promising" nodes.
- A set of legal moves from a node to other nodes, called the successors of that node.
- An initial node.
- A goal node, i.e, the solution.

Illustrating Search Strategies



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 167.

Nodes are ordered according to their identifier value ("smaller" means "more promising"):

- Depth-first search: [1,2,5,4,6,3]
- Breadth-first search: [1,2,6,3,5,4]
- Priority-first search: [1,2,3,5,4,6]

Implementing Priority-first Search as HOF (1)

ар. З
ap. 4 ap. 5 ap. 6
ар. 7 ар. 8
ар. 9 ар. 10
ap. 11 ap. 12

Implementing Priority-first Search as HOF (2)

Assumptions:

- an acyclic implicit graph
- all solutions shall be computed (not just the first one)

Note: The HOF can be adjusted to terminate after finding the first solution.

The ingredients of searchPfs:

- node: A type representing node information.
- <=: A comparison criterion for nodes; usually, this is the relator <= of the type class Ord. Often, the relator <= can not exactly be defined but only in terms of a plausible heuristic.
- succ :: node -> [nodes]: The function succ yields the list of successors of a node.
- goal :: node -> Bool: The function goal determines if a node is a solution.

```
Implementing Priority-first Search as HOF (3)
The HOF-Implementation:
 searchPfs ::
   (Ord node) => (node -> [node]) -> (node -> Bool)
                                                          33
                 -> node -> [node]
 searchPfs succ goal x
   = search' (enPQ x emptyPQ)
    where
     search' q
       | pqEmpty q
                         = []
       | goal (frontPQ q) = frontPQ q : search' (dePQ q)
        otherwise
            = let x = frontPQ q
              in search' (foldr enPQ (dePQ q) (succ x))
```

Chap. 15 195/135

The Abstract Data Type PQueue (1)

The user-visible interface specification of the Abstract Data Type (ADT) priority queue PQueue:

emptyPQ :: PQueue a
pqEmpty :: PQueue a -> Bool
enPQ :: (Ord a) => a -> PQueue a -> PQueue a
dePQ :: (Ord a) => PQueue a -> PQueue a
frontPQ :: (Ord a) => PQueue a -> a

33

The Abstract Data Type PQueue (2)	
A user-invisible implementation of PQueue as an algebraic	Contents
data type:	Chap. 1
newtype PQueue a = PQ [a]	Chap. 2 Chap. 3
emptyPQ = PQ []	3.1 3.2 3.3 3.4
pqEmpty (PQ []) = True pqEmpty _ = False	3.5 Chap. 4
enPQ x (PQ q) = PQ (insert x q)	Chap. 5 Chap. 6
where insert x [] = [x]	Chap. 7
insert x r@(e:r') x <= e = x:r	Chap. 8
otherwise = e:insert x r'	Chap. 9
<pre>dePQ (PQ []) = error "dePQ: empty priority queue" dePQ (PQ (_:xs)) = PQ xs</pre>	Chap. 10 Chap. 11 Chap. 12
<pre>frontPQ (PQ []) = error "frontPQ: empty priority que</pre>	
frontPQ (PQ $(x:_)$) = x	Chap. 14
	Chap. 15

Typical Applications of Priority-first Search

	3.1
Typical Applications:	3.2 3.3
 Application areas such as 	3.4 3.5
Application aleas such as	
game strategies	Chap. 4
►	
	Chap. 6
 The eight-tile problem (8TP) 	Chap. 7
•	
	Chap. 9
	Chap. 10
	Chap. 11
	Chap. 12
	Chap. 13
	Chap. 14

A Priority-first Search for 8TP

Comparing nodes heuristically: ...by summing the distance of each square from its home position to its destination as an estimate of the number of moves that will be required to transform the current node into the goal node.

```
33
heur :: Board -> Int
heur b = sum [mandist (b!i) (g8T!i) | i < -[0..8]]
instance Eq Boards
 where BDS (b1:_) == BDS (b2:_) = heur b1 == heur b2
instance Ord Boards
 where BDS (b1:_) <= BDS (b2:_) = heur b1 <= heur b2
pfs8Tile :: [[Position]]
pfs8Tile = map elems ls
 where ((BDS ls):_)
  = searchPfs succ8Tile goal8Tile (BDS [s8T])
```

```
199/135
```

Chapter 3.4 Greedy Search

3.4

Greedy Search

Given:

Let P be a problem specification.

Solving P – The Idea

 Similar to priority-first/best-first search but limiting the search to immediate successors of a node (greedy search/ hill climbing search).

Note: Maintaining the priority queue in priority-first search may be costly in terms of time and memory. Greedy search avoids this time and memory penalty by maintaining a much smaller priority queue considering immediate successors only (the search commits itself to each step taken during the search). Hence, only a single path of the search space is explored instead of its entirety what ensures efficiency. Optimality, however, requires the absence of local minimums. 3.4 201/135

Greedy Search (Cont'd)

Main Problem Characteristics for Applicability

- A set of all possible situations or nodes constituting the search (node) space; these are the potential solutions that need to be explored.
- A set of legal moves from a node to other nodes, called the successors of that node.
- An initial node.
- A goal node, i.e, the solution.
- There shall be no local minimums, i.e., no locally best solutions.

Note: If local minimums exist but are known to be "close" (enough) to the optimal solution, a greedy search might still be reasonable giving a "good", not necessarily optimal solution. Greedy search then becomes a heuristic algorithm.

3.4 202/135

Illustrating Greedy Search

Successive stages in a greedy algorithm:



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 171. 3.4 203/135

Implementing Greedy Search as HOF (1)

The Initial Setting:	
The mildi Setting.	
► A problem with	Chap. 3 3.1 3.2
problem instances of kind p	3.3 3.4
	3.5
and solutions with	Chap. 4
solution instances of kind s	
	Chap. 6
	Chap. 7
Objective:	
5	Chap. 9
A higher-order function (HOF) searchGreedy	Chap. 10
solving suitably parameterized problem instances of kind	Chap. 11
p utilizing the "greedy/hill climbing" principle.	Chap. 12
p utilizing the greedy/init climbing principle.	Chap. 13

Implementing Greedy Search as HOF (2)

Assumptions:

- an acyclic implicit graph
- no local minimums, i.e., no locally best solutions

The ingredients of searchGreedy:

- node: A type representing node information.
- <=: A comparison criterion for nodes; usually, this is the relator <= of the type class Ord.</p>
- succ :: node -> [nodes]: The function succ yields the list of successors of a node.
- goal :: node -> Bool: The function goal determines if a node is a solution.

3.4 205/135

```
Implementing Greedy Search as HOF (3)
The HOF-Implementation:
  searchGreedy ::
   (Ord node) \Rightarrow (node \rightarrow [node]) \rightarrow (node \rightarrow Bool)
                  -> node -> [node]
                                                                3.4
  searchGreedy succ goal x
   = search' (enPQ x emptyPQ)
     where
      search' q
        | pqEmpty q
                            = []
        | goal (frontPQ q) = [frontPQ q]
         otherwise
             = let x = frontPQ q
               in search' (foldr enPQ emptyPQ (succ x))
```

Chap. 15 206/135

Implementing Greedy Search as HOF (4)

Note:

The most striking difference to the HOF searchPfs is the replacement of dePQ q by emptyPQ in the recursive call to search' to remove old candidate nodes from the priority queue. 3.4 207/135

Typical Applications of Greedy Search

Typical Applications:

▶ ...

- Graph algorithms, e.g., Prim's minimum spanning tree algorithm
- Money Change Problem (MCP)



A Greedy Search for MCP

Problem statement: Give money change with the least number of coins.

Modeling coins:

```
coins :: [Int]
coins = [1,2,5,10,20,50,100]
```

Modeling nodes (remaining amount of money and change used so far, i.e., the coins that have been returned so far):

type NodeChange = (Int,SolChange)
type SolChange = [Int]

Generating successor nodes (by removing every possible coin from the remaining amount):

succCoins :: NodeChange -> [NodeChange]
succCoins (r,p)
= [(r-c,c:p) | c <- coins, r-c >= 0]

3.4 209/135

A Greedy Search for MCP (Cont'd)	
The goal function:	Contents
goalCoins :: NodeChange -> Bool goalCoins (v,_) = v == 0	Chap. 1 Chap. 2 Chap. 3 3.1 3.2
Putting things together:	3.3 3.4 3.5
change :: Int -> SolChange change amount	Chap. 4 Chap. 5 Chap. 6
<pre>= snd (head (searchGreedy succCoins goalCoins</pre>	Chap. 7 Chap. 8
Example: change 199 ->> [2,2,5,20,20,50,100]	Chap. 9 Chap. 10 Chap. 11
Note: For coins = [1,3,6,12,2,30] the above algorithm can yield suboptimal solutions: E.g., change 48 ->> [30,12,6] instead of the optimal solution [24,24].	Chap. 12 Chap. 13 Chap. 14 Chap. 15 210/135

Chapter 3.1-3.4: Further Reading (1)

- Alfred V. Aho, John E. Hopcroft, Jeffrey D. Ullman. The Design and Analysis of Computer Algorithms. Addison-Wesley, 1974. (Chapter 2.6, Divide-and-conquer)
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3.4 211/135

Chapter 3.1–3.4: Further Reading (2)

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3.4

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- Robert Sedgewick. Algorithmen. Addison-Wesley/Pearson, 2. Auflage, 2002. (Kapitel 5, Rekursion - Teile und Herrsche; Kapitel 44, Erschöpfendes Durchsuchen - Backtracking)
- Steven S. Skiena. *The Algorithm Design Manual*. Springer-V, 1998. (Chapter 3.6, Divide and Conquer)
- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 2nd edition, 1999. (Chapter 19.6, Avoiding recomputation: memoization – Greedy algorithms)
- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 20.6, Avoiding recomputation: memoization – dynamic programming)

3.4 213/135

Chapter 3.5 Dynamic Programming

3.5

Dynamic Programming

Given:

Let P be a problem specification.

Solving P – The Idea

- Solve (the) smaller instances of the problem first
- Save the solutions of these smaller problem instances

3.5

215/135

Use these results to solve larger problem instances

Note: Top-down algorithms as in the previous sections might suffer from generating a large number of identical subproblems. This replication of work can severely impair performance. Dynamic programming aims at overcoming this shortcoming by systematically precomputing and reusing results in a bottom-up fashion, i.e., from smaller to larger problem instances.

Illustrating Dynamic Programming for fib

The dynamic programming computation of the Fibonacci numbers (no recomputation of the solution to subproblems!):



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 179. 3.5 216/135
Illustrating Divide-and-Conquer for fib

The divide-and-conquer computation of the Fibonacci numbers (recomputing the solution to many subproblems!):



Fethi Rabhi, Guy Lapalme. Algorithms: A Functional Programming Approach. Addison-Wesley, 1999, page 179. 3.5 217/135

Implementing Dynamic Programming as HOF	
(1)	
The Initial Setting:	
The filled Setting.	Chap. 3.1
A problem with	3.2 3.3
problem instances of kind p	3.4 3.5
and solutions with	
solution instances of kind s	
	Chap.
Objective:	Chap. Chap.
A higher-order function (HOF) dynamic	Chap.
	Chap.
 solving suitably parameterized problem instances of kind suitibilities the "threaming means any instances" using interval 	
p utilizing the "dynamic programming" principle.	Chap.

Chap. 15 218/135 Implementing Dynamic Programming as HOF (2)

The ingredients of the HOF dynamic:

- compute :: (Ix coord) => Table entry coord -> coord -> entry: Given a table and an index, the function compute computes the corresponding entry in the table (possibly using other entries in the table).
- bnds :: (Ix coord) => (coord, coord): The parameter bnds represents the boundaries of the table. Since the type of the index is in the class Ix, all indices in the table can be generated from these boundaries using the function range.

3.5 219/135

```
Implementing Dynamic Programming as HOF
(3)
The HOF-Implementation:
                                                         3.5
 dynamic ::
   (Ix coord) => (Table entry coord -> coord -> entry)
                -> (coord, coord) -> (Table entry coord)
 dynamic compute bnds = t
   where
   t = newTable (map (\coord -> (coord, compute t coord))
                      (range bnds))
                                                          220/135
```

The Abstract Data Type Table (1) The user-visible interface specification of the Abstract Data Type (ADT) Table:

module Table (Table,newTable,findTable,updTable)
where

newTable :: (Ix b) => [(b,a)] -> Table a b findTable :: (Ix b) => Table a b -> b -> a updTable :: (Ix b) => (b,a) -> Table a b -> Table a b

Note:

- The function newTable takes a list of (index,value) pairs and returns the corresponding table.
- The functions findTable and updTable are used to retrieve and update values in the table.

3.5 221/135 The Abstract Data Type Table (2)

A user-invisible implementation of Table as an Array:

newtype Table a b = Tbl (Array a b)

newTable l = Tbl (array (lo,hi) l)
where indices = map fst l
lo = minimum indices
hi = maximum indices

findTable (Tbl a) i = a ! i

updTable p@(i,x) (Tbl a) = Tbl (a // [p])

3.5 222/135

The Abstract Data Type Table (2)

Note:

- The function newTable determines the boundaries of the new table by computing the maximum and the minimum key in the association list.
- In the function findTable, access to an invalid key returns a system error, not a user error.

3.5 223/135

Typical Applications of Dynamic Programming

Typical Applications:	3.1 3.2
 Fibonacci numbers 	3.3 3.4 3.5
 Chained matrix multiplication 	Chap. 4
 Optimal binary search (in trees) 	
 The travelling salesman problem 	Chap. 6 Chap. 7
 Graph algorithms, e.g., all-pairs shortest path 	
	Chap. 9
	Chap. 10
	Chap. 11
	Chap. 12
	Chap. 13
	Chap. 14

Chap. 15 224/135 Computing Fibonacci Numbers using Dynamic Programming Defining the problem-dependent parameters: bndsFibs :: Int -> (Int,Int) bndsFibs n = (0,n)3.5 compFib :: Table Int Int -> Int -> Int compFib t i | i <= 1 = i otherwise = findTable t (i-1) + findTable t (i-2) Putting things together: fib :: Int -> Int

fib n = findTable t n

where t = dynamic compFib (bndsFib n)

Chap. 15 225/135

Comparing Dynamic Programming and Memoization

Overall

- Dynamic programming and memoization enjoy very much the same characterics and offer the programmer quite similar benefits.
- In practice, differences in behaviour are minor and strongly problem-dependent.
- ► In general, both techniques are equally powerful.

Conceptual difference

- Memoization opportunistically computes and stores argument/result pairs on a by-need basis ("lazy" approach).
- Dynamic programming systematically precomputes and stores argument/result pairs before they are needed ("eager" approach).



Comparing Dynamic Programming and Memoization (Cont'd)

Minor benefits of dynamic programming

- Memory efficiency: For some problems the dynamic programming solution can be adjusted to use asymptotically less memory: limited history recurrence, i.e., only a limited number of preceding values need to be remembered (e.g., two for the computation of Fibonacci numbers) which allows to reuse memory during computation.
- Run-time performance: The systematic programmer-controlled computing and filling of the argument/result pairs table allows sometimes slightly more efficient (by a constant factor) implementations.

3.5 227/135 Comparing Dynamic Programming and Memoization (Cont'd)

Minor benefits of memoization

- Freedom of conceptual overhead: The programmer does not need to think about in what order argument/result pairs need to be computed and how to be stored in the memo table. In dynamic programming all table entries are computed systematically when needed.
- Freedom of computational overhead: Only argument/result pairs are computed and stored when needed. In dynamic programming they are systematically precomputed before they are needed.

3.5 228/135

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3.5 229/135

Chapter 3.5: Further Reading (2)

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- Jon Kleinberg, Éva Tardos. Algorithm Design. Addison-Wesley/Pearson, 2006. (Chapter 6, Dynamic Programming)
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3.5 230/135

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3.5 231/135

Chapter 3.5: Further Reading (4)

- Steven S. Skiena. The Algorithm Design Manual. Springer-V., 1998. (Chapter 3.1, Dynamic Programming; Chapter 3.2, Limitations of Dynamic Programming)
- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 2nd edition, 1999. (Chapter 19.6, Avoiding recomputation: memoization – dynamic programming)
 - Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 20.6, Avoiding recomputation: memoization – dynamic programming)

3.5 232/135

Chapter 4 Equational Reasoning

Chap. 4

233/135

Chapter 4.1 Motivation

4.1

Functional vs. Imperative Programming (1)

Functional Programming

The usage of = in functional definitions of the type

f x y = ...

as e.g. used in Haskell in the definition of a function f are genuine mathematical equations.

The equations state that the expressions on the left hand side and the right hand side have the same value. 4.1 235/135

Functional vs. Imperative Programming (2) Imperative Programming

The usage of = in imperative languages like C, Java, etc. in (assignment) statements of the form

x = x+y

does not mean that x and x+y have the same value.

Here, = is used to denote a command, a destructive assignment statement meaning that the old value of x is destroyed and replaced by the value of x+y.

Note: To avoid confusion some imperative programming languages use thus a different notation, e.g. := such as in Pascal, to denote the assignment operator (instead of the conceptually misleading notation =).

Consequence

Reasoning about

functional definitions

is because of this difference a lot easier as about

programs using destructive assignments

For functional definitions

 standard (algebraic) reasoning about mathematical equations applies.

For example: The sequence of definitions in Haskell

$$x = x + y$$

raises an error "x" multiply defined since = in Haskell has the meaning "is by definition equal to"; redefinition is forbidden. 4.1 237/135

Illustrating Algebraic Reasoning

By algebraic reasoning on equations we obtain:

$$(a+b) * (a-b) = a^2 - b^2$$

Proof:

$$(a+b) * (a-b)$$
(Distributivity of *, +) = $a * a - a * b + b * a - b * b$
(Commutativity of *) = $a * a - a * b + a * b - b * b$
= $a * a - b * b$
= $a^2 - b^2$

Contents

238/135

Extending Algebraic Reasoning to Functional Definitions

First Example:

This allows us to conclude: The Haskell functions ${\tt f}$ and ${\tt g}$ defined by

f	:: Int -> Int -> Int
f	a b = (a+b) * (a-b)
g	:: Int -> Int -> Int
g	$a b = a^2 - b^2$

denote the same function.

4.1 239/135

Reasoning on Functional Definitions –
More Examples (1)
Second Example:
Let
a = 3 b = 4
f :: Int -> Int -> Int f x y = x^2 + y^2

By equational reasoning on the functional definition of f and those of a and b we can show that the Haskell expression

f a (f a b) has value 634.

4.1 240/135

Reasoning on Functional Definitions – More Examples (2)

Proof:

$$a (f a b) = f a (a2 + b2)$$

= f 3 (3² + 4²)
= f 3 (9 + 16)
= f 3 25
= 3² + 25²
= 9 + 625
= 634

Note that the (Haskell) expression f a (f a b) is solely evaluated by equational reasoning applying standard algebraic mathematical laws and the Haskell definitions of a, b, and f. 4.1 241/135

Reasoning on Functional Definitions – More Examples (3)		
Third Example:		
Let		
g :: Int -> Int -> Int g x y = x ² - y ²		
h :: Int -> Int -> Int h x y = x * y		
By equational reasoning on the functional definitions of g a		

By equational reasoning on the functional definitions of g and h we can show the equality of the Haskell expressions

h (a+b) (a-b) and g a b.

4.1

242/135

Reasoning on Functional Definitions – More Examples (4)

Proof:

h (a+b) (a-b) (Unfolding h) = (a+b) * (a-b) (Distributivity of *, +) = a * a - a * b + b * a - b * b (Commutativity of *) = a * a - a * b + a * b - b * b = a * a - b * b $= a^{2} - b^{2}$ (Folding g) = g a b

4.1 243/135

Remark (1)

We have:

In equational reasoning functions can be applied/unapplied

- from left-to-right, called unfolding
- from right-to-left, called folding



Remark (2)

Note: Some care needs to be taken though. Let

```
isZero :: Int -> Bool
isZero 0 = True
isZero n = False
```

The first equation isZero 0 = True

 can just be viewed as a logical property that can freely be applied in both directions.

The second equation, however, isZero n = False can not, since Haskell implicitly imposes an ordering on the equations:

Application from left-to-right (i.e., replacing isZero n by False), and from right-to-left (i.e., replacing False by isZero n for some n) is legal only, if n is different from 0. 4.1 245/135 Reasoning on Functional Definitions – More Examples (5)

Fourth Example:

The standard implementation of the reverse function

requires $\frac{n(n+1)}{2}$ calls of the concatenation function (++), where *n* denotes the length of the argument list.

4.1 246/135

Reasoning on Functional Definitions – More Examples (6)

A more efficient implementation of the functionality of the reverse function is

Reasoning on Functional Definitions – More Examples (7)

Equational reasoning on functional definitions together with inductive proof principles, here structural induction, allows us to prove:

The Haskell expressions

reverse xs and fastReverse xs

are equal for all finite lists xs.



Summing up

Functional definitions aregenuine mathematical equations.
 This allow us to prove equality and other relations of functional expressions by applying standard algebraic mathematical reasoning.
In particular, this can be used to replace

- less efficient (called specification) by more efficient (called implementation) implementations of some functionality.
 Examples:
 - Basic: Replace (x*y)+(x*z) by x*(y+z)
 - Advanced: Replace reverse by fastReverse

4.1 249/135

Chapter 4.2 Functional Pearls

4.2

Functional Pearls – The Very Idea (1)

The design of functional pearls, i.e., functional programs

evolves from calculation!

In more detail:

Starting from a problem with a

simple, intuitive but often inefficient specification

we shall arrive at an

 efficient though often more complex and possibly less intuitive implementation

by means of

 mathematical reasoning, i.e., by equational and inductive reasoning, by theorems and laws.

Example: From reverse to fastReverse.

42

251/135

Functional Pearls – The Very Idea (2)

lt is important t	o note:
-------------------	---------

The functional pearl

- is not the final (efficient) implementation
- but the calculation process leading to it!

Chap. 4
4.1 4.2
4.3 4.4
4.4
Chap. 6
Chap. 7
Chap. 9
Chap. 10
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15 252/135
Functional Pearls – Origin and Background (1)

In the course of founding the
 Journal of Functional Programming
in 1990, Richard Bird was asked by the designated editors-in-chief Simon Peyton Jones and Philip Wadler to contribute a regular column called
 Functional Pearls

42

253/135

In spirit, this column should follow and emulate the successful series of essays written by Jon Bentley in the 1980s under the title

Programming Pearls

in the

Communications of the ACM

Functional Pearls – Origin and Background (2)

Since 1990, some

- 80 pearls have appeared in the Journal of Functional Programming related to
 - Divide-and-conquer
 - ► Greedy
 - Exhaustive search
 - ► ...

and other problems.

Some more appeared in proceedings of conferences including editions of the

- International Conference of Functional Programming
- Mathematics of Program Construction

42

Functional Pearls – Origin and Background (3)

Roughly,

 a quarter of these pearls have been written by Richard Bird

In his recent monograph

Pearls of Functional Algorithm Design. Cambridge University Press, 2011

Richard Bird presents a collection of 30 "revised, polished, and re-polished functional pearls" written by him and others.

Outline

In this chapter, we will consider some of these functional pearls for illustration:

- ► The Smallest Free Number
- Not the Maximum Segment Sum
- A Simple Sudoku Solver



It is worth noting:

The name of the functional programming language

GoFER

is an acronym for

Go F(or) E(quational) R(easoning)



Chapter 4.3 The Smallest Free Number

4.3

Conte The SFN-Problem:
The SEN-Problem:
Chap.
► Let X be a finite set of natural numbers.
• Compute the smallest natural number y that is not in X .
Examples:
The smallest free number for Chap.
► $\{0, 1, 5, 9, 2\}$ is 3
$\blacktriangleright \{0, 1, 2, 3, 18, 19, 22, 25, 42, 71\} \text{ is } 4$
► {8,23,9,12,11,1,10,0,13,7,41,4,21,5,17,3,19,2,6} is Chap.
not immediately obvious!
Chap.

Chap. 15 259/135

Analyzing the Problem

Obviously

- ► The SFN-problem can easily be solved, if the set X is represented as an increasingly ordered list xs of numbers without duplicates.
- If so, just look for the first gap in xs.

Example:

Computing the smallest free number for the set X

- $\blacktriangleright \ \{8, 23, 9, 12, 11, 1, 10, 0, 13, 7, 41, 4, 21, 5, 17, 3, 19, 2, 6\}$
- After sorting (and removing duplicates):
 [0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 17, 19, 21, 23, 41]
- Looking for the first gap yields: The smallest free number is 14!

4.3

Simple Algorithm for solving the SFN-Problem

This suggests the following simple algorithm for solving the SFN-problem:

The simple SFNP-Algorithm:

- 1. Represent X as a list of integers xs.
- 2. Sort xs increasingly, while removing all duplicates.
- 3. Compute the first gap in the list obtained from the previous step.



Possible Implementation of the Simple Algorithm

```
...by means of a system of functions
 ssfn (reminding to "simple sfn") and
 sap (reminding to "search and pick")
                                                        4.3
 ssfn :: [Integer] -> Integer
 ssfn = (sap 0) . removeDuplicates . quickSort
 sap :: Integer -> [Integer] -> Integer
 sap n []
               = n
 sap n (x:xs)
   |n/=x = n
   | otherwise = sap (n+1) xs
```

Chap. 15 262/135

The Advanced Algorithmic Problem

The simple SFNP-Algorithm is sound but inefficient:

Sorting is not of linear time complexity.

The Advanced SFNP-Algorithm Problem:

Develop an algorithm LinSFNP for solving the SFN-problem that is of

linear time complexity, i.e., that is linear in the number of the elements of the initial set X of natural numbers.



Towards the Linear Time Algorithm

The SFN-problem can be specified as a function minfree, defined by

```
minfree :: [Nat] -> Nat
minfree xs = head $ ([0..]) \\ xs
```

with

denoting difference on sets (i.e., $xs \setminus ys$ is the list of those elements of xs that remain after removing any elements in ys) and

type Nat = Int

the type of natural numbers starting from 0.

4.3 264/135

Analysing minfree

The function minfree solves the SFN-problem but its evaluation requires on a list of length n

• $\Theta(n^2)$ steps in the worst case.

For illustration consider:

Evaluating

minfree [n-1,n-2..0] requires evaluating

i is not an element in $[n-1, n-2 \dots 0]$

for $0 \le i \le n$, and thus n(n+1)/2 equality tests.

4.3

Outline

Starting from minfree we will develop an

- array based and a
- divide-and-conquer based

linear time algorithm for the SFN-problem.

The key fact (KF) both algorithms rely on is:

► There is a number in [0..length xs] that is not in xs where xs denotes the initial list of natural numbers.

This implies:

The smallest number not in filter (<=n) xs, n == length xs, is the smallest number not in xs! 4.3 266/135

Towards the Array-Based Algorithm

The array-based algorithm uses KF to build a

checklist of those numbers present in filter (<=n) xs.</p>

The checklist is a

► Boolean array with n + 1 slots, numbered from 0 to n, whose initial entries are set to False.

Algorithmic idea:

- For each element x in xs with x <= n the array element at position x is set to True.
- The smallest free number is then found as the position of the first False entry.

4.3

The Array-Based Algorithm	
The array-based algorithm LinSFNP:	
minfree = search . checklist	
minifee - Search . Checkiist	
search :: Array Int Bool -> Int	Chap. 4 4.1
search = length . takeWhile id . elems	4.2 4.3
	4.4 4.5
checklist :: [Int] -> Array Int Bool	
checklist xs = accumArray () False (0,n)	Chap. 6
(zip (filter (<=n) xs) (repeat True))	Chap. 7 Chap. 8
where n = length xs	Chap. 9
	Chap. 10
Nato, This alwayithm	Chap. 11
Note: This algorithm	Chap. 12
does not require the elements of xs to be distinct	Chap. 13
but does require them to be noticed numbers	Chap. 14

but does require them to be natural numbers

```
Two Variants of the Array-Based Algorithm (1)
 1st Variant: The function accumArray can be used to
   sort a list of numbers in linear time, provided the
     elements of the list all lie in some known range.
 This allows
   replacing of checklist by countlist.
                                                            4.3
  countlist :: [Int] -> Array Int Int
  countlist xs =
    accumArray (+) 0 (0,n) (zip xs (repeat 1))
  sort xs =
    concat [replicate k x | (x,k) <- countlist xs]</pre>
 Replacing checklist by countlist and sort, the
 implementation of minfree
```

boils down to finding the first 0 entry.

```
Two Variants of the Array-Based Algorithm (2)
 2nd Variant: Instead of using a smart library function as in the
 1st variant, checklist can be implemented
   using a constant-time array update operation.
 In Haskell, this can be done using a suitable monad, such as
 the
                                                                4.3
   state monad (cf. Data.Array.ST)
  checklist xs =
    runSTArray (do
       {a <- newArray (0,n) False;</pre>
       sequence [writeArray a x True | x<-xs, x<=n];</pre>
       return a})
    where n = \text{length } xs
 Note, however: This variant is essentially
   a procedural program in functional clothing.
```

Towards the Divide-and-Conquer Algorithm (1) Algorithmic idea:

Express minfree (xs++ys) in terms of minfree (xs) and minfree (ys).

First, we collect some properties satisfied by the set difference operation:

$$(as ++ bs) \setminus \langle cs \rangle = (as \setminus \langle cs \rangle ++ (bs \setminus \langle cs \rangle) \\ as \setminus \langle bs ++ cs \rangle \rangle = (as \setminus \langle bs \rangle \setminus \langle cs \rangle \\ (as \setminus \langle bs \rangle \setminus \langle cs \rangle \rangle = (as \setminus \langle cs \rangle \setminus \langle bs \rangle \\ bs \rangle$$

If as and vs are disjoint (i.e., as//vs == as), and bs and us are disjoint (i.e., bs//us == bs), we also have:

 $(as ++ bs) \setminus (us ++ vs) = (as \setminus vs) ++ (bs \setminus vs)$

4.3 271/135

Towards the Divide-and-Conquer Algorithm (2)

Going on, choose any natural number b, and let

- ▶ as = [0..b-1], ▶ bs = [b..],
 - ▶ us = filter (<b) xs,
 - ▶ vs = filter (>=b) xs

then

as and vs are disjoint, and bs and us are disjoint.

This implies:

where **partition** is a Haskell library function that partitions a list into those elements satisfying some property and those that do not.

4.3 272/135 The Divide-and-Conquer Algorithm

Moreover, because of head (xs++ys) = if null xsthen head ys else head xs 4.3 we obtain (still for any natural number b): The Basic Divide-and-Conquer Algorithm: minfree xs = if (null ([0..b-1]) \\ us) then (head ([b..]) \\ vs) else (head $([0..]) \setminus us$) where (us,vs) = partition (<b) xs

Chap 14

Chap. 15 273/135

Refining the Divide-and-Conquer Algorithm (1)

Note, the straightforward evaluation of the test

(null ([0..b-1]) \\ us) takes quadratic time in the length of us.

Note also, the lists [0..b-1] and us are lists of

- distinct natural numbers, and
- every element of us is less than b.

This allows us to replace the test by a test on the length of us:

null ([0..b-1] \\ us) = length us == b

Note, unlike for the array-based algorithm, it is crucial that the argument list does not contain duplicates to obtain an efficient

divide-and-conquer algorithm.

4.3 274/135

Refining the Divide-and-Conquer Algorithm (2)

Inspecting minfree in more detail reveals that it can be generalized to a function minfrom:

```
minfrom :: Nat -> [Nat] -> Nat
minfrom a xs = head ([a..] \\ xs)
```

where every element of \mathbf{xs} is assumed to be

greater than or equal to a.



```
Refining the Divide-and-Conquer Algorithm (3)
 Provided b is chosen so that both
  length us and length vs are less than length xs
the below recursive definition of minfree is well-founded:
                                                         4.3
 minfree xs = minfrom 0 xs
 minfrom a xs | null xs
                                    = a
                | length us == b-a = minfrom b vs
                | otherwise
                                = minfrom a us
                 where (us,vs) = partition (<b) xs
```

Refining the Divide-and-Conquer Algorithm (4)

It remains to choose b. This choice shall ensure: 4.3 ▶ b > a ▶ The maximum of the lengths of us and vs is minimum. This is achieved by choosing b as b = a + 1 + n 'div' 2 where n = length xs.

Chap 14

Chap. 15 277/135

Refining the Divide-and-Conquer Algorithm (5)

If n \neq 0 and length us \leq b-a, then

▶ (length us) <= (n div 2) < n

And, if length us = b-a, then

▶ (length vs) = (n - (n div 2) - 1) <= n div 2

With this choice, the number of steps for evaluating

minfrom 0 xs

is linear in the number of elements of xs.

4.3

The Optimized Divide-and-Conquer Algorithm

As a final optimization, we represent xs by a pair (length xs, xs) in order to avoid to repeatedly compute length.

The Optimized Divide-and-Conquer Algorithm:

```
minfree xs = minfrom 0 (length xs, xs)
minfrom a (n,xs)
| n == 0 = a
| m == b-a = minfrom b (n-m,vs)
| otherwise = minfrom a (m,us)
where (us,vs) = partition (<b) xs
b = a + 1 + n div 2
m = length us</pre>
```

4.3 279/135

Summing up

The optimized divide-and-conquer algorithm is about

- ▶ twice as fast as the incremental array-based program, and
- ► 20% faster than the accumArray-based program.

It is worth noting, the SFN-problem is not artificial:

 It can be considered a simplification of the common programming task to find some object not in use: Numbers then name objects, and X the set of objects that are currently in use.



Summing up (Cont'd)

- For a "procedural" programmer
 - an array-update operation takes constant time in the size of the array.

For a "pure functional" programmer

 an array-update operation takes logarithmic time in the size of the array.

This explains

why there sometimes seems to be a logarithmic gap between the best functional and the best procedural solutions to a problem.

Sometimes, however, this gap

vanishes as for the SFN-problem.

4.3 281/135

Chapter 4.4 Not the Maximum Segment Sum

4.4 282/135

Background and Motivation

A segment of a list

is a contiguous subsequence.

The Maximum Segment Sum (MSS) Problem:

- ▶ Let *L* be a list of (positive and negative) integers.
- Compute the maximum of the sums of all possible segments of *L*.

Example:

Let L be the list

► [-4,-3,-7,2,1,-2,-1,-4].

The maximum segment sum of L is

▶ 3 (from the segment [2,1]).



Background and Motivation (Cont'd)

The MSS-problem

had been considered quite often in the late 1980s mostly as a showcase for programmers to illustrate and demonstrate their favorite style of program development or their particular theorem prover.

In this pearl, however,

▶ we consider the "Maximum Non-Segment Sum (MNSS) Problem". 4.4 284/135

The Maximum Non-Segment Sum (MNSS) Problem

A non-segment of a list

is a subsequence that it is not a segment, i.e., a non-segment has one or more "holes" in it.

The Maximum Non-Segment Sum (MNSS) Problem:

- ▶ Let *L* be a list of (positive and negative) integers.
- Compute the maximum of the sums of all possible non-segments of *L*.

Example:

Let L be the list

► [-4,-3,-7,2,1,-2,-1,-4].

The maximum non-segment sum of L is

▶ 2 (from the non-segment [2,1,-1]).

4.4

What does MNSS make a Pearl Problem?

It is worth noting: Let *L* be a list of length *n*. • There are $\Theta(n^2)$ segments of L. • There are $\Theta(2^n)$ subsequences of L. Hence There are many more non-segments of a list than segments. This raises the problem Can the maximum non-segment sum be computed in linear time? This (pearl) problem will be tackled in this chapter.

4.4 286/135

Specifying Solution of the MNSS-Problem

The Specifying (Initial) Solution of the MNSS-Problem:

```
mnss :: [Int] -> [Int]
mnss = maximum . map sum . nonsegs
```

Intuition:

- First, nonsegs computes a list of all non-segments of the argument list,
- map sum then computes the sum of all these non-segments, and
- maximum, finally, picks those whose sum is maximum.

4.4 287/135

The Implementation of nonsegs

The implementation of the function nonsegs

nonsegs :: [a] -> [[a]]
nonsegs = extract . filter nonseg . markings

relies on the supporting functions

extract

markings

which itself relies on the supporting function

▶ booleans

4.4 288/135
The Implementation of nonsegs (Cont'd)

The implementation of the supporting functions:

extract :: [[(a,Bool)]] -> [[a]]
extract = map (map fst . filter snd)

4.4

The Implementation of nonsegs (Cont'd)

Intuition underlying the supporting functions:

To define the function nonsegs

each element of the argument list is marked with a Boolean value: True indicates that the element is included in the non-segment; False indicates that it is not.

This marking

 takes place in all possible ways, done by the function marking (Note: Markings are in one-to-one correspondence with subsequences.)

Then

the function extract filters for those markings that correspond to a non-segment, and then extracts those whose elements are marked True.



The Implementation of nonsegs (Cont'd)

The function

nonseg :: [(a,Bool)] -> Bool, finally, returns True on a list xms iff map snd xsm describes a non-segment marking (its implementation is given later).

Last but not least:

The Boolean list ms is a non-segment marking iff it is an element of the set represented by the regular expression

 $F^{*}T^{+}F^{+}T(T+F)^{*}$

where \mathtt{True} and \mathtt{False} are abbreviated by T and F, respectively.

Note: The regular expression identifies the leftmost gap T^+F^+T that makes the segment a non-segment.



The Finite State Automaton

... for recognizing members of the corresponding regular set:

data State = E | S | M | N

Intuition:

The 4 states of the above automaton are used as follows:

- State E (for Empty), starting state: if in E, markings only in the set F* have been recognized.
- State S (for Suffix): if in state S, one or more T s have been processed; hence, this indicates markings in the set F*T⁺, i.e., a non-empty suffix of T s.
- State M (for Middle): if in state M, this indicates the processing of markings in the set F*T+F+, i.e., a middle segment.
- State N (for Non-segment): if in state N, this indicates the processing of non-segments markings.

4.4 292/135

The Finite State Automaton (Cont'd)

This allows us to define:

nonseg = (== N) . foldl step E . map snd where the middle term foldl step E executes the step of

the finite automaton:

step	Е	False	=	Е	step	М	False	=	М
step	Е	True	=	S	step	М	True	=	Ν
step	S	False	=	М	step	N	False	=	Ν
step	S	True	=	S	step	N	True	=	Ν

It is worth noting:

- Finite automata process their input from left to right. This leads to the use of foldl.
- The input could have been processed from right to left as well, looking for the rightmost gap. This, however, would be less conventional without any benefit from breaking the left to right processing convention.

4.4 293/135

Towards Deriving the Linear Time Algorithm

Recall first the specifying (initial) solution of the MNSS-Problem with nonsegs replaced by its supporting functions:

Work plan:

- Express extract . filter nonseg . markings as an instance of foldl.
- Apply then the fusion law of foldl to arrive at a better algorithm.

4.4 294/135

Deriving the Linear Time Algorithm (1)

First, we introduce the function pick:

```
pick :: State -> [a] -> [[a]]
pick q
= extract .
    filter ((== q) . foldl step E . map snd) .
    markings
```

We have:

nonsegs == pick N

4.4

Properties of pick

Moreover, we can prove

- either by calculation from the definition of pick q (which is tedious!)
- or by referring to the definition of step the equalities:
 - pick E xs = [[]] pick S [] = [] pick S (xs++[x]) = map (++[x])(pick S xs) ++ pick E xs) pick M [] = [] pick M (xs++[x]) = pick M xs ++ pick S xs pick N [] = [] pick N (xs++ys) = pick N xs ++ map (++[x]) (pick N xs) ++ pick M xs)

4.4 296/135

Deriving the Linear Time Algorithm (2)

Second, we recast the definition of pick as an instance of foldl.

To this end, let **pickall** be specified by:

This allows us to express pickall as an instance of foldl:

4.4 297/135 Two new Solutions of the MNSS-Problem The 1st new Solution of the MNSS-Problem: mnss = maximum . map sum . fourth . pickall where **fourth** returns the fourth element of a quadruple. By means of function tuple tuple f (w,x,y,z) = (f w, f x, f y, f z)fourth can be moved to the front of the defining expression of mnss: maximum . map sum . fourth = fourth . tuple (maximum . map sum) This allows the 2nd new Solution of the MNSS-Problem: mnss = fourth . tuple (maximum . map sum) . pickall

4.4 298/135

The Fusion Law of foldl

The Fusion Law of foldl:

f (foldl g a xs) = foldl h b xs

for all finite lists xs provided that for all x and y holds:

Towards the Application of the Fusion Law (1)		
in our scenario to the instantiations:		
f = tuple (maximum . map sum)		
g = step a = ([[]], [],[], [])	Cha 4.1 4.2 4.3 4.4	
We are now left with finding h and b to satisfy the conditions of the fusion law.	4.5 Cha Cha	

Because the maximum of an empty set of numbers is $-\infty$, we have:

tuple (maximum . map sum) ([[]], [],[], []) = $(0, -\infty, -\infty, -\infty)$

...which gives the definition of b.



This is demonstrated for the fourth component in detail. The reasoning for the three components is similar.

4.4 301/135

Towards the Application of the Fusion Law (3) max is used as an abbreviation for maximum: max (map sum (nss dpl map (++ [x]) (nss ++ mss)))

= (definition of *map*) $max (map sum nss ++ map (sum . (++[x]))(nss ++ mss))_{1}^{Chap. 4}$ = (since sum . (++[x]) = (+x) . sum)4.4 max (map sum nss ++ map ((+x) . sum) nss ++ mss))= (since max (xs++ys) = (max xs) max (max ys))max (map sum nss) max max (map ((+x) . sum) (nss++mss))= (since max . map (+x) = (+x) . max) $max (map sum nss) max (max (map sum (nss++mss)) + x)^{ap 10}$ = (introducing n = max (map sum nss) and m = max (map sum mss) $n \max ((n \max m) + x)$

Chap. 14 Chap. 15 302/135

Towards the Application of the Fusion Law (4) Finally, we arrive at the implementation of h: h (e, s, m, n) x 4.4 = (e, (s max e)+x, m max s, n max ((n max m) + x)) This allows the 3rd new Solution of the MNSS-Problem: mnss = fourth . foldl h $(0, -\infty, -\infty, -\infty)$ 303/135

The Linear Time Algorithm

We are left with dealing with the fictitious ∞ values.

Here, we eliminate them entirely by considering the first three elements of the list separately, which gives us:

The Linear Time Algorithm for the MNSS-Problem:

mnss xs
= fourth (foldl h (start (take 3 xs)) (drop 3 xs))
start [x,y,z]
= (0, max [x+y+z,y+z,z], max [x,x+y,y], x+z)

4.4 304/135

Concluding Remarks (1)

The MSS problem goes back to Bentley:

 Jon R. Bentley. Programming Pearls. Addison-Wesley, 1987.

Gries and Bird later on presented an invariant assertions and algebraic approach, respectively.

- David Gries. The Maximum Segment Sum Problem. In Formal Development of Programs and Proofs. Edsger W. Dijkstra (Ed.), Addison-Wesley, 43-45, 1990.
- Richard Bird. Algebraic Identities for Program Calculation. Computer Journal 32(2):122-126, 1989.

4.4

Recent results on the MSS-problem can be found in:

 Shin-Cheng Mu. The Maximum Segment Sum is Back. In Proceedings of the ACM SIGPLAN Symposium on Partial Evaluation and Program Manipulation (PEPM 2008), 31-39, 2008. 4.4

Chapter 4.5 A Simple Sudoku Solver

4.5

Sudoku Puzzles

	3	7	8		6			5
		5	2	7			3	
				3	5		6	8
		1					9	3
		2		5		4		
5	7					8		
2	1		5	6				
	4			2	1	5		
6			3		7	2	4	

Fill in the grid so that every row, every column, and every 3×3 box contains the digits 1 - 9. There's no maths involved. You solve the puzzle with reasoning and logic.

The Independent Newspaper

Contents

Towards the Specifying Solution (1)

Preliminary definitions:

 $m \times n$ -matrix: A list of m rows of the same length n.

type Matrix a = [Row a] type Row a = [a]

Grid: A 9 \times 9-matrix of digits.

```
type Grid = Matrix Digit
type Digit = Char
```

Valid digits: '1' to '9'; '0' stands for a blank.

```
digits = ['1'..'9']
blank = (== '0')
```

Towards the Specifying Solution (2)

We assume that the input grid is valid, i.e.,

- it contains only digits and blanks
- no digit is repeated in any row, column or box.



Towards the Specifying Solution (3)

There are two straigthforward (brute force) approaches to solving a Sudoku puzzle:

- 1. 1st Approach:
 - Construct a list of all correctly completed grids.
 - Then test the input grid against them to identify those whose non-blank entries match the given ones.
- 2. 2nd Approach:
 - Start with the input grid and construct all possible choices for the blank entries.
 - Then compute all grids that arise from making every possible choice and filter the result for the valid ones.

In the following we follow the 2nd approach to define the specifying initial solution of the Sudoku-problem.

4.5 311/135

Specifying Solution of the Sudoku-Problem (1)	
The Specifying (Initial) Solution of the Sudoku-Problem:	
solve = filter valid . expand . choices	
choices :: Grid -> Matrix Choices expand :: Matrix Choices -> [Grid] valid :: Grid -> Bool	Chap. 4.1 4.2 4.3 4.4 4.5
Intuition:	

- choices constructs all choices for the blank entries of the input grid,
- expand then computes all grids that arise from making every possible choice,

312/135

filter valid finally selects all the valid grids.

Specifying Solution of the Sudoku-Problem (2)

To represent the set of choices we introduce the data type:

type Choices = [Digit]

This allows us to define the subsidiary functions of solve, i.e.,

- ▶ choices
- expand
- ▶ valid

4.5

Specifying Solution of the Sudoku-Problem (3)

The implementation of choices:

choices :: Grid -> Matrix Choices choices = map (map choice) choice d = if blank d then digits else [d]

Intuition:

- If the cell is blank, then all digits are installed as possible choices.
- Otherwise there is no choice and a singleton is returned.

4.5 314/135

Specifying Solution of the Sudoku-Problem (4)

The implementation of expand:

```
expand :: Matrix Choices -> [Grid]
expand :: cp . map cp
```

```
cp :: [[a]] -> [[a]]
cp [] = [[]]
cp (xs:xss) = [x:ys | x <- xs, ys <- cp xss]
```

Intuition:

- Expansion is a Cartesian product, i.e., a list of lists given by the function cp, e.g., cp[[1,2],[3],[4,5]] ->> [[1,3,4],[1,3,5],[2,3,4],[2,3,5]]
- map cp then returns a list of all possible choices for each row.
- cp . map cp, finally, installs each choice for the rows in all possible ways.

4.5 315/135

Specifying Solution of the Sudoku-Problem (5)

The implementation of valid:

Intuition:

 A grid is valid, if no row, column or box contains duplicates. 4.5 316/135

Specifying Solution of the Sudoku-Problem (6)

The implementation of rows and columns:

```
rows :: Matrix a -> Matrix a
rows = id
```

```
cols :: Matrix a -> Matrix a
cols [xs] = [ [x] | x <- xs]
cols (xs:xss) = zipWith (:) xs (cols xss)</pre>
```

Intuition:

- rows is the identity function, since the grid is already given as a list of rows.
- columns computes the transpose of a matrix.

4.5

Specifying Solution of the Sudoku-Problem (7) The implementation of boxs: boxs :: Matrix a -> Matrix a	
Chap	
hovs ·· Matrix a -> Matrix a	
Chap	
boxs = map ungroup . ungroup . map cols .	
group :: [a] -> [[a]] 41 group :: [a] -> [[a]] 42 43 group [] = [] 45	
group xs = take 3 xs : group (drop 3 xs)	
ungroup :: [[a]] -> [a]Chapungroup = concatChap	р. 7
Intuition: Chap	

- group splits a list into groups of three.
- ungroup takes a grouped list and ungroups it.
- group . map group produces a list of matrices; transposing each matrix and ungrouping them yields the boxes.

Specifying Solution of the Sudoku-Problem (8)

Illustrating the action of boxs for the 4×4 -case, when group splits a list into groups of two:

$$\begin{pmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & k \\ m & n & o & p \end{pmatrix} \rightarrow \begin{pmatrix} \begin{pmatrix} ab & cd \\ ef & gh \end{pmatrix} \\ \begin{pmatrix} ij & kl \\ mn & op \end{pmatrix} \end{pmatrix} \rightarrow \begin{pmatrix} \begin{pmatrix} ab & ef \\ cd & gh \end{pmatrix} \\ \begin{pmatrix} ij & mn \\ kl & op \end{pmatrix}$$

4.5 319/135

Wholemeal Programming

Instead of

- thinking about matrices in terms of indices, and
- doing arithmetic on indices to identify rows, columns, and boxes

the present approach has gone for functions that

treat the matrix as a complete entity in itself.

Geraint Jones coined the notion	
 wholemeal programming 	
for this style of programming.	
Wholemeal programming helps	
avoiding indexitis and	
encourages lawful program construction.	



Lawful Programming

Example:

•	The 3 laws (A), (B), and (C) hold on arbitrary $N \times N$ -matrices, in particular on 9×9 -grids:	
	rows . rows = id	(A)
	cols . cols = id	(B)
	boxs . boxs = id	(C)
	This means, all 3 functions are involutions.	
	The 3 laws (D), (E), and (F) hold on $N^2 \times N^2$ -matr	ices:
	map rows . expand = expand . rows	(D)
	<pre>map cols . expand = expand . cols</pre>	(E)
	<pre>map boxs . expand = expand . boxs</pre>	(F)

4.5 321/135 A Quick Analysis of the Specifying Solution

Suppose that half of the entries (cells) of the input grid are fixed.

Then there are about 9^{40} , or

147.808.829.414.345.923.316.083.210.206.383.297.601

to be constructed and checked for validity!

This is hopeless!

4.5 322/135

Towards a Better Performing Algorithm

```
Pruning the matrix of choices:
```

Idea

Remove any choices from a cell c that occurs as a singleton entry in the row, column or box containing c.

```
Hence, we are seeking for a function
```

```
prune :: Matrix Choices -> Matrix Choices
```

```
that satisfies
```

```
filter valid . expand
  = filter valid . expand . prune
```

```
and realizes the above idea.
```



Towards defining prune

Pruning a row

where

remove xs ds
= if singleton ds then ds else ds \\ xs

Intuition:

remove removes choices from any choice that is not fixed.

4.5 324/135
Laws for pruneRow, nodeups, and cp

- > The function pruneRow satisfies law (G):
 If f is an involution, i.e., f . f = id, then
 filter nodups . cp
 = filter nodups . cp . pruneRow
- The functions nodeups and cp satisfy laws (H) and (l): filter (p.f) = map f . filter p . map f (H) filter (all p) . cp = cp . map (filter p) (I)

4.5

325/135

(G)

Rewriting filter valid . expand We can prove:

filter valid . expand = filter (all nodups . boxs) . filter (all nodups . cols) . filter (all nodups . rows) . expand

It is worth noting:

The order of the 3 filters on the right hand side above is not relevant.

Work plan:

• Apply each of the filters to expand.

This requires some reasoning which we exemplify for the boxs case.

4.5 326/135

Reasoning in the boxs Case (1)

4.5

filter (all nodups . boxs) . expand $= \{(H), \text{ since } boxs \cdot boxs = id\}$ map boxs . filter (all nodups) . map boxs . expand $= \{(F)\}$ map boxs . filter (all nodups) . expand boxs = {definition of *expand*} map boxs . filter (all nodups) . cp . map cp . boxs = {(I), and map f . map g = map (f . g)} map boxs . cp . map (filter nodups . cp) . boxs $= \{(G)\}$ map boxs . cp . map (filter nodups . cp . pruneRow) . boxschap. 13

Reasoning in the boxs Case (2)

	((1))	
=	{(I)}	
	map boxs . filter (all nodups) . cp .	
	map cp . map pruneRow . boxs	Chap. 4 4.1
=	{definition of <i>expand</i> }	4.2 4.3 4.4
	map boxs . filter (all nodups) . expand .	4.5 Chap. 5
	map pruneRow . boxs	Chap. 6
=	$\{(H) \text{ in the form } map f \cdot filter p = filte (p \cdot f) \cdot map f \}$	Chap. 7
	filter (all nodups . boxs) . map boxs . expand .	Chap. 8 Chap. 9
	map pruneRow . boxs	Chap. 10
_	{(F)}	Chap. 11
_		Chap. 12
	filter (all nodups . boxs) . expand . boxs .	Chap. 13
	map pruneRow . boxs	Chap. 14
		Chap 15

Summing up

We have shown: filter (all nodups . boxs) . expand = filter (all nodups . boxs) . expand . pruneBy boxs		
where		
<pre>pruneBy f = f . map pruneRow . f</pre>		
Repeating the same calculation for rows and cols we get:		
filter valid . expand		
= filter valid . expand . prune		
where		
prune		
<pre>= pruneBy boxs . pruneBy cols . pruneBy rows</pre>		

4.5 Chap. 15 329/135 2nd and Improved Implementation of solve

The Pruning-improved Implementation of solve:

solve = filter valid . expand . prune . choices

4.5

330/135

It is worth noting:

Pruning can be done more than once.

- After each round of pruning some choices might be resolved into singletons allowing the next round of pruning to remove even more impossible choices.
- For simple Sudoku problems repeated rounds of pruning will eventually yield the solution of the input Sudoku problem.

Tuning the Solver Further

Idea

cell only.

 Combine pruning with expanding the choices for a single cell only at a time:

 \rightsquigarrow single-cell expansion

To this end we replace the function expand by a new version

expand = concat . map expand . expand1 (J) where expand1 (defined next) expands the choices of a single 4.5 331/135

Towards defining expand1

Which cell to expand?

 Any cell with the smallest number of choices for which there are at least 2 choices.

Note:

If there is a cell with no choices then the Sudoku problem is unsolvable.

(From a pragmatic point of view, such cells should be identified quickly.)

4.5

Defining expand1

Think of a cell containing cs choices as sitting in the middle of a row row, i.e., row = row1 ++ [cs] ++ row2, in the matrix of choices, with rows rows1 above it and row rows2 below it:

expand1 :: Matrix Choices -> [Matrix Choices]
expand1 rows

= [rows1 ++ [row1 ++ [c] : row2] ++ rows2 | c<-cs] where

(rows1,row:rows2) = break (any smallest) rows (row1, cs:row2) = break smallest row smallest cs = length cs == n n = minimum (counts rows) counts = filter (/=1) . map length . concat

break p xs

= (takeWhile (not . p) xs, dropWhile (not . p) xs)

4.5

Remarks on expand1

- The value n is the smallest number of choices, not equal to 1 in any cell of the matrix of choices.
- If the matrix contains only singleton choices, then n is the minimum of the empty list, which is not defined.
- ► The standard function break p splits a list into two.
- break (any smallest) rows thus breaks the matrix into two lists of rows with the head of the second list being some row that contains a cell with the smallest number of choices.
- Another application of break then breaks this row into two sub-rows, with the head of the second being the element cs with the smallest number of choices.
- Each possible choice is installed and the matrix reconstructed.
- ▶ If there are no choices, expand1 returns an empty list.

4.5 334/135

Completeness and Safety of a Matrix

The definition of n implies that (J) only holds when

applied to matrices with at least one non-singleton choice.

This suggests:

A matrix is

- complete, if all choices are singletons,
- unsafe, if the singleton choices in any row, column or box contain duplicates.

It is worth noting:

- Incomplete and unsafe matrices can never lead to valid grids.
- A complete and safe matrix of choices determines a unique valid grid.

4.5 335/135 Completeness and Safety Tests

Completeness and safety can be tested as follows.

```
Completeness Test:
complete = all (all single)
where single is the test for a singleton list.
```

```
► Safety Test:
```

safe m
= all ok (rows m) &&
 all ok (cols m) &&
 all ok (boxs m)

where

```
ok row = nodups [d | [d] <- row]
```



We can show

If a matrix is safe but incomplete, we can calculate:

filter valid . expand
= {since expand = concat . map expand . expand1
on incomplete matrices}
filter valid . concat . map expand . expand1
= {since filter p . concat = concat . map (filter p)}
concat . map (filter valid . expand) . expand1
= {since filter valid . expand = filter valid . expand . prune}

concat . map (filter valid . expand . prune) . expand1

4.5

```
3rd and Final Implementation of solve
 Introducing
  search = filter valid . expand . prune
 we have on safe but incomplete matrices that
  search . prune = concat . map search . expand1
                                                        4.5
 This allows:
 The Final Implementation of solve:
  solve = search. choices
  search m
    | not (safe m) = []
    complete m' = [map (map head) m']
    otherwise = concat (map search (expand1 m'))
      where m' = prune m
```

Quality and Performance Assessment

The final version of the Sudoku solver has been tested on various Sudoku puzzles available at

- haskell.org/haskellwiki/Sudoku
- It is reported that the solver
 - turned out to be most useful, and
 - competitive to (many) of the about a dozen different Haskell Sudoku solvers available at this site.

While many of the other solvers use arrays and monads, and reduce or transform the problem to

 Boolean satisfiability, constraint satisfaction, modelchecking, etc.

the solver presented here seems unique in terms of length, conceptual simplicity and that it has been derived in part by

equational reasoning.

4.5 339/135

Chapter 4: Further Reading (1)

- Jon R. Bentley. Programming Pearls. Addison-Wesley, 1987.
- Jon R. Bentley. *Programming Pearls*. Addison-Wesley, 2nd edition, 2000. (Excerpt of the book online available from www.cs.bell-labs.com/cm/cs/pearls)
- Richard Bird. Algebraic Identities for Program Calculation. Computer Journal 32(2):122-126, 1989.
- Richard Bird. Fifteen Years of Functional Pearls. In Proceedings of the 11th ACM SIGPLAN International Conference on Functional Programming (ICFP 2006), 215, 2006.

4.5

Chapter 4: Further Reading (2)

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4.5

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4.5 344/135

Part III Quality Assurance

4.5

Chap. 15 345/135

Chapter 5 Testing

Chap. 5

Chap. 14 346/135

Objective

How can we gain (sufficiently much) confidence that

- ours and
- other people's programs

are sound?

Essentially, there are two means at our disposal:

- Verification
- ► Testing



Verification vs. Testing

Verification

- Formal soundness proof (soundness of the specification, soundness of the implementation).
- High confidence but often high effort.

Testing

- Two Variants
 - Ad hoc: Controllable effort but usually unquantifiable, questionable quality statement.
 - Systematically: Controllable effort with quantifiable quality statement.

Chap. 5 348/135

Testing can only show the presence of errors. Not their absence.

Edsger Dijkstra

On the other hand, testing is often

amazingly successful in revealing errors.

Minimum Requirements of Testing

(Systematic) testing of programs should be

- Specification-based
- Tool-supported
- Automatically

Chap. 4
Chap. 5
5.1
5.2
5.3
5.4
5.5
5.6
5.7
Chap. 6
Chap. 7
Chap. 8
Chap. 9
Chap. 10
Chap. 11
Chap. 12
Chap. 13
Chap. 14 350/135

Minimum Requirements of Testing (Cont'd)

There shall be reporting on	
 What has been tested? How thoroughly, how comprehensively has been tested? How was success defined? 	Chap. 4 Chap. 5 5.1 5.2 5.3 5.4 5.5 5.6 5.7
Desirable, too	Chap. 6
	Chap. 7
 Reproducibility of tests 	Chap. 8
Repeated testing after program modifications	Chap. 9
	Chap. 1
	Chap. 1
	Chap. 1

Program Specification

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- Specification of the meaning of the program
 - ► Informally (e.g., as commentary in the program, in a separate documentation)
 → disadvantage: often ambiguous, open to interpretation
 - Formally (e.g., in terms of pre- and post-conditions, in a formal specification language)
 → advantage: precise and rigorous, unambiguous

Chap. 5 352/135

In this chapter

Specification-based, tool-supported testing in Haskell with QuickCheck:

- QuickCheck (a combinator library)
 - defines a formal specification language
 ...that allows property definitions inside of the (Haskell) source code.
 - defines a test data generator language

 ...that allows a simple and concise description of a large
 number of tests.
 - allows tests to be repeated at will ...which ensures reproducibility.
 - allows automatic testing of all properties specified in a module, including failure reports
 ...that are automatically generated.

Chap. 5 353/135

It is worth noting

QuickCheck and its specification and test data generator languages are:

 Examples of so-called domain-specific embedded languages

 \rightsquigarrow special strength of functional programming.

- Implemented as a combinator library in Haskell
 allows us to make use of the full expressiveness of
 Haskell when defining properties and test data generators.

Chap. 5 354/135

Chapter 5.1 Property Definitions

5.1

Chap. 14 355/135

Simple Property Definition w/ QuickCheck (1)

In the simplest cases properties are defined in terms of predicates, i.e., as Boolean valued functions.

Example:

Define inside of the program the property

prop_PlusAssociative :: Int -> Int -> Int -> Bool prop_PlusAssociative x y z = (x+y)+z == x+(y+z)

Double-checking the property with Hugs yields:

Main>quickCheck prop_PlusAssociative OK, passed 100 tests

Simple Property Definition w/ QuickCheck (2)

Note:

- The type specification for prop_PlusAssociative is required because of the overloading of (+) (otherwise there will be an error message on ambiguous overloading: QuickCheck needs to know which test data to generate).
- The type specification allows a type-specific generation of test data.

Simple Property Definition w/ QuickCheck (3) The same example slightly varied: Define inside of the program the property prop_PlusAssociative :: Float -> Float -> Float 51 -> Bool prop_PlusAssociative x y z = (x+y)+z == x+(y+z)Double-checking the property with Hugs yields: Main>quickCheck prop_PlusAssociative Falsifiable, after 13 tests: 1.0 -5.16667-3.71429

Simple Property Definition w/ QuickCheck (4)	
Note:	
 The property is falsifiable for type Float: think e.g. of rounding errors. 	Chap. 5 5.1 5.2 5.3 5.4 5.5
The error report contains:	5.6 5.7 Chap. 6
 The number of tests successfully passed A counter example 	Chap. 7 Chap. 8
 A counter example 	Chap. 9 Chap. 10
	Chap. 11 Chap. 12
	Chap. 13
	Chap. 14 359/135

Advanced Property Definition (1)

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- A function insert
- A predicate ordered

Property under test:

Insertion into a sorted list

A straightforward property definition to double-check the correctness of the insertion funcion were:

prop_InsertOrdered :: Int -> [Int] -> Bool
prop_InsertOrdered x xs = ordered (insert x xs)

However, this property is falsifiable.

The definition is naive and too strong (note that xs is not supposed to be sorted).
Advanced Property Definition (2)

First fix (trial-and-error):

Note:

ordered xs ==>: This adds a precondition to the property definition.

 \rightsquigarrow Generated test data that do not match the precondition, are dropped.

==>: is not a simple Boolean operator but affects the selection of test data.

 \rightsquigarrow Property definitions that rely on such operators always have the result type <code>Property</code> in <code>QuickCheck</code>.

 Overall: A trial-and-error approach to generating test data: Generate, then check if usable; if not, drop. 51 361/135

Advanced Property Definition (3)

```
Second Fix (systematic):
```

```
prop_InsertOrdered :: Int -> Property
prop_InsertOrdered x =
  forAll orderedLists $ \xs -> ordered (insert x xs)
```

Note:

- This fix works by direct quantifying (in the running example: direct quantifying over sorted lists)
- Overall: A systematic approach to generating test data: Only useful test data are generated.

```
51
362/135
```

The Operator (\$) — A Quick Reminder

Standard Prelude:

Remark:

- The operator (\$) is Haskell's infix function application.
- It is useful to avoid the usage of parentheses:
 Example: f (g x) can be written as f \$ g x.



It is worth noting

Expressiveness:

QuickCheck supports also the specification of more sophisticated properties, e.g.

 The list resulting from insertion coincides with the argument list (except of the inserted element).

Testing multiple properties:

A (small) program (also called quickCheck) can be run from the command line

>quickCheck Module.hs

in order to test all properties defined in Module.hs at once.

51 364/135

Chapter 5.2 Testing against Abstract Models

5.2 Chap. 14 365/135 Testing the correctness of an implementation against a reference implementation, a so-called

abstract model (reference model)

In the following:

 Demonstrating this by an extended example: Developing an abstract data type for queues. 5.2 366/135

Abstract Model of Queues

An abstract data type for first-in-first-out (FIFO) queues.

Specification:

type Queue a	=	[a]	
empty	=	[]	
add x q	=	q ++ [x] inefficient due to ++	1
isEmpty q	=	null q	
<pre>front (x:q)</pre>	=	x	
<pre>remove (x:q)</pre>	=	q	

This is a simple (but inefficient) implementation that we consider the abstract model of a FIFO queue; it is our reference model of a FIFO queue.

5.2 367/135

The Concrete Model of Queues (1)

...the implementation of interest, a more efficient implementation than the one of the abstract model.

Basic Idea:

- Split the list into two portions (a list front and a list back)
- Store the back of the list in reverse order

Together this ensures:

. . .

► Efficient access to list front and list back
→ ++ for addition boils down to : (strength reduction)

Example:

- Abstract queue: [7,2,9,4,1,6,8,3]++[5]
- Possible concrete queues:
 - ([7,2,9,4],5:[3,8,6,1])
 - ([7,2],5:[3,8,6,1,4,9])

5.2 368/135 The Concrete Model of Queues (2)

Implementation:

type QueueI a	= ([a],[a])		
emptyI	= ([],[])		
addI x (f,b)	= (f,x:b)		
isEmptyI (f,b)	= null f		
frontI (x:f,b)	= x		
removeI (x:f,b)	= flipQ (f,b)		
where			
flipQ ([],b)) = (reverse b, [])		
flipQ q	= q		

Chap. 4
5.1
5.2 5.3
5.4
5.5
5.6
5.7
Chap. 6
Chap. 7
Chap. 8
Chap. 9
Chap. 10
Chap. 11
Chap. 12
Chap. 13
Chap. 14 369/13

In the following

We think of

- Queue and
- ► QueueI

in terms of

- specification and
- implementation
- of FIFO queues, respectively.

Next we want to double-check/test if operations defined on QueueI (implementation / queues) behave in the same way as the operations defined on Queue (specification / abstract queues).

5.2 370/135

Relating Queues and Abstract Queues

...by means of a retrieve function:

```
retrieve :: QueueI Integer -> [Integer]
retrieve (f,b) = f ++ reverse b
```

The function retrieve

transforms each of the (usually many) concrete representations, i.e., values of QueueI, of an abstract queue, i.e., a value of Queue, into their unique canonical representation of an abstract queue. 5.2 371/135

Soundness Properties for Operations on Queuel

The understanding of QueueI and Queue as lists on integers

 allows us to omit type specifications in the definitions of properties defined next.

By means of retrieve we can double-check, if

the results of applying the efficient operations on QueueI coincide with those of the abstract operations on Queue.

5.2 372/135

Soundness Properties: Initial Definitions (1)

The below properties can reasonably be expected to hold:

However, this is not true!

```
5.2
373/135
```

Soundness Properties: Initial Definitions (2)

Testing e.g. prop_isEmpty using QuickCheck yields:

```
Main>quickCheck prop_isEmpty
Falsifiable, after 4 tests:
([],[-1])
```

Problem:

- The specification of isEmpty assumes implicitly that the following invariant holds:
 - The front of the list is only empty, if the back of the list is empty, too:

isEmptyI (f,b) = null f



Soundness Properties: Initial Definitions (3)

In fact:

- prop_isEmpty, prop_front, and prop_remove are all falsifiable because of this!
- The implementations of isEmptyI, frontI, and removeI assume implicitly that the front of a queue will only be empty if the back also is.

This silent assumption has to be made explicit in terms of an invariant.

5.2 375/135

Soundness Properties: Refined Definitions (1) We define the invariant as follows: invariant :: QueueI Integer -> Bool invariant (f,b) = not (null f) || null b ...and add them to the relevant property definitions: 5.2 prop_empty = retrieve emptyI == empty prop_add x q = invariant q ==> retrieve (addI x q) == add x (retrieve q) prop_isEmpty q = invariant q ==> isEmptyI q == isEmpty (retrieve q) prop_front q = invariant q ==> frontI q == front (retrieve q) prop_remove q = invariant q ==> retrieve (removeI q) == remove (retrieve q)

Chap. 14 376/135

Soundness Properties: Refined Definitions (2) Now, testing prop_isEmpty using QuickCheck yields: Main>quickCheck prop_isEmpty OK, passed 100 tests 5.2 However, testing prop_front still fails: Main>quickCheck prop_front Program error: front ([],[]) Problem: frontI (as well as removeI) may only be applied to non-empty lists. So far, we did not take care of this.

Chap. 14 377/135

Soundness Properties: Final Definitions Fix:

Add not (isEmptyI q) to the preconditions of the relevant properties.

This leads to:

```
prop_empty = retrieve emptyI == empty
                                                    5.2
prop_add x q = invariant q ==>
        retrieve (addI x q) == add x (retrieve q)
prop_isEmpty q = invariant q ==>
        isEmptyI q == isEmpty (retrieve q)
prop_front q = invariant q && not (isEmptyI q) ==>
        frontI q == front (retrieve q)
prop_remove q = invariant q && not (isEmptyI q) ==>______
        retrieve (removeI q) == remove (retrieve q) Chap.11
```

Now:

All properties pass the test successfully!

378/135

Soundness Considerations Continued

We are not yet done - we still need to check:

 Operations producing queues do only produce queues that satisfy this invariant.

Note:

So far we only tested that

operations on queues behave correctly on representations of queues that satisfy the invariant invariant (f,b) = not (null f) || null b 5.2 379/135

Adding Missing Soundness Properties (1)

Defining properties for operations producing queues:

Adding Missing Soundness Properties (2)

Testing by means of QuickCheck yields:

```
Main>quickCheck prop_inv_add
Falsifiable, after 0 tests:
0
([],[])
```

Problem:

- The invariant must hold
 - not only after applying removel,
 - but also after applying addI to the empty list; adding to the back of a queue breaks the invariant in this case.

5.2 381/135

Soundness Properties: Completed Now!

To overcome the last and final problem:

Adjust the function addI as follows: addI x (f,b) = flipQ (f,x:b) -- instead of: addI x (f,b) = (f,x:b) with flipQ as defined previously.

Now:

All properties pass the test successfully!



Summing up

In the course of developing this example it turned out:

- Testing revealed (only) one bug in the implementation (this was in function addI).
- But: Several missing preconditions and a missing invariant in the original definitions of properties were found and added.

Both is typical and valuable:

- The additional conditions and invariants are now explicitly given in the program text.
- They add to understanding the program and are valuable as documentation, both for the program developer and for future users (think e.g. of program maintainance!).

5.2 383/135

Chapter 5.3 Testing against Algebraic Specifications

5.3 384/135

Algebraic Specifications

Testing against algebraic specifications is (often) a useful alternative to testing against an abstract model.

An algebraic specification

 provides equational constraints the operations ought to satisfy. 5.3 385/135

Algebraic Specifications

For FIFO queues, e.g., we might start with the following algebraic specifications:

prop_isEmpty q = invariant q ==> isEmptyI q == (q == emptyI) prop_front_empty x = frontI (addI x emptyI) == x 5.3 prop_front_add x q = invariant q && not (isEmptyI q) ==> frontI (addI x q) == frontI q prop_remove_empty x = removeI (addI x emptyI) == emptyI prop_remove_add x q = invariant q && not (isEmptyI q) ==> removeI (addI x q) == addI x (removeI q)

> Chap. 14 386/135

Testing Algebraic Specifications (1) Testing prop_remove_add using QuickCheck yields: Main>quickCheck prop_remove_add Falsifiable, after 1 tests: 0 ([1], [0])Problem: The left hand side, i.e., removel (addI x q), yields: ([0.0], [])

- The right hand side, i.e., addI x (removel q), yields: ([0],[0])
- The queue representations ([0,0],[]) and ([0],[0]) are equivalent (representing both the abstract queue [0,0]) but are not equal!

5.3 387/135 Testing Algebraic Specifications (2) Fix: Consider "equivalent" instead of "equal": q 'equiv' q' = invariant q && invariant q' && retrieve q == retrieve q' In fact: Replacing prop_remove_add x q = invariant q && not (isEmptyI q) ==> removeI (addI x q) == addI x (removeI q) by prop_remove_add x q = invariant q && not (isEmptyI q) ==> removeI (addI x q) 'equiv' addI x (removeI q) yields as desired: The test of prop_remove_add passes successfully!

5.3 388/135

Testing Algebraic Specifications (3)

Similar to the setup in Chapter 5.1, we have to check:

 All operations producing queues yield results that are equivalent, if the arguments are.

Example:

For the operation addI this can be expressed by:

5.3 389/135

Summing up

Though mathematically sound, the definition of prop_add_equiv is inappropriate for fully automatic testing.

We might observe:

Main>quickCheck prop_add_equiv Arguments exhausted after 58 tests.

Problem and background:

- QuickCheck generates the lists q und q' randomly.
- Most of the generated pairs of lists will not be equivalent, and hence be discarded for the actual test.
- QuickCheck generates a maximum number of candidate arguments only (default: 1.000), and then stops, possibly before the number of 100 test cases is met.

5.3 390/135

Outlook

Enhancing usability of QuickCheck by adding support for				
 Quantifying over subsets by means of filters by means of generators (type-based, weighted, size controlled,) 				
Test case monitoring				
In the following: Illustrating this support by means of examples! 				

Contents Chap. 1 Chap. 2 Chap. 3 Chap. 4 Chap. 5 5.2 5.2 5.3

Chap. 14 391/135

Chapter 5.4 Quantifying over Subsets

5.4

Chap. 14 392/135

Background and Motivation

For QuickCheck holds:

 By default, parameters are quantified over the values of the underlying type (e.g., all integer lists)

Often, however, it is required:

- A quantification over subsets of these values
 - (e.g., all sorted integer lists)

	4
5.1 5.2	
5.3	
5.4	
5.5	
5.6 5.7	
	6
	7
Chap.	
Chap.	9
Chap.	10
Chap.	11
Chap.	12
Chap.	13
Chap. 393/	14 135

Quantifying over Subsets

QuickCheck offers several means for achieving this:

Representation of subsets in terms of

- Boolean functions that act as a filter for test cases
 - Adequate, if many elements of the underlying set are members of the relevant subset, too.
 - Inadequate, if only a few elements of the underlying set are members of the relevant subset.

generators

- A generator of type Gen a yields a random sequence of values of type a.
- The property forall set p successively checks p on randomly generated elements of set.

5.4 394/135

Support by QuickCheck

For the effective usage of generators QuickCheck supports:

- different variants for the specification of relations such as equiv
 - As a Boolean function
 - easy to check equivalence of two values (but difficult to generate values that are equivalent).
 - As a function from a value to a set of related (e.g., equivalent) values (generator!)
 - easy to generate equivalent values (but difficult to check if two values are equivalent).

The latter option will be considered in more detail in the following chapter.

5.4 395/135

Chapter 5.5 Generating Test Data

5.5

Chap. 14 396/135
Generators

The fundamental function to make a choice:

Note:

- The function choose generates "randomly" an element of the specified domain.
- choose (1,n) represents the set $\{1, \ldots, n\}$.
- ▶ The type Gen is a monad (cp. Chapter 11).

5.5 397/135

Using choose

```
...we can define equivQ:
```

where

- els = retrieve q n = length els
- Generates a random queue that contains the same elements as q.
- The number k of elements in the back of the queue will be chosen such that it is properly smaller than the total number of elements of the queue (under the assumption that the total number is different from 0).

5.5 398/135

Application (1)

This allows us to check that

generated elements are related, i.e., equivalent.

To this end check:

```
prop_EquivQ q = invariant q ==>
forAll (equivQ q) $ \q' -> q 'equiv' q'
```

Note:

- Recall that \$ means function application. Using \$ allows the omission of parentheses (see the λ expression in the example).
- The property which is dual to prop_EquivQ, i.e., that all related elements can be generated, cannot be checked by testing.

5.5 399/135

Application (2)

This allows:

 Reformulating the property that addI maps equivalent queues to equivalent queues

Remark:

Other properties analogously

Next we consider: How to define generators.

5.5 400/135 ... is eased because of the monadic type of Gen.

It holds:

- return a always yields (generates) a and represents the singleton set {a}
- ▶ do {x <- s; e} can be considered the (generated) set {e | x ∈ s}

5.5 401/135

Type-based Generators (1)

...by means of the overloaded generator **arbitrary**, e.g. for the generation of arguments of properties:

Example 1:

prop_max_le x y = x <= x 'max' y</pre>

is equivalent to

prop_max_le = forAll arbitrary \$ \x ->
 forAll arbitrary \$ \y -> x <= x 'max' y</pre>

5.5 402/135

```
Type-based Generators (2)
 Example 2:
 The set \{y \mid y \geq x\} can be generated by
  atLeast x = do diff <- arbitrary
                     return (x + abs diff)
                                                                     5.5
 because of the equality
               \{y \mid y > x\} = \{x + abs \ d \mid d \in \mathbb{Z}\}
```

403/135

that holds for numerical types.

Note: Similar definitions are possible for other types, too.

Selection

...between several generators can be achieved by means of a generator one of that can be thought of as set union.

```
Example: Constructing a sorted list
```

```
orderedLists = do x <- arbitrary
listsFrom x
```

```
where
```

```
listsFrom x
```

= oneof [return [], do y <- atLeast x

```
liftM (x:) (listsFrom y)]
```

Underlying intuition:

A sorted list is either empty or the addition of a new head element to a sorted list of larger elements. 5.5 404/135

Weighted Selection (1)

- The one of combinator picks with equal probability one of the alternatives.
- This often has an unduly impact on the test case generation (in the previous example the empty set will be selected too often).
- Remedy: A weight function frequency that assigns different weights to the alternatives. frequency :: [(Int,Gen a)] -> Gen a

5.5 405/135 Weighted Selection (2)

Application:

- A QuickCheck generator corresponds to a probability distribution over a set, not the set itself.
- The impact of the above assignment of weights is that on average the length of generated lists is 4.

The Type Class Arbitrary

If non-standard generators such as orderedLists are used frequently, it is advisable to make this type an instance of type class Arbitrary:

```
newtype OrderedList a = OL [a]
 instance (Num a, Arbitrary a) =>
                  Arbitrary (OrderedList a) where
   arbitrary = liftM OL orderedLists
Together with the re-definition of insert as
 insert :: Ord a => a -> OrderedList a
                            -> OrderedList a
```

arguments generated for it will automatically be ordered.

5.5 407/135

Controlling the Size of Generated Test Data

- This is usually wise for type-based test data generation
- It is explicitly supported by QuickCheck



```
Controlling the Size of Generated Test Data
 Generators that depend on the size can be defined by:
 sized :: (Int -> Gen a) -> Gen a
              -- For defining size aware gen.
 sized  \ n \rightarrow do \ len <- \ choose (0,n) 
                   vector len -- Application of sized
                               -- in the Def. of the
                               -- default list generator
                                                              5.5
vector n = sequence [arbitrary | i <- [1..n]]
                               -- generates random list
                               -- of length n
resize :: Int -> Gen a -> Gen a
                               -- for controlling the size
                               -- of generated values
 sized  (n \rightarrow resize (round (sqrt (fromInt n))) arbitrary_{hap.13}
                               -- Application of resize
                                                              409/135
```

Generators for User-defined Types

Test data generators for	
	Chap. 4
predefined ("built-in") types of Haskell	
are provided by QuickCheck	5.1 5.2
 for user-defined types, this is not possible 	5.3
F for user-defined types, this is not possible	5.4 5.5
 user-defined types 	5.6
have to be provided by the user in terms of defining a	5.7 Chap. 6
suitable instance of the type class Arbitrary	Chap. 7
•	
require usually, especially in case of recursive types, to	Chap. 8
control the size of generated test data	Chap. 9
č	Chap. 10
	Chap. 11

- Chap. 12
- Chap. 13

Chap. 14 410/135 Example: Binary Trees (1)

Consider type (Tree a):

data Tree a = Leaf | Branch (Tree a) a (Tree a)

The following definition of the test-data generator is obvious:

5.5 411/135

Example: Binary Trees (2)

Note:

- The assignment of weights (1 vs. 3) has been done in order to avoid the generation of all too many trivial trees of size 1.
- Problem: The likelihood that a generator comes up with a finite tree, is only one third.

 \rightsquigarrow this is because termination is possible only, if all subtrees generated are finite. With increasing breadth of the trees, the requirement of always selecting the "terminating" branch has to be satisfied at ever more places simultaneously. 5.5 412/135

Example: Binary Trees (3)

Remedy:

- Usage of the parameter size in order to ensure
 - termination and
 - "reasonable" size
 - of the generated trees.

5.5 413/135

```
Example: Binary Trees (4)
 Implementation:
  instance Arbitrary a => Arbitrary (Tree a) where
   arbitrary = sized arbTree
  arbTree 0 = return Leaf
                                                        5.5
  arbTree n | n>0 =
   frequency [(1, return Leaf),
              (3,liftM3 Branch shrub arbitrary shrub)
    where
     shrub = arbTree (n 'div' 2)
 Note: shrub is a generator for small(er) trees.
```

Example: Binary Trees (5)

Remark:

- shrub is a generator for "small(er)" trees.
- shrub is not bounded to a special tree; the two occurrences of shrub will usually generate different trees.
- Since the size limit for subtrees is halved, the total size is bounded by the parameter size.
- Defining generators for recursive types must usually be handled specifically as in this example.

5.5 415/135

Chapter 5.6 Monitoring, Reporting, and Coverage

5.6

Test-Data Monitoring

In practice, it is useful

- to monitor the generated test cases in order to obtain a hint on the quality and the coverage of test cases
- of a QuickCheck run.

For this purpose QuickCheck provides

► an array of monitoring and reporting possibilities.

Usefulness of Test-Data Monitoring

Why is test-data monitoring meaningful?

Reconsider the example of inserting into a sorted list:

```
5.6
418/135
```

Test-Data Monitoring and Test Coverage

QuickCheck performs the check of prop_InsertOrdered such that:

- lists are generated randomly
- each generated list will be checked, if it is sorted (used test case) or not (discarded test case)

Obviously, it holds:

the likelihood that a randomly generated list is sorted is the higher the shorter the list is

This introduces the danger that

- the property prop_InsertOrdered is mostly tested with lists of length one or two
- even a successful test is not meaningful

56

Test-Data Monitoring using trivial (1) For monitoring purposes QuickCheck provides a combinator trivial, where the meaning of "trivial" is user-definable. Example: prop_InsertOrdered :: Integer -> [Integer] -> Property prop_InsertOrdered x xs = ordered xs ==> trivial (length xs <= 2) \$ ordered (insert x xs) with Main>quickCheck prop_InsertOrdered

OK, passed 100 tests (91% trivial)

Test-Data Monitoring using trivial (2)

Observation:

- 91% are too many trivial test cases in order to ensure that the total test is meaningful
- The operator ==> should be used with care in test-case generators

Remedy:

► User-defined generators ~> as in the example of prop_InsertOrdered in Chapter 5.1 ("Second Fix (systematic)").

Test-Data Monitoring using classify (1)

The combinator trivial is

instance of a more general combinator classify
trivial p = classify p "trivial"

5.6

Test-Data Monitoring using classify (2)

Multiple applications of classify allow an even more refined test-case monitoring:

prop_InsertOrdered x xs = ordered xs =>
 classify (null xs) "empty lists" \$
 classify (length xs == 1) "unit lists" \$
 ordered (insert x xs)

This yields:

Main>quickCheck prop_InsertOrdered
OK, passed 100 tests.
42% unit lists.
40% empty lists.

Test-Data Monitoring using collect

Going beyond, the combinator collect allows us to keep track on all test cases:

prop_InsertOrdered x xs = ordered xs =>
 collect (length xs) \$ ordered (insert x xs)

This yields a histogram of values:

Main>quickCheck prop_InsertOrdered OK, passed 100 tests. 46% 0. 34% 1. 15% 2. 5% 3.

Chapter 5.7 Implementation of QuickCheck

5.7

Chap. 14 425/135

```
On the Implementation of QuickCheck (1)
A Glimpse into the implementation:
 class Testable a where
   property :: a -> Property
 newtype Property = Prop (Gen Result)
 instance Testable Bool where
   property b = Prop (return (resultBool b))
                                                       57
 instance (Arbitrary a, Show a, Testable b) =>
                            Testable (a->b) where
   property f = forAll arbitrary f
 instance Testable Property where
   property p = p
 quickCheck :: Testable a => a -> IO ()
```

On the Implementation of QuickCheck (2)

QuickCheck

- consists in total of about 300 lines of code.
- has initially been presented by Koen Claessen and John Hughes:

Koen Claessen, John Hughes. QuickCheck: A Lightweight Tool for Random Testing of Haskell Programs. In Proceedings of the 5th ACM SIGPLAN International Conference on Functional Programming (ICFP 2000), 268-279, 2000.

Summing up (1)

In general, it holds:

 Formalizing specifications is meaningful (even without a subsequent formal proof of soundness).

Experience shows:

 Specifications provided are often (initially) faulty themselves.

Summing up (2)

Out alt Chapter is an officiative tool	
QuickCheck is an effective tool	
to disclose bugs in	
 programs and specifications with little effort. 	Chap. 1 5.1 5.2 5.3 5.4 5.5 5.6 5.7
► to reduce	Chap. 6
► test costs	
while simultaneously	Chap. 8 Chap. 9
 testing more thoroughly. 	Chap. 1
	Chap. 1

Chap. 12

Chap. 13

Summing up (3)

Investigations of Richard Hamlet

 Richard Hamlet. Random Testing. In J. Marciniak (Ed.), Encyclopedia of Software Engineering, Wiley, 970-978, 1994

indicate that

a high number of test cases yields meaningful results even in the case of random testing.

Moreover

The generation of random test cases is often "cheap."

Hence, there are many reasons advising

the routine usage of a tool like QuickCheck!

Summing up (4)

Besides QuickCheck there are various other combinator libraries supporting the lightweight testing of Haskell programs, e.g.:

- EasyCheck
- SmallCheck
- Lazy SmallCheck
- ► Hat

Summing up (5)

The presentation of this chapter is closely based on:

 Koen Claessen, John Hughes. Specification-based Testing with QuickCheck. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 17-39, 2003.

For implementation details and applications refer to:

- Koen Claessen, John Hughes. QuickCheck: A Lightweight Tool for Random Testing of Haskell Programs. In Proceedings of the 5th ACM SIGPLAN International Conference on Functional Programming (ICFP 2000), 268-279, 2000.
- Koen Claessen, John Hughes. Testing Monadic Code with QuickCheck. In Proceedings of the ACM SIGPLAN 2002 Haskell Workshop (Haskell 2002), 65-77, 2002.


Chapter 5: Further Reading (1)

- Marco Block-Berlitz, Adrian Neumann. *Haskell Intensivkurs*. Springer-V., 2011. (Kapitel 18.2, QuickCheck)
- Koen Claessen, John Hughes. QuickCheck: A Lightweight Tool for Random Testing of Haskell Programs. In Proceedings of the 5th ACM SIGPLAN International Conference on Functional Programming (ICFP 2000), 268-279, 2000.
- Koen Claessen, John Hughes. Testing Monadic Code with QuickCheck. In Proceedings of the ACM SIGPLAN 2002 Haskell Workshop (Haskell 2002), 65-77, 2002.
- Koen Claessen, John Hughes. Specification-based Testing with QuickCheck. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 17-39, 2003.

5.7 433/135

Chapter 5: Further Reading (2)

- Koen Claessen, Colin Runciman, Olaf Chitil, John Hughes, Malcolm Wallace. Testing and Tracing Lazy Functional Programs Using QuickCheck and Hat. In Johan Jeuring, Simon Peyton Jones (Eds.) Advanced Functional Programming – Revised Lectures. Springer-V., LNCS Tutorial 2638, 59-99, 2003.
- Jan Christiansen, Sebastian Fischer. Easycheck Test Data for Free. In Proceedings of the 9th International Symposium on Functional and Logic Programming (SFLP 2008), Springer-V., LNCS 4989, 322-336, 2008.

5.7 434/135

Chapter 5: Further Reading (3)

- Colin Runciman, Matthew Naylor, Fredrik Lindblad. Small-Check and Lazy SmallCheck. In Proceedings of the ACM SIGPLAN 2008 Haskell Workshop (Haskell 2008), 37-48, 2008. (Available from http://hackage.haskell.org)
- Bryan O'Sullivan, John Goerzen, Don Stewart. Real World Haskell. O'Reilly, 2008. (Chapter 11, Testing and Quality Assurance; Chapter 26, Advanced Library Design: Building a Bloom Filter – Testing with QuickCheck)
- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 19.6, DSLs for computation: generating data in QuickCheck)

5.7 435/135

	Chap. 4
Chapter 6	Chap. 5 Chap. 6
	6.1
Verification	$\begin{array}{c} 6.2\\ 6.2.1\\ 6.2.2\\ 6.2.3\\ 6.3\\ 6.3.1\\ 6.3.2\\ 6.3.3\\ 6.3.4\\ 6.3.5\\ 6.4\\ 6.5\\ 6.6\\ 6.7\end{array}$
	Chap. 7
	Chap. 8
	Chap. 9
	436/135

Though often amazingly effective, testing is limited to	Chap. 4
 showing the presence of errors. 	Chap. 6
It can not show their absence!	6.1 6.2
	6.2.1 6.2.2
	6.2.3
By contrast, verification is able to	6.3 6.3.1
	6.3.2 6.3.3
proving the absence of errors!	6.3.4
	6.3.5 6.4
	6.5
	6.6 6.7
	Chap. 7
	Chap. 8
	Chap. 9

In this chapter

we will consider important proof	f techniques	for verifying
properties of functional (and other	r) programs	that may
operate on		

elementary data such as

- ► integers
- strings
- ▶ ...
- composed data (in Haskell: algebraic data types) such as
 - ► trees
 - lists (which are finite by definition)
 - streams (which are infinite by definition)
 - ► ...

Outline of the Proof Techniques

We already considered	(cf.	Chapter	4):
-----------------------	------	---------	-----

 Equational reasoning 	
We will consider in this chapter:	
 Basic inductive proof principles 	

- Natural (or mathematical) induction
- Strong induction
- Structural induction
- Specialized inductive proof principles
 - Induction on lists
 - Induction on streams
- Coinduction
- Fixed point induction

Chap. 6

Before going into details (1)

... it is worth noting:

Though of different power, testing and verification are both instances of approaches that aim at

• ensuring the correctness of a program or system.

Chap. 4	
Chap. 6	
6.1	
6.2	
6.2.1 6.2.2	
6.2.2	
6.2.3	
6.3	
6.3.1	
6.3.2	
6.3.3	
6.3.4	
6.3.5	
6.4	
6.5	
6.6 6.7	
0.7	
Chap. 7	
Chap. 8	
Chap. 9	
440/13	2

Before going into details (2)

Conceptually, we can distinguish between approaches that strive for ensuring correctness by

► Construction

 \rightsquigarrow applied a priori/on-the-fly of the program development

Checking

 \rightsquigarrow applied a posteriori of the program development

- Verification
- Testing (only to a limited extent if not exhaustive)

Chap. 6 441/135

Before going into details (3)

With this in mind, we may loosely conclude:

► Correctness by Construction

Equational Reasoning

- Correctness by Checking
 - Verification
 - Testing

	4
Chap.	6
6.1	
6.2	
6.2.1	
6.2.2	
6.2.3	
6.3	
6.3.1	
6.3.2	
6.3.3	
6.3.4	
6.3.5	
6.4	
6.5	
6.6	
6.7	
Chap.	7
Chap.	8
Chap.	9
442/	13

Chapter 6.1 Equational Reasoning – Correctness by Construction

6.1

Equational Reasoning

is sometimes also called	
, woof he warmen coloulation	
 proof by program calculation. 	6.1 6.2
	6.2.1 6.2.2
It has been considered and demonstrated previously. Consider	6.2.3 6.3
	6.3.1
Chapter 4 for details.	6.3.2 6.3.3
	6.3.4 6.3.5
	6.4
	6.5

Chapter 6.1: Further Reading (1)

- Roderick Chapman. Correctness by Construction: A Manifesto for High Integrity Software. In Proceedings of the 10th Australian Workshop on Safety Critical Systems and Software, Vol. 55, 43-46, 2006.
- Henning Dierks, Michael Schenke. A Unifying Framework for Correct Program Construction. In Proceedings of the 4th International Conference on the Mathematics of Program Construction (MPC'98). Springer-V., LNCS 1422, 122-150, 1998.
- Anthony Hall, Roderick Chapman. Correctness by Construction: Developing a Commercial Secure System. IEEE Software 19(1):18-25, 2002.

6.1 445/135

Chapter 6.1: Further Reading (2)

- Charles A.R. Hoare. The Ideal of Program Correctness. The Computer Journal 50(3):254-260, 2007.
- Derrick G. Kourie, Bruce W. Watson. The Correctnessby-Construction Approach to Programming. Springer-V., 2012.

6.1

Chapter 6.2 Basic Inductive Proof Principles

6.2 447/135 Basic inductive proof principles are:

- Natural or mathematical induction (dtsch. vollständige Induktion)
- Strong induction (dtsch. verallgemeinerte Induktion)
- Structural induction (dtsch. strukturelle Induktion)

6.2 448/135

Basic Inductive Proof Principles

Let *P* be a property; let *S* be a set of values *s* that are (inductively) constructed from a set of (structurally simpler) values subs(s); let IN denote the set of natural numbers.

The principles of

Natural (mathematical) induction

$$(P(1) \land (\forall n \in \mathbb{N}. P(n) \Rightarrow P(n+1))) \Rightarrow \forall n \in \mathbb{N}. P(n+1)$$

Strong induction

$$(\forall n \in \mathbb{N}. (\forall m < n. P(m)) \Rightarrow P(n)) \Rightarrow \forall n \in \mathbb{N}. P(n)$$

Structural induction

 $(\forall s \in S. \forall s' \in subs(s). P(s')) \Rightarrow P(s)) \Rightarrow \forall s \in S. P(s)$

6.2

Note

The proof principles of	Chap. 4
 natural (mathematical) 	Chap. 6 6.1
	6.2
► strong	6.2.1 6.2.2
► structural	6.2.3 6.3
- Structural	6.3.1 6.3.2
induction are equally expressive and powerful.	6.3.3
induction are equally expressive and powerful.	6.3.4 6.3.5
	6.4
	6.5 6.6
	6.7
	Chap. 7
	Chap. 8
	Chap. 9
	450/135

Next we provide some typical examples illustrating the usage of these three basic inductive principles of

natural	(mathematical)

- strong
- structural

induction.

6.2 451/135

	Chap. 4
Chapter 6.2.1	Chap. 6
	6.1 6.2
Natural Induction	6.2.1 6.2.2
	6.2.3 6.3
	0.3 6.3.1
	6.3.2
	6.3.3
	6.3.4 6.3.5
	6.4
	6.5
	6.6
	6.7
	Chap. 7
	Chap. 8
	Chap. 9
	452/135

Example A

Theorem (6.2.1.1)
$$\forall n \in IN. \ \sum_{i=1}^{n} i = \frac{n * (n+1)}{2}$$

Proof: By means of natural (mathematical) induction.

6.2.1 453/135

Proof of Theorem 6.2.1.1(1)

Base case: n = 1. In this case we obtain the desired equality by a straightforward calculation:

$$\sum_{i=1}^{n} i = \sum_{i=1}^{1} i$$

= 1
= $\frac{2}{2}$
= $\frac{1*2}{2}$
= $\frac{1*(1+1)}{2} = \frac{n*(n+1)}{2}$

6.2.1 454/135

Proof of Theorem 6.2.1.1(2)

Inductive case: Applying the induction hypothesis (IH) once, we obtain as desired:

$$\sum_{i=1}^{n+1} i = (n+1) + \sum_{i=1}^{n} i$$

(IH) = $(n+1) + \frac{n*(n+1)}{2}$
= $(n+1)*(\frac{n}{2}+1)$
= $\frac{(n+1)*(n+2)}{2} = \frac{(n+1)*((n+1)+1)}{2}$

6.2.1 455/135

Example B

Theorem (6.2.1.2)
$$\forall n \in IN. \sum_{i=1}^{n} (2 * i - 1) = n^2$$

Proof: By means of natural (mathematical) induction.

6.2.1 456/135

Proof of Theorem 6.2.1.2(1)

Base case: n = 1. In this case we obtain the desired equality by a straightforward calculation:

$$\sum_{i=1}^{n} (2 * i - 1) = \sum_{i=1}^{1} (2 * i - 1)$$

$$= 2 * 1 - 1 \\ = 2 - 1$$

$$= 1$$

 $= 1^{2} = n^{2}$

6.2.1

chap. 0

Chap. 9

Proof of Theorem 6.2.1.2 (2)

Inductive case: Applying the induction hypothesis (IH) once, we obtain as desired:

$$\sum_{i=1}^{n+1} (2 * i - 1) = 2 * (n + 1) - 1 + \sum_{i=1}^{n} (2 * i - 1)$$

(IH) = $(2 * (n + 1) - 1) + n^2$
= $2n + 2 - 1 + n^2$
= $2n + 1 + n^2$
= $n^2 + 2n + 1$
= $n^2 + n + n + 1$
= $(n + 1) * (n + 1) = (n + 1)^2$

Contents

5.3 6.3.1 6.3.2 6.3.3 6.3.4 6.3.5 5.4 5.5 5.6 5.7 7 7 hap. 7 7 hap. 8 thap. 9

458/135

6.2.1

	Chap. 4
Chapter 6.2.2	
	Chap. 6 6.1
	6.2 6.2.1
Strong Induction	6.2.2 6.2.3
	6.3
	6.3.1 6.3.2
	6.3.3
	6.3.4 6.3.5
	6.4
	6.5 6.6
	6.7
	Chap. 7
	Chap. 8
	Chap. 9
	459/135

Fibonacci Function

The Fibonacci function is defined by:

 $\textit{fib}: IN_0 \to IN_0$

$$fib(n) =_{df} \begin{cases} 0 & \text{if } n = 0\\ 1 & \text{if } n = 1\\ fib(n-1) + fib(n-2) & \text{otherwise} \end{cases}$$

6.2.2 460/135

Example

-

Theorem (6.2.2.1)

$$\forall n \in IN_0. \ fib(n) = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^n - \left(\frac{1-\sqrt{5}}{2}\right)^n}{\sqrt{5}}$$

Proof: By means of strong induction.

6.2.2 461/135

Key Idea for proving Theorem 6.2.2.1

Using the induction hypothesis (IH) that for all k < n, $n \in \mathbb{N}_0$, the equality

$$fib(k) = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^k - \left(\frac{1-\sqrt{5}}{2}\right)^k}{\sqrt{5}}$$

holds, we can prove the premise underlying the implication of the principle of strong induction for all natural numbers n by investigating the following basic and inductive cases.

Proof of Theorem 6.2.2.1 (2)

Base case 1: n = 0. In this case, a straightforward calculation yields the desired equality:

$$fib(0) = 0 = \frac{0}{\sqrt{5}} = \frac{1-1}{\sqrt{5}} = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^0 - \left(\frac{1-\sqrt{5}}{2}\right)^0}{\sqrt{5}}$$

Base case 2: n = 1. Again, a straightforward calculation yields as desired:

$$fib(1) = 1 = \frac{\sqrt{5}}{\sqrt{5}} = \frac{\frac{1}{2} + \frac{\sqrt{5}}{2} - (\frac{1}{2} - \frac{\sqrt{5}}{2})}{\sqrt{5}} = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^1 - \left(\frac{1-\sqrt{5}}{2}\right)^1}{\sqrt{5}}$$

6.2.2 463/135

Proof of Theorem 6.2.2.1 (3)

Inductive case: $n \ge 2$. Applying the IH for n-2, n-1 yields as desired:

$$fib(n) = fib(n - 2) + fib(n - 1)$$

$$fib(n) = fib(n - 2) + fib(n - 1)$$

$$(hap. 1)$$

$$2x IH) = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n-2} - \left(\frac{1-\sqrt{5}}{2}\right)^{n-2}}{\sqrt{5}} + \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n-1} - \left(\frac{1-\sqrt{5}}{2}\right)^{n-1}}{\sqrt{5}}$$

$$= \frac{\left[\left(\frac{1+\sqrt{5}}{2}\right)^{n-2} + \left(\frac{1+\sqrt{5}}{2}\right)^{n-1}\right] - \left[\left(\frac{1-\sqrt{5}}{2}\right)^{n-2} + \left(\frac{1-\sqrt{5}}{2}\right)^{n-1}\right]}{\sqrt{5}}$$

$$= \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n-2} \left[1 + \frac{1+\sqrt{5}}{2}\right] - \left(\frac{1-\sqrt{5}}{2}\right)^{n-2} \left[1 + \frac{1-\sqrt{5}}{2}\right]}{\sqrt{5}}$$

$$(*) = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n-2} \left(\frac{1+\sqrt{5}}{2}\right)^{2} - \left(\frac{1-\sqrt{5}}{2}\right)^{n-2} \left(\frac{1-\sqrt{5}}{2}\right)^{2}}{\sqrt{5}}$$

$$= \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n-2} \left(\frac{1+\sqrt{5}}{2}\right)^{2} - \left(\frac{1-\sqrt{5}}{2}\right)^{n-2} \left(\frac{1-\sqrt{5}}{2}\right)^{2}}{\sqrt{5}}$$

$$= \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n} - \left(\frac{1-\sqrt{5}}{2}\right)^{n}}{\sqrt{5}}$$

$$(*) = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{n} - \left(\frac{1-\sqrt{5}}{2}\right)^{n}}{\sqrt{5}}$$

Proof of Theorem 6.2.2.1 (4)

The equality marked by (*) follows from the below two calculations that make use of the binomial formulae.

We have:

$$\left(\frac{1+\sqrt{5}}{2}\right)^2 = \frac{1+2\sqrt{5}+5}{4} = \frac{6+2\sqrt{5}}{4} = \frac{3+\sqrt{5}}{2} = 1 + \frac{1+\sqrt{5}}{2}$$

Similarly we get:

$$\left(\frac{1-\sqrt{5}}{2}\right)^2 = \frac{1-2\sqrt{5}+5}{4} = \frac{6-2\sqrt{5}}{4} = \frac{3-\sqrt{5}}{2} = 1 + \frac{1-\sqrt{5}}{2}$$

6.3.1 6.3.2 6.3.3 6.3.4 6.5 6.5 6.6 6.7 Chap. 7 Chap. 8 Chap. 9 465/135

6.2.2

Excursus: Which Rectangle looks 'nicest'?



Most People say 'Rectangle 3'!

Contents

6.2.2

Rectangle 3

Why?




Intuitively:

The ratio of section A and section B is the same as the ratio of section B and section C

$$A/B = B/C$$

The value of this ratio is denoted by ϕ .

6.6 6.7 Chap. 7 Chap. 8 Chap. 9 **469/135**

The Golden Ratio

... is perceived as harmonious:



470/135

6.2.2

What is the value of ϕ ?



The Golden Ratio

...not only in terms of the ratios of sections but also in terms of the ratios of the areas of e.g. rectangles:

 $1 \text{ UoL} \qquad (\phi - 1) \text{ UoL}$ $1 \text{ UoL} \qquad 1^2 \text{ UoL}^2 = 1 \text{ UoL}^2 \qquad 1^*(\phi - 1) \text{ UoL}^2 = (\phi - 1) \text{ UoL}^2$

6.2.2

The Golden Ratio and Fibonacci Numbers (1)

The Golden Ratio, rectangles and the Fibonacci numbers:



6.2.2 473/135

The Golden Ratio and Fibonacci Numbers (2) The sequence of Fibonacci numbers: 0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144, 233, 377, ... The sequence of the ratios of the Fibonacci numbers: 1/1 = 12/1 = 23/2 = 1.56.2.2 $5/3 = 1.\overline{6}$ 8/5 = 1.613/8 = 1.62521/13 = 1.61538461538461534/21 = 1.619047619047619. . . 1,346,269/832,040 = 1.618033988750541474/135

The Golden Ratio and Fibonacci Numbers (3)

...as the limit of the ratios of the Fibonacci numbers.

We have:

$$\lim_{n\to\infty}\frac{fib(n+1)}{fib(n)}=\frac{1+\sqrt{5}}{2}=\phi$$

	Chap. 4
Chapter 6.2.3	Chap. 6
	6.1 6.2
Company of the department	6.2.1
Structural Induction	6.2.2 6.2.3
	6.3
	6.3.1 6.3.2
	6.3.3
	6.3.4
	6.3.5 6.4
	6.5
	6.6
	6.7
	Chap. 7
	Chap. 8
	Chap. 9
	476/135

Arithmetic Expressions

The set \mathcal{AE} of (simple) arithmetic expressions is defined by the BNF rule:

$$e ::= n | v | (e_1 + e_2) | (e_1 - e_2) | (e_1 * e_2) | (e_1 / e_2)$$

where n and v stand for an (integer) numeral and variable, respectively.

6.2.3 477/135

Example A

Theorem (6.2.3.1) Let $e \in A\mathcal{E}$, let $|p_e|$ and rp_e denote the number of left and right parentheses of e. Then we have:

$$lp_e = rp_e$$

Proof: By means of structural induction.

6.2.3 478/135

Proof of Theorem 6.2.3.1(1)

Base case 1: Let $e \equiv n$, n a numeral.

In this case *e* does not contain any parentheses. This means $lp_e = 0 = rp_e$ which yields the desired equality of lp_e and rp_e .

Base case 2: Let $e \equiv v$, v a variable.

As above, we conclude $lp_e = 0 = rp_e$ obtaining the desired equality of lp_e and rp_e also in this case.

Proof of Theorem 6.2.3.1(2)

Inductive case: Let $e_1, e_2 \in \mathcal{AE}$, let $\circ \in \{+, -, *, /\}$, and let $e \equiv (e_1 \circ e_2)$.

By means of the induction hypothesis (IH) we can assume $lp_{e_1} = rp_{e_1}$ and $lp_{e_2} = rp_{e_2}$. This allows us to prove the desired equality of lp_e and rp_e thereby completing the proof as follows:

6.2.3 480/135

Example B

Theorem (6.2.3.2) Let $e \in A\mathcal{E}$, let p_e and op_e denote the number of parentheses and of operators of e, respectively. Then we have:

$$p_e = 2 * op_e$$

Proof: By means of structural induction.

6.2.3 481/135

Proof of Theorem 6.2.3.2(1)

Base case 1: Let $e \equiv n$, n a numeral.

In this case *e* does not contain any parentheses or operators. This means $p_e = 0 = op_e$, which yields as desired

 $p_e = 0 = 2 * 0 = 2 * op_e$

Base case 2: Let $e \equiv v$, v a variable.

As above, we conclude $p_e = 0 = op_e$ obtaining the desired equality

 $p_e = 0 = 2 * 0 = 2 * op_e$

in this case, too.

Proof of Theorem 6.2.3.2 (2)

Inductive case: Let $e_1, e_2 \in \mathcal{AE}$, let $\circ \in \{+, -, *, /\}$, and let $e \equiv (e_1 \circ e_2)$.

By means of the induction hypothesis (IH) we can assume that $p_{e_1} = 2 * op_{e_1}$ and $p_{e_2} = 2 * op_{e_2}$. With these equalities we obtain as desired:

n

Example C

Theorem (6.2.3.3)

Let $e \in AE$ be an arithmetic expression of depth n, let opd_e denote the number of of operands of e. Then we have:

$$opd_e \leq 2^n$$

Proof: By means of structural induction.

6.2.3 484/135

Proof of Theorem 6.2.3.3(1)

Base case 1: Let $e \equiv n$, n a numeral.

In this case e has depth 0 and contains 1 operand. This yields as desired:

$$opd_e = opd_n = 1 = 2^0 \leq 2^0$$

Base case 2: Let $e \equiv v$, v a variable.

As in the previous case e has depth 0 and contains 1 operand. Again we obtain as desired:

$$opd_e = opd_v = 1 = 2^0 \leq 2^0$$

Proof of Theorem 6.2.3.3 (2)

Inductive case: Let $e_1, e_2 \in \mathcal{AE}$ be arithmetic expressions of depth *n* and *m*, respectively. Without losing generality let $m \leq n$. Let $\circ \in \{+, -, *, /\}$, and let $e \equiv (e_1 \circ e_2)$.

In this case expression *e* has depth n + 1. By means of the induction hypothesis (IH) we can assume $opd_{e_1} \leq 2^n$ and $opd_{e_2} \leq 2^m$. Using these inequalities the proof can be completed as follows:

0	р	d	e

$(e \equiv (e_1 \circ e_2))$	=	$opd_{(e_1 \circ e_2)}$
	=	$opd_{e_1} + opd_{e_2}$
(2x IH)	\leq	$2^{n} + 2^{m}$
$(m \le n)$	\leq	$2^{n} + 2^{n}$
	=	2 * 2 ⁿ
	=	2 ^{<i>n</i>+1}

Chapter 6.3 Inductive Proofs on Algebraic Data Types

6.3 487/135

Chapter 6.3.1 Induction and Recursion

6.3.1 488/135

Induction and Recursion

... are closely related.

Intuitively:

- Induction describes things starting from something very simple, and building up from there: It is a bottom-up principle.
- Recursion starts from the whole thing, working backward to the simple case(s): It is a top-down principle.

Thus:

Induction (bottom-up) and recursion (top-down) can be considered the two sides of the same coin.

In fact

The preferred usage of

 induction over recursion in some contexts (e.g., defining data structures) resp. vice versa in others (e.g., defining algorithms) is often mostly due to historical reasons.

Data types:

data Tree = Leaf Integer | Node Tree Tree

Algorithms:

fac :: Integer \rightarrow Integer fac n = if n == 0 then 1 else n * fac (n-1) 631

Examples

- Inductive definition of (simple) arithmetic expressions:
 - (r1) Each numeral n and variable v is an (elementary) arithmetic expression.
 - (r2) If e_1 and e_2 are arithmetic expressions, then also $(e_1 + e_2)$, $(e_1 e_2)$, $(e_1 * e_2)$, and (e_1/e_2) .
 - (r3) Every arithmetic expression is inductively constructed by means of rules (r1) and (r2).
- Recursive definition of merge sort:

A list of integers *I* is sorted by the following 3 steps:

- (ms1) Split *I* into two sublists l_1 and l_2 .
- (ms2) Sort the sublists l₁ and l₂ recursively obtaining the sorted sublists sl₁ and sl₂.
- (ms3) Merge the sorted sublists *sl*₁ and *sl*₂ into the sorted list *sl* of *l*.

Summing up

- Definitions of data structures follow often an inductive definition pattern, e.g.:
 - A list is either empty or a pair consisting of an element and another list.
 - A tree is either empty or consists of a node and a set of subtrees.
 - An arithmetic expression is either a numeral or a variable, or is composed of (two) arithmetic expressions by means of a (binary) arithmetic operator.
- Algorithms (functions) on data structures follow often a recursive definition pattern, e.g.:
 - The function length computing the length of a list.
 - The function depth computing the depth of a tree.
 - The function evaluate computing the value of an arithmetic expression (given a valuation of its variables).

Chapter 6.3.2 Inductive Proofs on Trees

493/135

6.3.2

Inductive Proofs on Trees

Let

Theorem (6.3.2.1)

Let t be a value, i.e., a tree, of type Tree of depth n, let leaves(t) denote the number of leafs of t. Then we have:

$$leaves(t) \leq 2^n$$

Proof: By means of structural induction.

6.3.2 494/135

Proof of Theorem 6.3.2.1 (1)

Base case: Let $t \equiv \text{Leaf } k$ for some integer k.

In this case t has depth 0 and contains 1 leaf. This yields as desired:

$$\texttt{leaves(t)} = \texttt{leaves(Leaf k)} = 1 = 2^0 \le 2^0$$

6.3.2 495/135

Proof of Theorem 6.3.2.1 (2)

Inductive case: Let t1 and t2 be two values of type Tree of depth n and m, respectively. Without losing generality let $m \le n$, and let t \equiv Node t1 t2.

In this case t is a tree of depth n + 1. By means of the inductive hypothesis (IH) we can assume leaves(t1) $\leq 2^n$ and leaves(t2) $\leq 2^m$. Using these inequalities the proof can be completed as follows:

leaves(t)

 $(t \equiv \text{Node t1 t2}) = \text{leaves}(\text{Node t1 t2})$ = leaves(t1) + leaves(t2) $(2x \text{ IH}) \leq 2^{n} + 2^{m}$ $(m \leq n) \leq 2^{n} + 2^{n}$ $= 2 * 2^{n}$ $= 2^{n+1}$

Chapter 6.3.3 Inductive Proofs on Lists

Chap. 7 Chap. 8 Chap. 9 ^C497/135

6.3.3

Preliminaries

Reca	all:					
•	А	list	is	by	definition	finite.

Given a list, it is called

- partial, if it is built from the undefined list
- defined, if it is not partial and all its elements are defined

Note:

- For inductively proving properties on lists we have to distinguish the two cases of
 - defined lists (cf. Chapter 6.3.3)
 - partial lists with possibly undefined lists (cf. Chapter 6.3.4)

6.3.3 498/135 Inductive Proofs on Defined Lists

The inductive proof pattern for defined lists:

- Let P be a property on lists.
 - Base case: Prove that P is true for the empty list, i.e. prove P([]).
 - 2. Inductive case: Assuming that P(xs) is true (induction hypothesis), prove that P(x : xs) is true (induction step).

Note:

- The above pattern is an instance of the more general pattern of structural induction.
- A property P proved using this pattern is true for lists with only defined elements of any finite length.

6.3.3 499/135 Example A: Induction on Lists (1)

Let

length :: [a] -> Int
length [] = 0
length (_:xs) = 1 + length xs

Lemma (6.3.3.1)

For all defined lists xs, ys holds:

length (xs ++ys) = length xs + length ys

Proof by induction on the structure of *xs*.

6.3.3 500/135

Example A:	Induction on Lists (2)			
Base case:				
	$length([] + y_s)$			
	icingtri([] + + ys)			
	= length ys			
= 0 + length ys				
	0,			
	= length [] + length ys			
		6.1		
the second second		6.2 6.2.1		
Inductive case:		6.2.1 6.2.2		
		6.2.3		
	length((x : xs) + +ys)	6.3 6.3.1		
		6.3.2		
	= length (x : (xs + +ys))	6.3.3		
	= 1 + length(xs + +ys)	6.3.4 6.3.5		
	= 1 + length (xs ++ys)	6.4		
(IH)	= 1 + (length xs + length ys)	6.5 6.6		
(11)	= 1 + (length xs + length ys)	6.7		
	= (1 + length xs) + length ys	Chap. 7		
	= length (x : xs) + length ys	Chap. 8		
		Chap. 9		

Example B: Induction on Lists (1)

Let

listSum :: Num a => [a] -> a
listSum [] = 0
listSum (x:xs) = x + listSum xs

Lemma (6.3.3.2)

For all defined lists xs holds:

$$listSum xs = foldr (+) 0 xs$$

Proof by induction on the structure of xs.

6.3.3 502/135

Example B: Induction on Lists (2) Base case: listSum [] 0 = = foldr (+) 0 [] Inductive case: listSum(x:xs)6.3.3 = x + listSum xs(IH) = x + foldr (+) 0 xs= foldr (+) 0 (x : xs)

Example C: Induction on Lists w/ map (1)

Properties of map that can be proved by induction on lists.

map (f.g) = map f . map g
map f.tail = tail . map f
map f . reverse = reverse . map f
map f . concat = concat . map (map f)
map f (xs++ys) = map f xs ++ map f ys

map $(\langle x \rightarrow x \rangle) = \langle y \rightarrow y \rangle$ Note: $\langle x \rightarrow x :: a \rightarrow a \rangle$ $\langle y \rightarrow y :: [a] \rightarrow [a]$ 6.3.3
Example C: Induction on Lists w/ map (2)

	Chap. 4
Lemma (6.3.3.3)	
If f is strict, it is true:	Chap. 6 6.1
	6.2
f . head = head . map f	6.2.1 6.2.2
1 · noud noud · map 1	6.2.3 6.3
Dreaf by induction on the structure of lists	6.3.1 6.3.2
Proof by induction on the structure of lists.	6.3.3 6.3.4
	6.3.5 6.4
	6.5
	6.6 6.7
	Chap. 7
	Chap. 8
	Chap. 9
	505/135

Example C: Induction on Lists w/ map (3)	
Base case: (f . head) []	Contents
(Def. of ".") = f(head[])	Chap. 1
(f + f + f) = f + f	Chap. 2 Chap. 3
	Chap. 3
$(f \text{ strict}) = \bot$	Chap. 5
= head []	Chap. 6
(Def. of map) = head (map f [])	6.1 6.2 6.2.1
$(\text{Def. of "."}) = (head \cdot map f)$	6.2.2 6.2.3
Inductive case: $f \cdot head(x : xs)$	6.3 6.3.1 6.3.2 6.3.3
(Def. of ".") = f (head (x : xs))	6.3.4 6.3.5
= f x	6.4 6.5
= head (f x : map f xs)	6.6 6.7 Chap. 7
(Def. of map) = head (map f (x : xs))	Chap. 8
(Def. of ".") = (head . map f) $(x : xs)$	Chap. 9
	506/135

Example D: Induction on Lists w/ fold

Properties of fold that can be proved by induction on lists.

- If op is associative with e 'op' x = x and x 'op' e =
 x for all x, then for all finite xs
 foldr op e xs = foldl op e xs
 is true.
- If x 'op1' (y 'op2' z) = (x 'op1' y) 'op2' z
 and x 'op1' e = e 'op2' x, then for all finite xs
 foldr op1 e xs = foldl op2 e xs
 is true.
- For all finite xs foldr op e xs = foldl (flip op) e (reverse xs) is true.

6.3.3 507/135

Example D: Induction on Lists w/ (++)

Properties of (++) that can be proved by induction on lists.

For all xs, ys, and zs it is true:

(xs++ys) ++ zs = xs ++ (ys++zs) (Associativity of (++))

 Example E: Induction on Lists w/ take/drop

Properties of take and drop that can be proved by induction on lists.

• For all m, n with $m, n \ge 0$ and finite xs it is true:

tal	ke n	X	3 ++	drop	n	xs	=	XS				
tal	ke m		take	n			=	take	(m	in	m n))
dr	op m	•	drop	n			=	drop	(m·	+n))	
tal	ke m		drop	n			=	drop	n	. 1	take	(m+n)

• If $n \ge m$, it is additionally true: drop m . take n = take (n-m) . drop m

Example F: Induction on Lists w/ reverse

Properties of **reverse** that can be proved by induction on lists.

For all finite xs it is true: head (reverse xs) = last xs last (reverse xs) = head xs

For all finite xs with only defined elements it is true: reverse (reverse xs) = xs 6.3.3

Chapter 6.3.4 Inductive Proofs on Partial Lists

622 6.3.4 511/135

Preliminaries

Computations that	
 fail to terminate are faulty, i.e., produce an error 	Chap. 4 Chap. 5
do not give a proper, i.e., a defined value.	Chap. 6 6.1 6.2 6.2.1 6.2.2
The value of such computations is called the • undefined value.	6.2.3 6.3 6.3.1 6.3.2 6.3.3 6.3.4
The undefined value is usually denoted by \perp ("bottom").	6.3.5 6.4 6.5 6.6 6.7

Examples

The function

```
buggy_fac :: Integer -> Integer
buggy_fac n = (n-1) * buggy_fac n
buggy_fac 0 = 1
```

...induces for every argument a non-terminating computation.

The function

```
buggy_div :: Integer -> Integer
buggy_div n = div n 0
```

...produces an error for each argument called with.

6.3.4 513/135

The Undefined Value in Haskell

The undefined value \bot

- is an element of every data type of Haskell representing the value of a
 - faulty or non-terminating computation.
 - \perp can be considered the "least accurate" approximation of (ordinary) values of the corresponding data type.

The definition

Polymorphic	Concrete
bottom :: a	bottom :: Integer
bottom = bottom	bottom = bottom

is the most simple expression (of arbitrary type) whose evaluation leads to a non-terminating computation with value \perp .

6.3.4 514/135

The Undefined Value and Lists	
 ▶ an "ordinary" element of a list 	
	Chap. 3 Chap. 4
Example.	Chap. 5 Chap. 6 6.1 6.2 6.2.1 6.2.2 6.2.3 6.3 6.3.1 6.3.2 6.3.3
The occurrence of bottom in 1st2 and the second occur-	6.3.3 6.3.4 6.3.5 6.4 6.5 6.6 6.6 6.7 Chap. 7 Chap. 8
rence of bottom in 1st3 are of type [Integer].	Chap. 9

Defined and Partial Lists

Definition (6.3.4.1, Defined Values) A value of a data type is defined, if it is not equal to \perp .

Definition (6.3.4.2, Defined and Partial Lists)

A list is

- defined, if it is a list of defined values
- ▶ partial, if it is built from the undefined list, i.e., if its tail is the undefined list ⊥

Example:

- 1st4 is a defined list, while 1st1, 1st2, 1st3 are not.
- lst2 and lst3 are partial, while lst1 is neither defined nor partial (note: lst1 contains an undefined element but is not built from the undefined list).

6.3.4 516/135

Examples of Partial Lists

Successively increasingly defined partial lists:

- ▶ bottom (the undefined list, i.e., the "least defined" partial list)
- ▶ 1 : bottom (partial list)
- ▶ 1 : 2 : bottom (partial list)
- ▶ 1 : 2 : 3 : bottom (*partial list*)

▶ ...

▶ ...

▶ 1 : 2 : 3 : 4 : 5 : 6 : 7 : bottom (*partial list*)

Properties of Functions on Partial Lists (1)

```
reverse (lst1) ->> [9,7 ...followed by an infinite wait
reverse (lst2) ->> ...infinite wait
reverse (1st3) ->> ...infinite wait
reverse (lst4) ->> [7,5,3,2]
head (tail (reverse lst1)) ->> 7
head (tail (tail (reverse lst1)]) ->> ...infinite wait
last (lst1) ->> 7
last (lst2) ->> ...infinite wait
head (tail (reverse 1st2)) ->> ...infinite wait
                                                          6.3.4
head (reverse lst1) ->> 9
head (tail (reverse lst1)) ->> 7
head (reverse (reverse lst1)) ->> 2
reverse (reverse (lst1) ->> [2 ...followed by an
                                   infinite wait
                                                          518/135
```

Properties of Functions on Partial Lists (2)

length lst1 ->> 4	
<pre>length lst2 ->>infinite wait</pre>	
<pre>length lst3 ->>infinite wait</pre>	
length 1st4 ->> 4	
5	
<pre>length (take 3 lst1) ->> 3 length (take 2 lst2) ->> 2 length (take 3 lst3) ->> 3</pre>	6.1 6.2 6.2.1 6.2.2 6.2.3 6.3 6.3.1 6.3.2
<pre>length (take 4 lst4) ->> 4 length (take 5 lst4) ->> 4 length (take 4 lst2) ->> 4 length (take 5 lst2) ->>infinite wait</pre>	6.3.3 6.3.4 6.3.5 6.4 6.5 6.6 6.7 Chap. 7 Chap. 8
	спар. о

Chap. 9

Properties of Functions on Partial Lists (3)

For understanding the different behaviours recall the definitions of length and reverse:

```
length :: [a] -> Int
length [] = 0
length (x:xs) = 1 + length xs -- x is not evaluated!
length :: [a] -> Int
length [] = 0
length (_:xs) = 1 + length xs -- x is not evaluated!
reverse :: [a] -> [a]
                                                       6.3.4
reverse [] = []
reverse (x:xs) = reverse x ++ [x] -- x is evaluated!
reverse :: [a] -> [a]
                              -- x is evaluated!
reverse = foldl (flip (:)) []
```

Inductive Proofs on Lists Reconsidered

The inductive proof pattern introduced at the beginning of Chapter 6.3.3 holds for

defined lists.

For inductive proofs of properties on partial lists (such as lst2) with possibly undefined elements (such as lst3) it has to be replaced by the inductive proof principle shown next.

6.3.4

Inductive Proofs on Partial Lists w/ Possibly Undefined Elements

Inductive proof pattern for partial lists with possibly undefined elements:

- Let P be a property on lists.
 - 1. Base case: Prove that P is true for the empty list and for the undefined list, i.e. prove P([]) and $P(\bot)$.
 - 2. Inductive case: Assuming that P(xs) is true (induction hypothesis), prove that P(x : xs) is true, for x being a defined and an undefined value (induction step).

6.3.4 522/135

Chapter 6.3.5 Inductive Proofs on Streams

523/135

6.3.5

Approximating Lists and Streams

Lists and Streams

 can be approximated by sequences of increasingly more accurate partial lists, also called approximants. 6.3.5 524/135 Approximating Lists by Partial Lists

The list

[1,2,3,4,5] = 1 : 2 : 3 : 4 : 5 : []

is approximated by the below sequence of partial lists that are increasingly more accurate approximations and ultimately culminate in the list [1,2,3,4,5]:

bottom

1	:	bo	bt'	ton	1						
1	:	2	:	bo	bt	ton	1				
1	:	2	:	3	:	bc	bt'	ton	1		
1	:	2	:	3	:	4	:	bc	bt!	tom	
1	:	2	:	3	:	4	:	5	:	bottom	
1	:	2	:	3	:	4	:	5	:	[]	

6.3.5 525/135

Approximating Streams by Partial Lists (1)	
The stream	
[1,2,3,4,5]	
of natural numbers is the limit of the infinite sequence of increasing approximations of partial lists:	Chap. 4 Chap. 5
bottom 1 : bottom 1 : 2 : bottom 1 : 2 : 3 : bottom 1 : 2 : 3 : 4 : bottom 1 : 2 : 3 : 4 : 5 : bottom 1 : 2 : 3 : 4 : 5 : 6 : 7 : 8 : 9 : bottom 	Chap. 6 6.1 6.2 6.2.1 6.2.2 6.2.3 6.3 6.3.1 6.3.2 6.3.3 6.3.4 6.3.5 6.4 6.5 6.6 6.7 Chap. 7 Chap. 8 Chap. 9
	526/13

Approximating Streams by Partial Lists (2)

Note:

- Considering partial lists approximations of streams reminds to the strategy of partially outputting/printing streams by hitting Ctrl-C after some period of time.
- Extending this period of time further and further yields successively more accurate approximations of the stream.

6.3.5 527/135

Equality of Lists and Streams

Definition (6.3.5.1, Equality of Lists)

Two lists xs and ys are equal, if all their approximants are equal, i.e., if for all natural numbers n, take n xs = take n ys.

Definition (6.3.5.2, Infinite Lists, Streams) A list xs is infinite or a stream, if for all natural numbers n, take n xs /= take (n+1) xs.

Definition (6.3.5.3, Equality of Streams)

Two streams xs and ys are equal, if for all natural numbers n, xs!!n = ys!!n.

6.3.5 528/135

Extending Properties from Lists to Streams

Properties on lists	
 can be extensible to streams, e.g., 	
take n xs ++ drop n xs = xs	Chap. 4
-	
but need not be extensible to streams, e.g.,	Chap. 6
reverse (reverse xs)) = xs	6.1 6.2 6.2.1 6.2.2
Similarly, properties that are true for every partial list of an approximating sequence of partial lists	6.2.3 6.3 6.3.1 6.3.2 6.3.3
can be true for their limit	6.3.4 6.3.5 6.4
but need not be true for their limit, e.g., "this list is partial"	6.5 6.6 6.7
partial".	Chap. 7
	Chap. 8
	Chap. 9

Hence

Proving properties on streams thus demands for tailored

proof strategies

that avoid such anomalies and paradoxes.

Fortunately

The restriction "expressed as an equation in Haskell" is sufficient to ensure that a property that is true for every partial list of an approximating sequence is also true for its limit.

6.3.5 530/135

Inductive Proofs on Streams

Inductive proof pattern for streams with only defined elements: Let P be a property on streams expressed as an equation in Haskell.

- Base case: Prove that P holds for the least defined list, i.e. prove P(⊥) (instead of P([])).
- 2. Inductive case: Assume that P(xs) is true (induction hypothesis) and prove that P(x : xs) is true (induction step).

6.3.5 531/135

Example A: Induction on Streams (1)

	Chap. 4
Lemma (6.3.5.4)	
For all streams xs is true:	Chap. 6 6.1 6.2
take n xs ++ drop n xs = xs	6.2.1 6.2.2 6.2.3 6.3
Proof by induction on the structure of xs .	6.3.1 6.3.2 6.3.3 6.3.4
	6.3.5 6.4 6.5 6.6 6.7
	Chap. 7
	Chap. 8
	Chap. 9
	Chan 10

Example A: Induction on Streams (2)	
Base case:	
take n \perp ++ drop n \perp	
$=$ \perp ++ drop n \perp	
$= \perp$ Inductive case:	Chap. 6 6.1 6.2 6.2.1 6.2.2 6.2.3
$take \ n \ (x : xs) \ ++ \ drop \ n \ (x : xs)$ $= x : (take \ (n-1) \ xs \ ++ \ drop \ (n-1) \ xs)$ $(IH) = x : xs$	6.3 6.3.1 6.3.2 6.3.3 6.3.4 6.3.5 6.4 6.5 6.6 6.6 6.7
	Chap. 7 Chap. 8 Chap. 9

	Chap. 4
Charter 6 1	
Chapter 6.4	Chap. 6 6.1
	6.2 6.2.1
Approximation	6.2.2
· · · · · · · · · · · · · · · · · · ·	6.2.3 6.3
	6.3.1 6.3.2
	6.3.3
	6.3.4 6.3.5
	6.4
	6.5 6.6
	6.7
	Chap. 7
	Chap. 8
	Chap. 9
	534/135

Proof by Approximation

... is an important principle

- for proving properties of infinite objects, e.g. equality of streams
- has been applied in Chapter 6.3.5.
- is more general than the usage suggested there.

...will be considered in more detail in this chapter.

Preliminaries

Definition (6.4.1, Partially Ordered Set)

A relation R on M is called a partially ordered set (or partial order) iff R is reflexive, transitive, and anti-symmetric.

Definition (6.4.2, Chain)

Let (P, \sqsubseteq) be a partially ordered set. A subset $C \subseteq P$ is called a chain of P, if the elements of C are totally ordered.

Remark

 Refer to Appendix to recall the meaning of terms if necessary.

Domains

Definition (6.4.3, Domain)

A set D with a partial order \sqsubseteq is called a domain, if

- 1. D has a least element \perp
- 2. $\Box C$ exists for every chain C in D

Example

Let P(IN) denote the power set of IN. Then (P(IN), ⊑) with ⊑ =_{df} ⊆ is a domain with least element Ø and ∐ C = ∪ C for every chain C in P(IN).

Note

- A domain is a (chain) complete partial order (cf. Appendix)
- ► The relation ⊆ of a domain is also called approximation order.

Approximation Order for Lists and Streams

Definition (6.4.4, Approximation Order) We define the following relation on lists and streams:

$$\begin{array}{cccc} \bot & \sqsubseteq & xs \\ [] & \sqsubseteq & xs & =_{df} & xs = [] \\ x : xs & \sqsubseteq & y : ys & =_{df} & x \sqsubseteq & y & \land & xs \sqsubseteq & ys \end{array}$$

Lemma (6.4.5, Domain Property of List Types)

Let a be a type such that its values form a domain. Then the values of the data types [a] form under the approximation order of Definition 6.4.4 a domain.

Approximating Lists by Partial Lists

By means of Definition 6.4.4, we have:

$$\perp \sqsubseteq x_0 : \perp \sqsubseteq x_0 : x_1 : \perp \sqsubseteq x_0 : x_1 : \ldots : x_n : \perp \\ \sqsubseteq x_0 : x_1 : \ldots : x_n : []$$

This finite set of approximations is a chain. We have:

$$\bigcup \{ \bot, x_0 : \bot, x_0 : x_1 : \bot, x_0 : x_1 : \ldots : x_n : \bot, \\ x_0 : x_1 : \ldots : x_n : [] \} \\ = x_0 : x_1 : \ldots : x_n : []$$

6.4 539/135

Approximating Streams by Partial Lists

Similarly, streams can be approximated by partial lists, too:

$$\perp \sqsubseteq x_0 : \perp \sqsubseteq x_0 : x_1 : \perp \sqsubseteq x_0 : x_1 : \ldots : x_n : \perp \\ \sqsubseteq x_0 : x_1 : \ldots : x_n : x_{n+1} : \perp \sqsubseteq \ldots$$

This infinite set of approximations is a chain. We have:

$$\bigsqcup \{ \bot, x_0 : \bot, x_0 : x_1 : \bot, x_0 : x_1 : x_2 : \bot, \ldots \} = xs$$

6.4 540/135
Computing Partial Approximations

The function approx gives approximations of any list, stream:

approx	:: Int	ceger	->	[a]	-	->	[a]		
approx	(n+1)	[]	=	[]					
approx	(n+1)	(x:xs)) =	х	:	ap	prox	n	xs

Note:

- n+1 matches only positive integers.
- Calling approx n xs with n smaller or equal to the length of xs will cause an error after generating the first n elements of the list, i.e., it generates the partial list

 x_0 : x_1 : . . . : x_{n-1} : \perp

If n is greater than the length of xs, the call approx n xs generates the whole list xs.

Proof by Approximation

Lemma (6.4.6, Approximation) For any list, stream xs holds:

$$\bigsqcup_{n=0}^{\infty} approx \ n \ xs = xs$$

Theorem (6.4.7, Approximation) For any two lists, streams xs, ys hold:

 $xs = ys \Leftrightarrow \forall n \in IN$. approx n xs = approx n ys

Proving Properties of Streams

Note:

- The Approximation Theorem 6.4.7 is an important means for proving properties of streams.
- The inductive proof principle for streams of Chapter 6.3.5 is justified by Theorem 6.4.7.

Chapter 6.4: Further Reading

Kees Doets, Jan van Eijck. The Haskell Road to Logic, Maths and Programming. Texts in Computing, Vol. 4, King's College, UK, 2004. (Chapter 10, Corecursion – Proof by Approximation) 6.4 544/135

	Chap. 4
Chapter 6.5	Chap. 6
	6.1 6.2
C to L at	6.2.1
Coinduction	6.2.2
	6.2.3 6.3
	6.3.1
	6.3.2
	6.3.3 6.3.4
	6.3.5
	6.4
	6.5
	6.6 6.7
	Chap. 7
	Chap. 8
	Chap. 9
	545/135

Proof by Coinduction

... is another important principle

- for proving properties of infinite objects, e.g. equality of streams
- complements the principle of proof by approximation for proving properties of infinite objects (cf. Chapter 6.3.5)
- extends our tool box for proving properties of infinite objects like streams

Essence of Proof by Coinduction (1)

Proof by coinduction of equality of two infinite objects

 amounts to proving that the two objects exhibit the same observational behaviour.

For example, proving the equality of two streams *xs* and *ys* using the principle of proof by coinduction amounts to proving that

- xs and ys have the same heads
- the tails of xs and ys have the same observational behaviour

6.5 547/135

Essence of Proof by Coinduction (2)

Technically, proof by coinduction of the equality of two infinite objects *xs* and *ys* boils down to

defining a bisimulation relation on xs and ys, and proving them to be bisimilar.

65

548/135

Formalizing this requires the notions of a labeled transition system and a bisimulation relation.

Labeled Transition Systems

Definition (6.5.1, Labeled Transition System)

A labeled transition system is a tripel (Q, A, T) consisting of

- a set of states Q
- a set of action labels A
- ▶ a ternary relation $T \subseteq Q \times A \times Q$, the transition relation.

Note:

• If $(q, a, p) \in T$, we write this as $q \stackrel{a}{\longrightarrow} p$.

6.5 549/135

Bisimulations

Definition (6.5.2, (Greatest) Bisimulation)

Let (Q, A, T) be a labeled transition system.

A bisimulation on (Q, A, T) is a binary relation R on Q with the following properties.

If q R p and $a \in A$ then

• If $q \xrightarrow{a} q'$ then there is a $p' \in Q$ with $p \xrightarrow{a} p'$ and q' R p'

▶ If $p \xrightarrow{a} p'$ then there is a $q' \in Q$ with $q \xrightarrow{a} q'$ and q' R p'

We denote the greatest bisimulation on Q by \sim .

6.5 550/135 Example

Consider the following decimal representations of $\frac{1}{7}$

- ▶ 0.142857
- ▶ 0.1428571
- ▶ 0.14285714
- ▶ 0.142857142857142
- and the relation R 'having the same infinite expansion' on decimal representations.

Then

- ► *R* is a bisimulation on decimal representations
- ► 0.142857, 0.1428571, 0.14285714, 0.142857142857142 are all bisimilar.

Illustration



Chap. 4
Chap. 6
6.1
6.2
6.2.1
6.2.2
6.2.3
6.3
6.3.1
6.3.2
6.3.3
6.3.4
6.3.5
6.4
6.5
6.6 6.7
0.7
Chap. 7
Chap. 8
Chap. 9
552/135

Definition (6.5.3, Bisimilar) Let (Q, A, T) be a labeled transition system, and let $p, q \in Q$. Then p and q are called bisimilar, if they are related by a bisimulation on Q. 6.5 553/135 The general pattern of a proof by coinduction for proving the equality of infinite objects:

Let x and y be two infinite objects.

To prove that x and y are equal, show that they exhibit the same behaviour, i.e. prove that $x \sim y$:

 $a \sim b \Leftrightarrow \exists R. (R \text{ is a bisimulation, and } a R b)$

Proof by Coinduction (2)

A proof matching the preceding pattern is called a

proof by coinduction.

Next, we are going to show how to use this pattern to prove equality of streams.

6.5 555/135

Proof by Coinduction (3)

To this end, we introduce the following notation:

If $f = [f_0, f_1, f_3, f_4, f_5, \ldots]$ is a stream, then f_0 denotes the head and \overline{f} the tail of f, i.e., $f = f_0 : \overline{f}$.

Note:

A stream *f* can be considered a labeled transition system.



6.5 556/135

Equality of Streams

Let $f = [f_0, f_1, f_3, f_4, f_5, ...]$ and $g = [g_0, g_1, g_3, g_4, g_5, ...]$ be two streams.

Then

► f and g are equal iff they exhibit the same behaviour iff $\forall i \in IN_0$. $f_i = g_i$

This boils down to

▶ f and g are equal iff $f \sim g$, i.e., $f_0 = g_0$ and $\overline{f} \sim \overline{g}$ with $f \xrightarrow{f_0} \overline{f}$ and $g \xrightarrow{g_0} \overline{g}$.

Stream Bisimulation

Definition (6.5.4, Stream Bisimulation)

A stream bisimulation on a set A is a relation R on [A] with the following property.

If $f, g \in [A]$ and f R g then both $f_0 = g_0$ and $\overline{f} R \overline{g}$.

Illustration



6.5 558/135

Proof by Coinduction w/ Stream Bisimulations

The general pattern of a proof by coinduction using stream bisimulations of $f \sim g$, where $f, g \in [A]$:

1. Define a relation R on [A]

2. Prove that R is a stream bisimulation, with f R g.

6.5 559/135

Chapter 6.5: Further Reading (1)

- Kees Doets, Jan van Eijck. The Haskell Road to Logic, Maths and Programming. Texts in Computing, Vol. 4, King's College, UK, 2004. (Chapter 10.3, Proof by Approximation; Chapter 10.4, Proof by Coinduction)
- Chung-Kil Hur, Georg Neis, Derek Dreyer, Viktor Vafeiadis. The Power of Parameterization in Coinductive Proofs. In Conference Record of the 40th Annual ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages (POPL 2013), 193-205, 2013.
- Robin Milner. Communicating and Mobile Systems: The Pi-Calculus. Cambridge University Press, 1999.

6.5 560/135

Chapter 6.5: Further Reading (2)

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6.5 561/135

Chapter 6.6 Fixed Point Induction

Fixed Point Induction

...another important proof principle.

Fixed point induction allows proving properties of functions on ordered sets, such as complete partial orders, lattices, and the like (cf. Appendix).

Admissible Predicates

Definition (6.5.1, Admissible Predicate)

Let (C, \sqsubseteq) be a complete partial order (CPO), and let $\psi : C \rightarrow IB$ be a predicate on C.

The predicate ψ is called admissible iff for every chain $D \subseteq C$ holds:

if
$$\psi(d) = true$$
 for all $d \in D$ then $\psi(| D) = true$

6.6 564/135

Fixed Point Induction

The general pattern of a proof by fixed point induction:

Theorem (6.5.2, Fixed Point Induction) Let (C, \sqsubseteq) be a complete partial order (CPO), let $f : C \to C$ be a continuous function on C, and let $\psi : C \to IB$ be an admissible predicate on C.

If for all $c \in C$ holds that

$$\psi(c) = true implies \psi(f(c))$$

then

$$\psi(\mu f)$$
 $=$ true

where μf denotes the least fixed point of f.

Note

Streams

▶ form a domain resp. CPO (cf. Chapter 6.4 and Appendix)

Hence, fixed point induction is a relevant proof technique for a functional programmer.

6.6 566/135

Chapter 6.6: Further Reading

- Hanne Riis Nielson, Flemming Nielson. Semantics with Applications: A Formal Introduction. Wiley, 1992. (Chapter 6, Axiomatic Program Verification – Fixed Point Induction)
- Hanne Riis Nielson, Flemming Nielson. Semantics with Applications: An Appetizer. Springer-V., 2007. (Chapter 9, Axiomatic Program Verification – Fixed Point Induction)

6.6 567/135

Chapter 6.7 Other Approaches, Verification Tools

6.7 568/135

Other Approaches and Tools: A Selection (1)

- Programming by contracts (Vytiniotis et al., POPL 2013)
- Verifying equational properties of functional programs (Sonnex et al., TACAS 2012)
 - Tool Zeno: proof search based on induction and equality reasoning driven by syntactic heuristics.
- Verifying first-order and call-by-value recursive functional programs (Suter et al., SAS 2011)
 - Tool Leon: based on extending SMT with recursive programs.

6.7 569/135

Other Approaches and Tools: A Selection (2)

- Verifying higher-order functional programs (Unno et al., POPL 2013)
 - Tool MoCHi-X: prototype implementation of the type inference algorithm as an extension of the software model checker MoChi (Kobayashi et al, PLDI 2011).
- Verifying lazy Haskell (Mitchell et al., Haskell 2008)
 - Tool Catch: based on static analysis; can prove absence of pattern match failures; evaluated on 'real' programs.

6.7 570/135

Chapter 6: Further Reading (1)

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- Matthias Blume, David McAllester. Sound and Complete Models of Contracts. Journal of Functional Programming 16(4-5):375-414, 2006.

6.7 571/135

Chapter 6: Further Reading (2)

- Manuel Chakravarty, Gabriele Keller. Einführung in die Programmierung mit Haskell. Pearson Studium, 2004. (Kapitel 9.1.2, Induktion; Kapitel 9.1.3, Strukturelle Induktion; Kapitel 9.2, Mit Lemmata und Generalisierung arbeiten; Kapitel 9.3, Programmherleitung)
- Werner Damm, Bernhard Josko. A Sound and Relatively^{*} Complete Hoare-Logic for a Language with Higher Type Procedures. Acta Informatica 20:59-101, 1983.
- Antonie J.T. Davie. An Introduction to Functional Programming Systems using Haskell. Cambridge University Press, 1992. (Chapter 9, Correctness)

6.7 572/135

Chapter 6: Further Reading (3)

- Kees Doets, Jan van Eijck. The Haskell Road to Logic, Maths and Programming. Texts in Computing, Vol. 4, King's College, UK, 2004. (Chapter 3, The Use of Logic: Proof – Proof Style, Proof Recipes, Strategic (Proof) Guidelines; Chapter 7, Induction and Recursion; Chapter 10, Corecursion – Proof by Approximation, Proof by Coinduction; Chapter 11.1, More on Mathematical Induction)
- Andreas Goerdt. A Hoare Calculus for Functions defined by Recursion on Higher Types. In Proceedings of the Conference on Logic of Programs, Springer-V, LNCS 193, 106-117, 1985.

6.7 573/135

Chapter 6: Further Reading (4)

- Paul Hudak. The Haskell School of Expression: Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 11, Proof by Induction; Chapter 14.6, Inductive Properties of Infinite Lists)
- Ranjit Jhala, Rupak Majumdar, Andrey Rybalchenko. HMC: Verifying Functional Programs using Abstract Interpreters. In Proceedings of the 23rd International Conference on Computer Aided Verification (CAV 2011), Springer-V., LNCS 6806, 470-485, 2011.
- Steve King, Jonathan Hammond, Roderick Chapman, Andy Pryor. Is Proof More Cost-Effective than Testing? IEEE Transactions on Software Engineering 26(8):675-686, 2000.

6.7 574/135

Chapter 6: Further Reading (5)

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- Hanne Riis Nielson, Flemming Nielson. Semantics with Applications: A Formal Introduction. Wiley, 1992. Chapter 1, Introduction – Structural Induction; Chapter 6, Axiomatic Program Verification – Fixed Point Induction)

Chapter 6: Further Reading (6)

- Hanne Riis Nielson, Flemming Nielson. Semantics with Applications: An Appetizer. Springer-V., 2007. Chapter 1, Introduction – Structural Induction; Chapter 9, Axiomatic Program Verification – Fixed Point Induction)
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- Peter Pepper. Funktionale Programmierung in OPAL, ML, Haskell und Gofer. Springer-V., 2. Auflage, 2003. (Kapitel 11.4.1, Über wohlfundierte Ordnungen; Kapitel 11.4.2, Wie beweist man Terminierung?)

6.7 576/135
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6.7 577/135

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- Simon Thompson. Proof. In Research Directions in Parallel Functional Programming, Kevin Hammond, Greg Michaelson (Eds.), Springer-V., Chapter 4, 93-119, 1999.

6.7 578/135

Chapter 6: Further Reading (9)

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6.7 579/135

Part IV Advanced Language Concepts

6.7

Chapter 7 Functional Arrays

Chap. 7

For imperative arrays holds:

- A value of the array can be accessed or updated in constant time.
- The update operation does not need extra space.
- There is no need for chaining the array elements with pointers as they can be stored in contiguous memory locations.

Chap. 7 582/135

Lists and Functional Arrays

(Functional) lists

- do not enjoy the favorable list of characteristics of imperative arrays; most importantly, values of a list cannot be accessed or updated in constant time.
 - Using (!!) to access the *i*th element of a list takes a number of steps proportional to *i*.
- ► Lists can be arbitrarily long, potentially even infinite.

Functional arrays

- are designed and implemented to get as close as possible to the characteristics of imperative arrays.
 - Using (!) to access the *i*th element of an array takes a constant number of steps, regardless of *i*.
- Arrays are of a fixed size which must be defined at the time the array is (first) created.

Chap. 7 583/135

Functional Arrays

Functional arrays

 are not part of the standard prelude Prelude.hs of Haskell.

Various libraries

- provide different kinds of functional arrays
 - import Array
 - import Data.Array.IArray
 - import Data.Array.Diff

Important variants of functional arrays

- Static arrays (w/out destructive update)
- Dynamic arrays (w/ destructive update)

Chap. 7 584/135

Static Arrays

Creating static arrays

import Array

There are three functions for creating static arrays:

- array bounds list_of_associations
- listArray bounds list_of_values
- accumArray f init bounds list_of_associations

Creating Static Arrays

The three functions for creating static arrays in more detail:

- array :: Ix a => (a,a) -> [(a,b)] -> Array a b
 array bounds list_of_associations
- listArray::(Ix a) => (a,a) -> [b] -> Array a b
 listArray bounds list_of_values
- accumArray :: (Ix a) => (b -> c -> b) -> b -> (a,a) -> [(a,c)] -> Array a b accumArray f init bounds list_of_associations

Chap. 7 586/135

The Type Class Ix

Ix denotes the class of types that are (mainly) used for indices of arrays.

- Members of the type class Ix must provide implementations of the functions
 - range
 - ▶ index
 - ▶ inRange
 - rangeSize
- Ix inherits from the type class Ord (and indirectly from the type class Eq):

class (Ord	a) => Ix a where	
range	:: (a,a) -> [a]	
index	:: (a,a) -> a -> Int	
inRange	:: (a,a) -> a -> Bool	
rangeSize	:: (a,a) -> Int	

Chap. 7 587/135

Creating Static Arrays: The 1st Mechanism

The first and most fundamental array creation mechanism:

array :: Ix a => (a,a) -> [(a,b)] -> Array a b
array bounds list_of_associations

Meaning of the arguments:

bounds: gives the value of the lowest and the highest index in the array.

Example: bounds of a

- zero-origin vector of five elements: (0,4)
- one-origin 10 by 10 matrix: ((1,1),(10,10))

Note: The values of the bounds can be arbitrary expressions.

list_of_associations: a list of associations, where an association is of the form (i,x) meaning that the value of the array element i is x.

Chap. 7 588/135

Examples

The expressions

have type

a' :: Array Int Char f :: Int -> Array Int Int m :: Array (Int,Int) Int

and value

Chap. 7 589/135

Properties of Array Creation

In general:

Arrays have type

- Array a b where
 - a: represents the type of the index
 - b: represents the type of the value

Moreover:

- An array is undefined if any specified index is out of bounds.
- If two associations in the association list have the same index, the value at that index is undefined.

This means: array is strict in the bounds but non-strict (lazy) in the values. In particular, an array can thus contain 'undefined' elements.

Chap. 7 590/135

Example

The computation of the Fibonacci numbers:

Chap. 7 591/135

Example (Cont'd)		
More Applications:		
more applications.		
fibs 5!5 ->> 3		
fibs 10!10 ->> 34		Chap. 4
fibs 100!10 ->> 34 1	Thanks to lazy evaluation	Chap. 6
(computation stops at	Chap. 7
1	fibs 10!10	Chap. 8
-		Chap. 9
fibs 50!50 ->> 7.778.7	742 040	Chap. 10
		Chap. 11
fibs 100!100 ->> 218.922	2.995.834.555.169.026	Chap. 12
		Chap. 13
fibs 5!10 ->> Program en	rror: Ix.index: index out	Chap. 14
of range		Chap. 15
-		Chap. 16

Chap. 16 Chap. 17 (592/135)

The Array Access Function (!)

The signature of the array access function (!):

(!) :: Ix a => Array a b -> a -> b

Recall: The index type must be an element of type class Ix, which defines operations specifically needed for index computations.

Chap. 7 593/135

Example (Cont'd)

Note:

- The declaration of a in a where-clause is crucial for performance.
- The local declaration of a avoids creating new arrays during computation.

For comparison consider:

xfibs n = a n

Chap. 7 Chap. 12 594/135 Example (Cont'd)

Applications:

```
xfibs 3 \rightarrow array (1,3) [(1,0),(2,1),(3,1)]
xfibs 5 \rightarrow array (1,5) [(1,0),(2,1),(3,1),
                            (4.2), (5.3)]
xfibs 10 ->> array (1,10) [(1,0),(2,1),(3,1),(4,2),
                              (5,3),(6,5),(7,8),(8,13),<sub>Chap.7</sub>
                              (9,21),(10,34)]
xfibs 5!5
              ->> 3
xfibs 10!10 ->> 34
xfibs 25!20 ->> 4.181
xfibs 25!25
               ->> ...takes too long to be feasible!
```

Note: Though correct, the evaluation of xfibs n is most inefficient due to the generation of new arrays during computation.

Creating Static Arrays: The 2nd Mechanism

The second array creation mechanism:

> listArray::(Ix a) => (a,a) -> [b] -> Array a b
listArray bounds list_of_values

Meaning of the arguments:

- bounds: gives the value of the lowest and the highest index in the array.
- *list_of_values*: a list of values.

The function listArray

 is useful for the frequenly occurring case where an array is constructed from a list of values in index order.
 Example:

Chap. 7 596/135

Creating Static Arrays: The 3rd Mechanism

The third array creation mechanism:

> accumArray :: (Ix a) => (b -> c -> b) -> b -> (a,a) -> [(a,c)] -> Array a b accumArray f init bounds list_of_associations

...removes the restriction that a given index may appear at most once in the association list. Instead, 'conflicting' indices are accumulated via a function f.

Meaning of the arguments:

- ▶ *f*: an accumulation function.
- init: gives the (default) value the entries of the array shall be initialized with.
- bounds: gives the value of the lowest and the highest index in the array.
- list_of_associations: a list of associations.

Chap. 7 597/135

A Histogram Function



A Prime Number Test

```
...using the function accumArray:
primes :: Int -> Array Int Bool
primes n =
   accumArray (\e e' -> False) True (2,n) 1
    where l = concat [map (flip (,) ())
                  (takeWhile (<=n) [k*i|k<-[2..]])
                                                            Chap. 7
                                    | i < -[2...n 'div' 2] |
Applications:
 (primes 100)!1 ->> Program error: Ix.index: index
                   out of range
 (primes 100)!2 ->> True
 (primes 100)!4 ->> False
 (primes 100)!71 ->> True
 (primes 100)!100 ->> False
 (primes 100)!101 ->> Program error: Ix.index: index
                     out of range
                                                             599/135
```

```
A Prime Number Test (Cont'd)
 More Applications:
  elems (primes 10)
                                                           Chap. 2
   ->> [True,True,False,True,False,True,False,False,False]
                                                           Chap. 3
  assocs (primes 10)
   ->> [(2,True),(3,True),(4,False),(5,True),(6,False),
        (7,True), (8,False), (9,False), (10,False)]
                                                           Chap. 7
  yieldPrimes (assocs (primes 100))
   ->> [2,3,5,7,11,13,17,19,23,29,31,37,41,43,47,53,
        59,61,67,71,73,79,83,89,97]
 where
  yieldPrimes :: [(a,Bool)] -> [a]
  yieldPrimes [] = []
  yieldPrimes ((v,w):t)
   | w = v : yieldPrimes t
   | otherwise = yieldPrimes t
```

Array Operators

Array operators are:

- I: array subscripting.
- bounds: yields bounds of an array.
- indices: yields list of indices of an array.
- elems: yields list of elements of an array.
- assocs: yields list of associations of an array.
- //: array updating the operator // takes an array and a list of associations and returns a new array identical to the left argument except for every element specified by the right argument list.

This means: // does not perform a destructive update!

Chap. 7 601/135

Array Operators (Cont'd)

► ...

- ▶ (!) :: (Ix a) => Array a b -> a -> b
- ▶ bounds :: (Ix a) => Array a b (a,a)
- ▶ indices :: (Ix a) => Array a b -> [a]
- ▶ elems :: (Ix a) => Array a b -> [b]
- ▶ assocs :: (Ix a) => Array a b -> [(a,b)]
- ► (//) :: (Ix a) => Array a b -> [(a,b)] -> Array a b

Chap. 7

Illustrating the Usage of Array Operators Let m = array((1,1), (2,3))[((i,j), (i*j))]| i<-[1..2], i<-[1..3]] Then $m \rightarrow array ((1,1),(2,3)) [((1,1),1),((1,2),2),((1,3),3)], Chap 5 ((1,1),1),((1,2),2),((1,3),3)], Chap 5 ((1,1),1),((1,2),2),((1,3),3), Chap 5 ((1,1),1),((1,2),2),((1,1),1),((1,2),2),((1,1),1),((1,2),2),((1,1),1),((1,2),2),((1,1),1),((1$ ((2,1),2),((2,2),4),((2,3),6)]_{Chap. 7} $m!(1,2) \rightarrow 2, m!(2,2) \rightarrow 4, m!(2,3) \rightarrow 6$ bounds m $\rightarrow > ((1,1),(2,3))$ indices m ->> [(1,1),(1,2),(1,3),(2,1),(2,2),(2,3)] elems m ->> [1,2,3,2,4,6] assocs m $\rightarrow > [((1,1),1), ((1,2),2), ((1,3),3),$

((2,1),2), ((2,2),4), ((2,3),6)]

Illustrating the Update Operator The histogram function: histogram (lower, upper) xs = updHist (array (lower,upper) [(i,0) | i<-[lower..upper]]) XS Chap. 7 updHist a [] = a XS^{ap. 9} updHist a (x:xs) = updHist (a // [(x, (a!x + 1))])Application: histogram (0,9) [3,1,4,1,5,9,2] ->> array (0,9) [(0,0),(1,2),(2,1),(3,1),(4,1), (5.1), (6.0), (7.0), (8.0), (9.1)

Illustrating the accum Operator

Instead of replacing the old value, values with the same index could also be combined using the predefined:

> accum :: (Ix a) => (b -> c -> b) -> Array a b -> [(a,c)] -> Array a b accum function array list_of_associations

Application:

Note:

The result is a new matrix identical to m except for the elements (1,1) and (2,2) to which 4 and 8 have been added, respectively. Chap. 7 605/135

Higher-Order Array Functions

Higher-order functions can be defined on arrays just as on lists.

For illustration consider:

The expression
 map (\x -> x*10) a

...creates a new array where all elements of a are multiplied by 10.

The expression

ixmap b f a = array b $[(k, a ! f k) | k < -range b]_{Chap.12}$... with ixmap :: (Ix a, Ix b) => (a,a) -> (a -> b)

Chap. 7 606/135

Higher-Order Array Functions (Cont'd)

The functions **row** and **col** return a row and a column of a matrix:

Chap. 7 607/135 Higher-Order Array Functions (Cont'd)

Applications:

Chap. 7 608/135

Dynamic Arrays

Creating dynamic arrays

import Data.Array.Diff

Instead of

type Array

we now have to use

type DiffArray

... everything else remains the same.

Chap. 7 609/135

Summing up

Static Arrays

- Access operator (!): access to each array element in constant time.
- Update operator (//): no destructive updates; instead an identical copy of the argument array is created except of those elements which were 'updated.' Updates thus do not take constant time.

Dynamic Arrays

- Update operator (//): destructive updates; updates take constant time per index.
- Access operator (!): access to array elements may sometimes take longer as for static arrays.

Chap. 7 610/135 Summing up (Cont'd)

Recommendation

- Dynamic arrays should only be used if constant time updates are crucial for the application.
- Often, updates can completely be avoided by smartly written recursive array constructions (cp. the prime number test in this chapter).

Chap. 7 611/135

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Chap. 7

Chapter 7: Further Reading (4)

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Chap. 7 615/135

Chapter 7: Further Reading (5)

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- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 20, Time and space behaviour)
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Chap. 7

Chapter 8 Abstract Data Types

Chap. 8

Concrete vs. Abstract Data Types (1)

Concrete Data Types (CDTs)

- ► A new CDT is specified by naming its values.
- With the exception of functions, each value is of a type is described by a unique expression in terms of constructors.
- Using definition by pattern matching as a basis, these expressions can be generated, inspected, and modified in various ways.
- There is no need to specify the operations associated with a type.
- The Haskell means for defining CDTs are algebraic data type definitions.

Chap. 8

Concrete vs. Abstract Data Types (2)

Abstract Data Types (ADTs)

- A new ADT is not specified by naming its values but by naming its operations.
- How values are represented is thus less important than what operations are provided for manipulating them, whose meaning, of course, has to be described
 - degree of freedom for the implementation!
 - Information hiding!
- There is no dedicated means in Haskell for defining ADTs; ADTs, however, can be defined using modules.

Chap. 8 619/135

Concrete vs. Abstract Data Types (3)

Implementing an ADT

- When implementing an ADT, a representation of its values has to be provided, and a definition of the operations of the type in terms of this representation.
- The representation can be chosen e.g. for grounds of simplicity or efficiency.
- It has to be shown that the implemented operations satisfy the prescribed relationships.



In the following

we consider abstract data types for	Chap. 4
we consider abstract data types for	
► Stacks	
► Queues	Chap. 7 Chap. 8
 Priority Queues 	8.1 8.2 8.3
 Tables 	8.4 8.5
	Chap. 9
	Chap. 10
	Chap. 13
	Chap. 12
	Chap. 13
	Chap. 14
	Char 11

Chapter 8.1 Stacks

8.1

The Abstract Data Type Stack (1)

The user-visible interface specification of the Abstract Data Type (ADT) Stack:

push	::	a -> Stack a -> Stack a
рор	::	Stack a -> Stack a
top	::	Stack a -> a
emptyStack	::	Stack a
stackEmpty	::	Stack a -> Bool

Note: In a stack elements are removed in a last-in/first-out (LIFO) order.

8.1 623/135 The Abstract Data Type Stack (2) A user-invisible implementation of Stack as an algebraic data type (using data): data Stack a = EmptyStk | Stk a (Stack a) push x s = Stk x spop EmptyStk = error "pop from an empty stack" $pop (Stk _ s) = s$ top EmptyStk = error "top from an empty stack" $top (Stk x _) = x$ emptyStack = EmptyStk stackEmpty EmptyStk = True stackEmpty _ = False

Chap. 15 624/135

8.1

The Abstract Data Type Stack (3) A user-invisible implementation of Stack as an algebraic data type (using newtype): newtype Stack a = Stk [a] push x (Stk xs) = Stk (x:xs) pop (Stk []) = error "pop from an empty stack" pop (Stk (:xs)) = Stk xs8.1 top (Stk []) = error "top from an empty stack" $top (Stk (x:_)) = x$ emptyStack = Stk [] stackEmpty (Stk []) = True stackEmpty (Stk _) = False

> Chap. 15 625/135

Displaying Stacks (1)

Note:

- The constructors EmptyStk and Stk are not exported from the module.
- This implies that a user of the module can not use or create a Stack by any other way than the operations exported by the module
- While this is actually so desired, the user can also not display a value of type Stack except for the crude and cumbersome way of completely popping the whole stack.

Next, we describe and compare to ways to display stacks and their elements more elegantly.

8.1 626/135

Displaying Stacks (2)	
The easy way: Using a deriving-clause	Contents Chap. 1
	Chap. 2
data Stack a = EmptyStk Stk a (Stack a) deriving Show	Chap. 3 Chap. 4
newtype Stack a = Stk [a] deriving Show	Chap. 5 Chap. 6
newtype Stack a - Stk [a] deriving Snow	Chap. 7
Effect:	Chap. 8 8.1 8.2
<pre>push 3 (push 2 (push 1 emptyStack))</pre>	8.3 8.4 8.5
->> Stk 3 (Stk 2 (Stk 1 EmptyStk))	Chap. 9
	Chap. 10
<pre>push 3 (push 2 (push 1 emptyStack))</pre>	Chap. 11 Chap. 12
->> Stk [3,2,1]	Chap. 13
	Chap. 14
	Chap. 15 627/135

Displaying Stacks (3)

Using the deriving-clause for type class Show:

Advantage

Simplicity, no effort.

Disadvantage

The implementation of the ADT Stack is disclosed to the programmer (though the user cannot access the representation in any way outside the module definition of the ADT Stack).



Displaying Stacks (4)

A smarter solution:

instance (Show a) => Show (Stack a) where showsPrec _ EmptyStk str = showChar '-' str showsPrec _ (Stk x s) str = shows x (showChar '|' (shows s str)) instance (Show a) => Show (Stack a) where showsPrec (Stk []) str = showChar '-' str showsPrec _ (Stk (x:xs)) str = shows x (showChar '|' (shows (Stk xs) str))

Effect:

push 3 (push 2 (push 1 emptyStack)) $\rightarrow 3|2|1|-$

8.1

Displaying Stacks (5)

This way:

- The implementation of the ADT Stack remains hidden. It is not disclosed to the user.
- The output is the same for both implementations!

Note:

The first argument of showsPrec is an unused precedence value.



Last but not least

An implementation of stacks in terms of

predefined lists in Haskell: type Stack a = [a] would be possible, too.

Advantage

Even less conceptual overhead as for the implementation in terms of newtype Stack a = Stk [a]

Disadvantage

- All predefined functions on lists would be available on stacks, too.
- Many of these, however, e.g. for reversing a list, for picking some arbitrary element, are not meaningful for stacks.
- Implementing stacks in terms of predefined lists would not automatically exclude the application of such meaningless functions but require to explicitly abstain from them. Conceptually, this is disadvantageous.

8.1 631/135

Chapter 8.2 Queues

8.2

Chap. 15 632/135

The Abstract Data Type Queue (1)

The user-visible interface specification of the Abstract Data Type (ADT) Queue:

emptyQueue	::	Queue a
queueEmpty	::	Queue a -> Bool
enQueue	::	a -> Queue a -> Queue a
deQueue	::	Queue a -> Queue a
front	::	Queue a -> a

Note: In a queue elements are removed in a first-in/first-out (FIFO) order.

82

The Abstract Data Type Queue (2)	
A user-invisible implementation of Queue as an algebraic data	
type:	
newtype Queue a = Q [a]	
emptyQueue = Q []	
queueEmpty (Q []) = True	
<pre>queueEmpty _ = False</pre>	Chap 8.1
enQueue x (Q q) = Q (q ++ $[x]$)	8.2 8.3 8.4 8.5
<pre>deQueue (Q []) = error "deQueue: empty queue"</pre>	Chap
	Chap
$deQueue (Q (_:xs)) = Q xs$	Chap
<pre>front (Q []) = error "front: empty queue"</pre>	Chap
	Chap
front $(Q(x:_)) = x$	Chap

Chap. 15 634/135

Displaying Queues

The easy v	vay: Usi	ng	а	de	rivi	.ng-clause	
newtype	Queue	a	=	Q	[a]	deriving	Show

Advantages, disadavantages:

► Cp. Chapter 8.1.

Chap. 4
Chap. 6
Chap. 7
8.1 8.2 8.3 8.4 8.5
Chap. 9
Chap. 10
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15 635/135

Chapter 8.3 Priority Queues

8.3

The Abstract Data Type PQueue (1)
The user-visible interface specification of the Abstract Data Type (ADT) PQueue:
<pre>module PQueue (PQueue,emptyPQ,pqEmpty, enPQ,dePQ,frontPQ) where</pre>
<pre>emptyPQ :: PQueue a pqEmpty :: PQueue a -> Bool enPQ :: (Ord a) => a -> PQueue a -> PQueue a dePQ :: (Ord a) => PQueue a -> PQueue a frontPQ :: (Ord a) => PQueue a -> a</pre>
Note: In a priority queue each entry has a priority associated with it. The dequeue operation always removes the entry with the highest (or lowest) priority. Technically, this is ensured by

the highest (or lowest) priority. Technically, this is ensured by the enqueue operation, which places a new element according to its priority in a queue. 8.3

Chap. 15 637/135

The Abstract Data Type PQueue (2)	
A user-invisible implementation of PQueue as an algebraic	Contents
data type:	Chap. 1
newtype PQueue a = PQ [a]	Chap. 2
newcype rqueue a - rq [a]	Chap. 3
emptyPQ = PQ []	Chap. 4
	Chap. 5
pqEmpty (PQ []) = True	Chap. 6
pqEmpty _ = False	Chap. 7
$enPQ \times (PQ q) = PQ (insert x q)$	Chap. 8 8.1
where insert $x [] = [x]$	8.2 8.3
insert x r@(e:r') x <= e = x:r	8.4
otherwise = e:insert x r'	o.o Chap. 9
	Chap. 10
<pre>dePQ (PQ []) = error "dePQ: empty priority queue"</pre>	Chap. 11
dePQ (PQ (_:xs)) = PQ xs	Chap. 12
<pre>frontPQ (PQ []) = error "frontPQ: empty priority que</pre>	
$frontPQ (PQ (x:_)) = x$	Chap. 14
	Chap. 15 638/135

Displaying Priority Queues

The easy way: Using a deriving-clause
newtype PQueue a = PQ [a] deriving Show
Advantages, disadavantages: • Cp. Chapter 8.1.

8.3 639/135

Chapter 8.4 Tables

8.4

The Abstract Data Type Table (1) The user-visible interface specification of the Abstract Data Type (ADT) Table:

module Table (Table,newTable,findTable,updTable)
where

newTable :: (Eq b) => [(b,a)] -> Table a b findTable :: (Eq b) => Table a b -> b -> a updTable :: (Eq b) => (b,a) -> Table a b -> Table a b

Note:

- The function newTable takes a list of (index,value) pairs and returns the corresponding table.
- The functions findTable and updTable are used to retrieve and update values in the table.

The Abstract Data Type Table (2) A user-invisible implementation of Table as a function: newtype Table a b = Tbl (b -> a) newTable assocs = foldr updTable (Tbl (_ -> eror "updTable: item not found")) $\sum_{k=0}^{Chap. 7}$ assocs 8.4 findTable (Tbl f) i = f iupdTable (i,x) (Tbl f) = Tbl g where g j | j = i = x| otherwise = f j

> Chap. 15 642/135

Displaying Tables Represented as Functions

Using an instance-clause

instance Show (Table a b) where
showsPrec _ _ str = showString "<<A Table>>" str

8.4 643/135

The Abstract Data Type Table (3)
A user-invisible implementation of Table as a list:
<pre>newtype Table a b = Tbl [(b,a)]</pre>
newTable t = Tbl t
<pre>findTable (Tbl []) i = error "findTable: item not found" findTable (Tbl ((j,v):r)) i i==j = v otherwise = findTable (Tbl r) i</pre>
<pre>updTable e (Tbl []) = Tbl [e] updTable e'@(i,_) (Tbl (e@(j,_):r)) i==j = Tbl (e':r) otherwise = Tabl (e:r') where Tbl r' = updTable e' (Tbl r)</pre>

8.4

Chap. 15 644/135

Displaying Tables Represented as Lists

The easy way: Using a deriving-clause newtype Table a b = Tbl [(b,a)] deriving Show Advantages, disadavantages:

8.4

645/135

Cp. Chapter 8.1.

The Abstract Data Type Table (4)

The user-visible interface specification of the Abstract Data Type (ADT) Table for implementation as as Array:

module Table (Table,newTable,findTable,updTable)
where

newTable :: (Ix b) => [(b,a)] -> Table a b findTable :: (Ix b) => Table a b -> b -> a updTable :: (Ix b) => (b,a) -> Table a b -> Table a b

Note:

- The function newTable takes a list of (index,value) pairs and returns the corresponding table.
- The functions findTable and updTable are used to retrieve and update values in the table.

The Abstract Data Type Table (5)

A user-invisible implementation of Table as an Array:

newtype Table a b = Tbl (Array b a)

newTable 1 = Tbl (array (lo,hi) 1)
where indices = map fst 1
lo = minimum indices
hi = maximum indices

findTable (Tbl a) i = a ! i

updTable p@(i,x) (Tbl a) = Tbl (a // [p])

8.4 647/135

The Abstract Data Type Table (6)

Note:

The function newTable determines the boundaries of the new table by computing the maximum and the minimum key in the association list.

84

648/135

In the function findTable, access to an invalid key returns a system error, not a user error.
Displaying Tables Represented as Arrays

The easy way: Using a deriving-clause newtype Table a b = Tbl (Array b a) deriving Show Advantages, disadavantages: Cp. Chapter 8.1.

Chap. 14

8.4

Chap. 15 649/135

Chapter 8.5 Summing Up

8.5

Summing up

Benefits of using abstract data types:

- Information hiding: Only the interface is publicly known; the implementation itself is hidden. This offers:
 - Security of the data (structure) from uncontrolled or unintended/not admitted access.
 - Simple exchangeability of the underlying implementation (e.g. simplicity vs. performance).
 - Work-sharing of implementation.

There are many more implementations of data types in terms of an abstract data type. E.g.:

- Sets
- Heaps
- (Binary Search) Trees
- Arrays

• ...



Arrays: An Abstract Data Type

```
module Array (
       module Ix, -- export all of Ix for convenience
       Array, array, listarray (!), bounds, indices,
       elems, assocs, accumArray, (//),
       accum, ixmap ) where
import Ix
infixl 9 !, //
data (Ix a) => Array a b = ... -- Abstract
            :: (Ix a) \Rightarrow (a,a) \rightarrow [(a,b)] \rightarrow Array a b
array
                                                               85
listArray :: (Ix a) => (a,a) -> [b] -> Array a b
(!)
            :: (Ix a) => Array a b -> a -> b
bounds
            :: (Ix a) \Rightarrow Array a b (a,a)
            :: (Ix a) => Array a b -> [a]
indices
elems
            :: (Ix a) => Array a b -> [b]
            :: (Ix a) \Rightarrow Array a b \Rightarrow [(a,b)]
assocs
```

Arrays: An Abstract Data Type (Cont'd)

instance (Ix a, Eq b) => Eq (Array a b) where... instance (Ix a, Ord b) => Ord (Array a b) where... instance (Ix a, Show a, Show b) => Show (Array a b) where... instance (Ix a, Read a, Read b) => Read (Array a b) where... 8.5 653/135

Arrays: An Abstract Data Type (Cont'd)

See also:

 Simon Peyton Jones (Hrsg.). Haskell 98: Language and Libraries. The Revised Report. Cambridge University Press, 173-178, 2003.



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- Fethi Rabhi, Guy Lapalme. Algorithms A Functional Programming Approach. Addison-Wesley, 1999. (Chapter 5, Abstract Data Types)

85

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 (Chapter 16, Abstract data types)
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 (Chapter 16, Abstract data types)

85

Chapter 9 Monoids

Chap. 9

The Type Class Monoid

Monoids are instances of the type class Monoid:

```
class Monoid m where
 mempty :: m
 mappend :: m -> m -> m
 mconcat :: [m] -> m
 mconcat = foldr mappend mempty
```

...where the implementations of the monoid operations need to satisfy the so-called monoid laws.

Intuitively:

- A monoid is made up of an associative binary function mappend, and an element mempty that acts as an identity for with respect to the function mappend.
- The function mconcat takes a list of monoid values and reduces them to a single monoid value by using mappend.

Chap. 9 660/135

The Laws of Monoid

Members of the type class Monoid must satisfy the following three laws:

mempty 'mappend' $x = x$	(MoL1)
x 'mappend' mempty = x	(MoL2)
(x 'mappend'y) 'mappend'z =	
x 'mappend' (y 'mappend' z)	(MoL3)

Intuitively:

- The first two laws (MoL1) and (MoL2) require that mempty is the identity with respect to mappend.
- The third law (MoL3) requires that function mappend is associative.

Note:

It needs to be proven that these laws are satisfied by a concrete instance of class Monoid. This is a proof obligation for the programmer! Chap. 9 661/135

Remarks

Note:

- The element mempty can be considered a nullary function or a polymorphic constant.
- The name mappend is often misleading; for most monoids the effect of mappend cannot be thought in terms of "appending" values.
- Usually, it is wise to think of mappend in terms of a function that takes two m values and maps them to another m value.

Chap. 9 662/135

Examples: The List Monoid (1)

instance Monoid [a] where mempty = [] mappend = (++)

Examples:

[1,2,3] 'mappend' [4,5,6] ->> [1,2,3,4,5,6] "Advanced " 'mappend' "Functional " 'mappend' "Programming" ->> "Advanced Functional Programming" "Advanced " 'mappend' ("Functional " 'mappend' "Programming" ->> "Advanced Functional Programming") ("Advanced " 'mappend' "Functional ") 'mappend' "Programming" ->> "Advanced Functional Programming"

Chap. 9 663/135 Examples: The List Monoid (2) More Examples:

[1,2,3] 'mappend' mempty ->> [1,2,3]
mempty :: [a] ->> []

Note:

The monoid laws do not require commutativity of the binary operation mappend:

"Semester " 'mappend' "Holiday" ->> "Semester Holiday"

but

```
"Holiday " 'mappend' "Semester"
->> "Holiday Semester"
```

Chap. 9 664/135

Examples: The Product and Sum Monoids (1)

newtype Product a = Product { getProduct :: a }
deriving (Eq, Ord, Read, Show, Bounded)

newtype Sum a = Sum { getSum :: a }
deriving (Eq, Ord, Read, Show, Bounded)

```
instance Num a => Monoid (Product a) where
mempty = Product 1
Product x 'mappend' Product y = Product (x*y)
instance Num a => Monoid (Sum a) where
mempty = Sum 0
Sum x 'mappend' Sum y = Product (x+y)
```

```
Chap. 9
665/135
```

Examples: The Product and Sum Monoids (2) Examples:

getProduct \$ Product 3 'mappend' Product 7 ->> 21
getSum \$ Sum 17 'mappend' Sum 4 ->> 21

getProduct . mconcat . map Product \$ [3,7,11] ->> 231^{ap,11} getSum . mconcat . map Sum \$ [3,7,11] ->> 21

Product 3 'mappend' mempty ->> Product 3
getSum \$ mempty 'mappend' Sum 3 ->> 3

Chap. 9 666/135

Examples: The Any and All Monoids (1)

```
newtype Any = Any { getAny :: Bool }
  deriving (Eq, Ord, Read, Show, Bounded)
newtype All = All { getAll :: Bool }
  deriving (Eq, Ord, Read, Show, Bounded)
instance Monoid Any where
  mempty = Any False
  Any x 'mappend' Any y = Any (x || y)
    -- Any because True if any argument is true.
instance Monoid All where
  mempty = All True
  All x 'mappend' All y = All (x \&\& y)
    -- All because True if all arguments are true.
```

Chap. 9 667/135

```
Examples: The Any and All Monoids (2)
 Examples:
  getAny $ Any True 'mappend' Any False ->> True
 getAll $ All True 'mappend' All False ->> False
  getAny $ mempty 'mappend' Any False ->> False
 getAll $ All True 'mappend' mempty ->> True
                                                        Chap. 9
 getAny . mconcat . map Any $ [False,True,False,False]<sup>ap.10</sup>
     ->> True
 getAll . mconcat . map All $ [False,True,True,False]_Chap.13
     ->> False
```

Chap. 17

Remark

Note:

For the Product, Sum, Any, and All monoids the binary function mappend happens to be commutative, too. Chap. 9 669/135

Examples: The Ordering Monoid (1)

```
instance Monoid Ordering where
 mempty = EQ
 LT 'mappend' _ = LT
 EQ 'mappend' x = x
 GT 'mappend' _ = GT
```

Note:

- The definition of the binary function mappend leads to 'alphabetically' comparing lists of arguments.
- For the Ordering monoid the binary function mappend fails to be commutative:

LT 'mappend' GT ->> LT GT 'mappend' LT ->> GT Chap. 9 670/135 Examples: The Ordering Monoid (2) Example: The declaration lengthCompare :: String -> String -> Ordering lengthCompare x y = let a = length x 'compare' length y -- fst priority b = x 'compare' y -- snd priority in if a == EQ then b else a can equivalently be rewritten as lengthCompare :: String -> String -> Ordering lengthCompare x y = (length x 'compare' length y) 'mappend' (x 'compare' y)

by using the monoid properties.

Chap. 9 671/135

Examples: The Ordering Monoid (3)

As expected we get

lengthCompare "his" "ants" ->> LT

but

lengthCompare "his" "ant" ->> GT

Chap. 9 672/135

Examples: The Ordering Monoid (4)

Comparison criteria can easily be added and prioritisized.

E.g., the below extension of lengthCompare takes the number of vowels as the second most important comparison criteron:

lengthCompareExt :: String -> String -> Ordering
lengthCompareExt x y

'mappend' (x 'compare' y) -- thd priority
where vowels = length . filter ('elem' "aeiou")

As expected we get:

lengthCompareExt "his" "ancestors" ->> LT lengthCompare "his" "ancestors" ->> LT lengthCompare "his" "ant" ->> GT Chap. 9 673/135

Summing up (1)

Monoids are especially useful for defining

► folds over various data structures.

While this seems obvious for

lists

it also holds for many other data structures including

trees

and many others.

Chap. 9 674/135

Summing up (2)

This has led to the introduction of the type class Foldable (see module Data.Foldable):

class Foldable f where foldr :: (a -> b -> b) -> b -> f a -> b foldl :: (a -> b -> a) -> a -> f b -> a ...

whose fold operations generalize those on lists to foldable types, i.e., instances of the class Foldable:

foldr ::
$$(a \rightarrow b \rightarrow b) \rightarrow b \rightarrow [a] \rightarrow b$$

foldl :: $(a \rightarrow b \rightarrow a) \rightarrow a \rightarrow [b] \rightarrow a$

Chap. 9 675/135

Chapter 9: Further Reading

- Paul Hudak. The Haskell School of Expression Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 13.4.3, Defining New Type Classes for Behaviors)
- Miran Lipovača. Learn You a Haskell for Great Good! A Beginner's Guide. No Starch Press, 2011. (Chapter 12, Monoids)
- Bryan O'Sullivan, John Goerzen, Don Stewart. Real World Haskell. O'Reilly, 2008. (Chapter 13, Data Structures – Monoids)

Chap. 9 676/135

Chapter 10 Functors

Chap. 10

Outline

In Chapter 7 of LVA 185.A03 we were g	going
---------------------------------------	-------

from functions to higher-order functions

In this chapter we are going

from type classes to higher-order type classes

Chap. 4
Chap. 6
Chap. 7
Chap. 9
Chap. 10
10.1
10.2 10.3
10.4
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15
678/135

Chapter 9.1 Motivation

10.1

F

Funktionale Abstraktion höherer Stufe (1)		
(siehe Fethi Rabhi, Guy Lapalme. Algorithms - A Functional Approach, Addison-Wesley, 1999, S. 7f.)		Chap. 3 Chap. 4
Betrachte folgende Beispiele:		Chap. 5 Chap. 6
Fakultätsfunktion: fac n n==0 = 1 n>0 = n * fac (n-1)	Kap. 6 Kap. 7 Kap. 8 Kap. 9	Chap. 7 Chap. 8 Chap. 9
Summe der n ersten natürlichen Zahlen: natSum n n==0 = 0 n>0 = n + natSum (n−1)	Kap. 10 Kap. 11 Kap. 12 Kap. 13 Kap. 14	Chap. 10 10.1 10.2 10.3 10.4
Summe der n ersten natürlichen Quadratzahlen: natSquSum n n==0 = 0 n>0 = n*n + natSquSum (n-1)	Kap. 14 Kap. 15 Kap. 16 Kap. 17 Literatur	Chap. 11 Chap. 12 Chap. 13
	A1/873	Chap. 14

Funktionale Abstraktion höherer Stufe (2)

Beobachtung:

 Die Definitionen von fac, sumNat und sumSquNat folgen demselben Rekursionsschema.

Dieses zugrundeliegende gemeinsame Rekursionsschema ist gekennzeichnet durch:

- Festlegung eines Wertes der Funktion im
 - Basisfall
 - verbleibenden rekursiven Fall als Kombination des Argumentwerts n und des Funktionswerts für n-1

Chap. 4
Chap. 6
Chap. 7
Chap. 9
10.1
10.2
10.3
10.4
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15
681/135

Funktionale Abstraktion höherer Stufe (3)

Dies legt nahe:

 Obiges Rekursionsschema, gekennzeichnet durch Basisfall und Funktion zur Kombination von Werten, herauszuziehen (zu abstrahieren) und musterhaft zu realisieren.

Wir erhalten:

> Realisierung des Rekursionsschemas recScheme base comb n | n==0 = base | n>0 = comb n (recScheme base comb (n-1))

Contents
Chap. 1
Chap. 2
Chap. 3
Chap. 4
Chap. 5
Chap. 6
Chap. 7
Chap. 8
Chap. 9
Chap. 10
10.1
10.2
10.3
10.4
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15

682/135

		Chap. 1
Funktionale Abstraktion höherer Stufe (4)		Chap. 2
		Chap. 3
Funktionale Abstraktion höherer Stufe:		Chap. 4
fac n = recScheme 1 (*) n		Chap. 5
	Kap. 4	Chap. 6
natSum n = recScheme 0 (+) n	Kap. 5	Chap. 0
	Kap. 6	Chap. 7
natSquSum n = recScheme 0 (\x y -> x*x + y) n	Kap. 7	Chap. 8
nabbqubum n reebeneme o ((x y x x x y) n	Кар. 8 Кар. 9	Charle D
	Кар. 10	Chap. 9
Noch einfacher: In argumentfreier Ausführung	Kap. 11	Chap. 10
	Kap. 12	10.1 10.2
<pre>fac = recScheme 1 (*)</pre>	Kap. 13	10.2
	Kap. 14	10.4
natSum = recScheme 0 (+)	Kap. 15	Chap. 11
	Kap. 16	Chap. 12
natSquSum = recScheme 0 (\x y -> x*x + y)	Kap. 17	
	Literatur	Chap. 13
	1/873	Chap. 14
		Chap. 15
		2

Funktionale Abstraktion höherer Stufe (5)

Unmittelbarer Vorteil obigen Vorgehens:

- Wiederverwendung und dadurch
 - kürzerer, verlässlicherer, wartungsfreundlicherer Code

Erforderlich für erfolgreiches Gelingen:

Funktionen höherer Ordnung; kürzer: Funktionale.

Intuition: Funktionale sind (spezielle) Funktionen, die Funktionen als Argumente erwarten und/oder als Resultat zurückgeben.

Chap. 4
Chap. 6
Chap. 7
Chap. 9
10.1
10.2
10.3
10.4
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15
684/135
Recall "Kapitel 7, LVA 185.A03"

Funktionale Abstraktion höherer Stufe (6)

Illustriert am obigen Beispiel:

- Die Untersuchung des Typs von recScheme recScheme :: Int -> (Int -> Int -> Int) -> Int zeigt:
 - recScheme ist ein Funktional!

In der Anwendungssituation des Beispiels gilt weiter:

	Wert i. Basisf. (base)	Fkt. z. Kb. v. W. (comb)	Кар
fac	1	(*)	Кар
natSum	0	(+)	Кар
natSquSum	0	\x y -> x*x + y	Кар
			Kap

Chap. 4
Chap. 6
Chap. 7
Chap. 9
10.1
10.2
10.3
10.4
Chap. 11
Chap. 12
Chap. 12 Chap. 13

685/135

1/873

Let's switch to a slightly more complex example

The higher-order function map on

Lists mapList :: (a -> b) -> [a] -> [b] mapList g [] = []mapList g (l:ls) = g l : mapList g ls ► (Binary) Trees data Tree a = Leaf a | Node a (Tree a) (Tree a) mapTree :: (a -> b) -> Tree a -> Tree b mapTree g (Leaf v) = Leaf (g v) mapTree g (Node v l r) = Node (g v) (mapTree g l) (mapTree g r)

686/135

10.1

From Higher-Order Functions

...to Higher-Order Type Classes.

It is worth noting that the implementations of

- mapList
- ▶ mapTree

like the implementations of fac, natSum, and natSquSum are structurally similar, too.

This similarity suggests

striving for a function genericMap that covers mapList, mapTree, and more

...and leads us to the

• (type) constructor class Functor.

10.1

687/135

Chapter 10.2 Constructor Class Functor

688/135

10.2

The Constructor Class Functor

Functors are instances of the constructor class Functor:

class Functor f where fmap :: (a -> b) -> f a -> f b

...where the implementation of the functor operation fmap needs to satisfy the so-called functor laws.

Note:

- The argument f of Functor is applied to type variables. This means, f is not a type variable but a type constructor that is applied to the type variables a and b.
- Members of (type) constructor classes are type constructors, no types.
- The functor operation of an instance of Functor takes a polymorphic function g :: a -> b and yields a polymorphic function g' :: f a -> f b, e.g., g :: Int -> String, and g' :: Month Int -> Season String.

10.2 689/135

The Type Class Eq

For comparison recall the type class Eq:

Note:

- The argument a of Eq is a type variable. Functions declared in Eq operate on a; a itself operates on nothing.
- This holds as well for the other type classes we considered so far such as Ord, Num, Fractional, etc.

10.2 690/135

Constructor Classes vs. Type Classes

In principle, these are similar concepts but with different members.

- ► Constructor classes (Functor, Monad,...)
 - have type constructors (e.g., Tree, [], (,),...) as members.
- ► Type classes (Eq a, Ord a, Num a,...)
 - ▶ have types (e.g., Tree a, [a], (a, a), ...) as members.

Type constructors are

functions, which from given types construct new ones.

Examples: Tuple constructors (,), (,,), (,,,); List constructor []; Functional constructor ->; Input/output constructor IO,...

10.2 691/135

The Laws of Functor

Members of the constructor class Functor must satisfy the following two laws:

fmap id= id(FL1)fmap (g.h)= fmap g . fmap h(FL2)

Intuitively:

- ► The "shape of the container type" is preserved.
- The contents of the container is not regrouped.

Note:

It needs to be proven that these two laws are satisfied by a concrete instance of class Functor such as trees, lists, etc. This is a proof obligation for the programmer! 10.2 692/135

Lists and Trees as Instances of Functor (1)

instance Functor [] where
fmap g [] = []
fmap g (1:1s) = g 1 : fmap g 1s

instance Functor Tree where fmap g (Leaf v) = Leaf (g v) fmap g (Node v l r) = Node (g v) (fmap g l) (fmap g r)

Note:

- The symbol [] is used above in two roles, as a
 - ▶ type constructor in the line instance Functor [a] where...
 - ▶ value of some list type in the line fmap g [] = [].
- The declarations instance Functor [a] where... and instance Functor (Tree a) where... were incorrect, since [a] and (Tree a) are types, no type constructors.

10.2 693/135

Lists and Trees as Instances of Functor (2)

The next instance declarations are equivalent but more concise:

instance Functor [] where fmap = mapList -- user-defined mapList instance Functor [] where fmap = map -- predefined map instance Functor Tree where fmap = mapTree -- user-defined mapTree 10.2

694/135

Lists and Trees as Instances of Functor (3) **Applications:** t = Node 2 (Node 3 (Leaf 5) (Leaf 7)) (Leaf 11) fmap (*2) t ->> Node 4 (Node 6 (Leaf 10) (Leaf 14)) (Leaf 22) fmap (^3) t ->> Node 8 (Node 27 (Leaf 125) (Leaf 343)) (Leaf 1331) fmap (*2) [1..5] ->> [2,4,6,8,10] fmap (^3) [1..5] ->> [1,8,27,64,125]

695/135

10.2

The function fmap of constructor class Functor is
the function genericMap
that we were looking and striving for.
Members of the constructor class Functor can be both pre-defined and user-defined type constructors.

10.2 696/135

Predefined Type Constructors

Examples of predefined type constructors:

- \blacktriangleright (,), (, ,), (, , ,), etc.: constructors for tuple types
- []: constructor for list types
- ► (->): constructor for functional types

Chap. 4
Chap. 6
Chap. 7
Chap. 9
10.1
10.2
10.3 10.4
Chap. 11
Chap. 12
Chap. 13
Chap. 14
Chap. 15
697/135

Notational Remarks

The following notations are equivalent:

- (a,b) is equivalent to (,) a b
 (a,b,c) is eqivalent to (, ,) a b c, etc.
- [a] is equivalent to [] a
- f \rightarrow g is equivalent to (->) f g
- T a b is equivalent to ((T a) b) (i.e., associativity to the left as for function application)

Contents

Chap. 15

698/135

Illustration (1)

The signatures of the functions fac and list2pair

fac :: Int -> Int
fac 0 = 1
fac n = n * fac (n-1)
list2pair :: [a] -> (a,a)
list2pair (x : (y : _)) = (x,y)
list2pair (x : _) = (x,x)

10.2 699/135

Illustration (2)	
can equivalently be specified as follows:	
fac :: (->) Int Int	
list2pair :: [] a -> (a,a)	
list2pair :: [a] -> (,) a a list2pair :: (->) [a] (a,a)	
list2pair :: [] a -> (,) a a	
 list2pair :: (->) ([] a) ((,) a a)	Ch Ch
Nonetheless, more easily understandable (maybe only because we are more accustomed to) seem the "classical" variants:	

LO.1 LO.2 LO.3 700/135

More Examples: Maybe as Functor

```
data Maybe a = Nothing | Just a
```

instance Functor Maybe where fmap f (Just x) = Just (f x) fmap f Nothing = Nothing

Example:

fmap (++ "Programming") (Just "Functional")
 ->> Just "Functional Programming"

fmap (++ "Programming") Nothing
 ->> Nothing

10.2 701/135

```
More Examples: IO as Functor (1)
  instance Functor IO where
    fmap f action = do result <- action</pre>
                        return (f result)
 Example:
 main =
  do line <- fmap reverse getLine
     putStrLn $ "You said " ++ line' ++ " backwards!"
     putStrLn $ "Yes, you said " ++ line' ++ " backwards!"
 is equivalent to
                                                          10.2
 main =
  do line <- getLine
      let line' = reverse line
     putStrLn $ "You said " ++ line' ++ " backwards!"
     putStrLn $ "Yes, you said " ++ line' ++ " backwards [...
```

702/135

More Examples: IO as Functor (2)

import Data Chan	Contents
import Data.Char	Chap. 1
import Data.List	Chap. 2
main =	Chap. 3
	Chap. 4
do line <- fmap (intersperse '-' . reverse .	Chap. 5
map toUpper) getLine	Chap. 6
putStrLn line	Chap. 7
has the effect of	Chap. 8
has the effect of	Chap. 9
(\xs -> intersperse '-' (reverse (map toUpper xs)))	Chap. 10
	10.2 10.3
Applied to	10.4
helle theme	Chap. 11
hello there	Chap. 12
we get	Chap. 13
5	Chap. 14
E-R-E-H-TO-L-L-E-H	Chap. 15
	703/135

More Examples: Either as Functor (1)

data Either a b = Left a | Right b

Either has two type parameters. Hence, only (Either a) can be made an instance of Functor:

instance Functor (Either a) where fmap f (Right x) = Right (f x) fmap f (Left x) = Left x

Example:

```
fmap (length) (Right "Programming")
  ->> Right 11
```

```
fmap (length) (Left "Programming")
   ->> Left "Programming"
```

10.2 704/135

More Examples: Either as Functor (2)

Note that

instance Functor (Either a) where
fmap f (Right x) = Right (f x)
fmap f (Left x) = Left (f x)

would not be meaningful. Think about why not. Think about what this would mean for the types replaced for a and b.

10.2 705/135

An Antiexample (1)

```
Consider the type CounterMaybe
 data CounterMaybe a = CNothing
                         | CJust Int a deriving (Show)
and make it an instance of class Functor:
 instance Functor CounterMaybe where
  fmap f CNothing = CNothing
                                                         10.2
  fmap f (CJust counter x) = CJust (counter+1) (f x)
```

706/135

An Antiexample (2)

We get:

CNothing ->> CNothing CJust 0 "haha" ->> Cjust 0 "haha" CNothing :: CMaybe a CJust 0 "haha" :: CMaybe [Char] CJust 100 [1,2,3] ->> CJust 100 [1,2,3]

We also get:

```
fmap (++ "ha") (CJust 0 "ho")
   ->> CJust 1 "hoha"
fmap (++ "he") (fmap (++ "ha") (CJust 0 "ho")
   ->> CJust 2 "hohahe"
fmap (++ "blah") CNothing
   ->> CNothing
```

10.2 707/135

An Antiexample (3)	
However, we get	Contents Chap. 1
fmap id (CJust 0 "haha") ->> CJust 1 "haha"	Chap. 2 Chap. 3 Chap. 4
whereas	Chap. 5 Chap. 6
id (CJust 0 "haha") ->> CJust 0 "haha"	Chap. 7 Chap. 8 Chap. 9
	Chap. 10 10.1 10.2

- This shows that fmap defined for CounterMaybe violates the first Functor law: fmap id = id
- CounterMaybe can not be considered a valid instance of class Functor.

708/135

Summing up (1)

The constructor class Functor:

class Functor f where fmap :: (a -> b) -> f a -> f b

Laws of Functor:

fmap id = id
fmap (g.h) = fmap g . fmap h

(FL1) (FL2)

10.2 709/135

Summing up (2)

Some instance declarations:

instance Functor	Tree where
fmap g (Leaf v)) = Leaf (g v)
fmap g (Node v	l r)
= Node (g v)	(fmap g l) (fmap g r
instance Functor	[] where

fmap g [] = []
fmap g (l:ls) = g l : fmap g ls

10.2 710/135

Summing up (3)

More concise instance declarations:

instance Functor [] where
 fmap = mapList -- user-defined mapList

instance Functor [] where
fmap = map -- predefined map

instance Functor Tree where
 fmap = mapTree -- user-defined mapTree

10.2 711/135

Summing up (4)

Some applications of the Functor function fmap:

t = Node 2 (Node 3 (Leaf 5) (Leaf 7)) (Leaf 11) fmap (*2) t ->> Node 4 (Node 6 (Leaf 10) (Leaf 14)) (Leaf 22) fmap (^3) t ->> Node 8 (Node 27 (Leaf 125) (Leaf 343)) (Leaf 1331) fmap (3[^]) t ->> Node 9 (Node 27 (Leaf 243) (Leaf 2187)) (Leaf 177147) fmap (*2) [1..5] ->> [2,4,6,8,10] fmap (^3) [1..5] ->> [1,8,27,64,125]

fmap (3^) [1..5] ->> [3,9,27,81,243]

Chapter 10.3 Applicative Functors

10.3

Motivation

Comparing

data Either a b = Left a | Right b
and
(->) r l

suggests that

can be made an instance of class Functor just as

(Either a)

can be made.

 \rightsquigarrow This leads us to applicative functors, i.e., to functions as functors.

10.3 714/135

Functions as Functors (1)

instance Functor ((->) r) where fmap f g = ($x \rightarrow f (g x)$)

The type of fmap

fmap :: (Functor f) => $(a \rightarrow b) \rightarrow f a \rightarrow f b$

for this instance of Functor becomes

fmap :: (a \rightarrow b) \rightarrow ((\rightarrow) r a) \rightarrow ((\rightarrow) r b)

Using infix notation for -> this becomes:

fmap :: (a \rightarrow b) \rightarrow (r \rightarrow a) \rightarrow (r \rightarrow b)

10.3 715/135

Functions as Functors (2)

In effect, this means:

fmap f g = $(x \rightarrow f (g x))$

stands for function composition!

Hence, the instance definition can more concisely be given by:

instance Functor ((->) r) where
fmap = (.)

10.3 716/135

Functions as Functors (3)

Examples:

Main>:t fmap (*3) (+100) fmap (*3) (+100) :: (Num a) => a -> a

fmap (+3) (+100) 1 ->> 303

(*3) 'fmap' (+100) \$ 1 ->> 303 (*3) . (+100) \$ 1 ->> 303

fmap (show . (*3)) (+100) 1 ->> "303"

Note:

Calling fmap as an infix operation emphasizes the similarity of fmap and function composition.

10.3 717/135 fmap and Currying (1)

Reconsidering

fmap :: (Functor f) => $(a \rightarrow b) \rightarrow f a \rightarrow f b$ we get:

Main>:t fmap (*2) fmap (*2) :: (Num a, Functor f) => f a -> f b

```
Main>:t fmap (replicate 3)
fmap (replicate 3) :: (Functor f) => f a -> f [a]
```

This can be considered

lifting of an a -> b function to an f a -> f b function.

10.3 718/135

fmap and Currying (2)

This shows that fmap can be thought of in two ways:

- Uncurried: As a function that takes a function and a function value and then maps that function over the functor value.
- Curried: As a function that takes a function and lifts that function so it operates on functor values.

10.3 719/135

fmap and Currying (3)

Examples:

```
fmap (replicate 3) [1,2,3,4]
 ->> [[1,1,1],[2,2,2],[3,3,3],[4,4,4]]
fmap (replicate 3) (Just 4)
 ->> Just [4.4.4]
fmap (replicate 3) (Right "blah")
 ->> Right ["blah", "blah", "blah"]
fmap (replicate 3) Nothing
 ->> Nothing
fmap (replicate 3) (Left "foo")
 ->> Left "foo"
```

10.3 720/135
Towards Applicative Functors

Some Examples:

fmap (++) (Just "hey") :: Maybe ([Char] -> [Char]) fmap compare (Just 'a') :: Maybe (Char -> Ordering) Chap 5 fmap compare "A LIST OF CHARS" :: [Char -> Ordering]Chap.6 fmap ($x y z \rightarrow x + y / z$) [3,4,5,6] :: (Fractional a) => [a -> a -> a] let a = fmap(*) [1,2,3,4] a :: [Integer -> Integer] 10.3 fmap ($f \rightarrow f 9$) a \rightarrow [9,18,27,36]

The Type Constructor Class Applicative

Contents

Chap. 3 Chap. 4

hap. 5

Chap. 6

Chap. 7

Chap 8

Them 0

10.1 10.2 10.3 10.4

Chap. 11

Chap. 12

Chap. 13

Chap. 14

Chap. 15

Maybe as Applicative

```
instance Applicative Maybe where
pure = Just
Nothing <*> _ = Nothing
(Just f) <*> something = fmap f something
```

Examples:

```
Just (+3) <*> Just 9 ->> Just 12
Just (+3) <*> Just 10 ->> Just 13
```

```
Just (++ "hello") <*> Nothing ->> Nothing
Nothing <*> Just "hello" ->> Nothing
```

10.3 723/135

The Applicative Style

Examples:

pure (+) <*> Just 3 <*> Just 5 ->> 8
pure (+) <*> Just 3 <*> Nothing ->> Nothing
pure (+) <*> Nothing <*> Just 5 ->> Nothing

The operator (<*>) is left-associative:

```
pure (+) <*> Just 3 <*> Just 5 =
(pure (+) <*> Just 3) <*> Just 5
```

10.3 724/135

Defining an Infix Alias for fmap(1)

Note:

would be valid as well:

Type variables (like the f in the function declaration) are independent of parameter names (like the f in the function body) and other value names.

10.3 725/135

b

Defining an Infix Alias for fmap (2) Examples: (++) <\$> Just "Functional " <*> Just "Programming" ->> Just "Functional Programming" 10.3 726/135

Lists [] as Applicative (1)

```
instance Applicative [] where
  pure x = [x]
  fs <*> xs = [f x | f <- fs, x <- xs]</pre>
```

Examples:

pure "Hallo" :: String ->> ["Hallo"]
pure "Hallo" :: Maybe String ->> Just "Hallo"

10.3 727/135

Lists [] as Applicative (2)	
More Examples:	
[(*0),(+100),(^2)] <*> [1,2,3]	
->> [0,0,0,101,102,103,1,4,9]	
[(+),(*)] <*> [1,2] <*> [3,4]	Chap. 3 Chap. 4
->> [4,5,5,6,3,4,6,8]	
(++) <\$> ["ha","heh","hmm"] <*> ["?","!","."]	Chap. 6
->> ["ha?","ha!","ha.","heh?","heh!","heh.",	Chap. 7
"hmm?","hmm!","hmm."]	
Also list comprehension can be replaced this way:	Chap. 9 Chap. 10
[x*y x <- [2,5,10], y <- [8,10,11]] ->> [16,20,22,40,50,55,80,100,110]	10.1 10.2 10.3 10.4
(*) <\$> [2,5,10] <*> [8,10,11]	Chap. 11 Chap. 12
->> [16,20,22,40,50,55,80,100,110]	Chap. 12 Chap. 13
- , , , , , , , , , _	Chap. 14
filter (>50) \$ (*) <\$> [2,5,10] <*> [8,10,11]	Chap. 15
->> [55,80,100,110]	728/13

IO as Applicative (1)

instance Applicative IO where	
pure = return	
a < *> b = do f <- a	
x <- b	
return (f x)	
More Examples:	
myAction :: IO String	
	Chap. 10.1
myAction = do a <- getLine	10.2 10.3
b <- getLine	10.4
return \$ a++b	Chap.
	Chap.
myAction :: IO String	Chap.
<pre>myAction = (++) <\$> getLine <*> getLine</pre>	Chap.
	Chan

IO as Applicative (2)

main = do a <- (++) <\$> getLine <*> getLine putStrLn \$ "The concatenation of the two lines is: " ++ a

10.3 730/135

Functions (->) r as Applicative (1)

instance Applic	ative	((->)	r)	where
pure x = $(_$	-> x)			
f <*> g = \x	-> f x	(g x)	

Examples:

(+) <\$> (+3) <*> (*100) \$ 5 ->> 508

(\x y z -> [x,y,z]) <\$> (+3) <*> (*2) <*> (/2) \$ 5 ->> [8.0,10.0,2.5] Contents

10.3

Chap. 14

Chap. 15

Zip Lists as Applicative (1)

```
instance Applicative ZipList where
pure x = ZipList (repeat x)
ZipList fs <*> ZipList xs =
    ZipList (zipWith (\f x -> f x) fs xs)
```

Chap. 14 Chap. 15 (732/135

10.3

Zip Lists as Applicative (2)

Examples:

getZipList \$ (+) <\$> ZipList [1,2,3] <*> ZipList [100,100,100] ->> [101,102,103] getZipList \$ (+) <\$> ZipList [1,2,3] <*> ZipList [100,100..] ->> [101,102,103] getZipList \$ max <\$> ZipList [1,2,3,4,5,3] <*> ZipList [5,3,1,2] ->> [5.3.3.4] getZipList \$ (,,) <\$> ZipList "dog" <*> ZipList "cat" <*> ZipList "rat" ->> [('d','c','r'),('o','a','a'),('g','t','t')]

10.3 733/135

The Laws of Applicative

Members of the constructor class Applicative must satisfy the following laws:

pure id $\langle * \rangle v = v$ (AL1)

pure (.) <*> u <*> v <*> w = u <*> (v <*> w) (AL2) pure f <*> pure x = pure (f x) (AL3)

 $u \iff pure y = pure (\$ y) \iff u$ (AL4)

10.3

Useful Functions for Applicative (1)

Examples:

10.3 735/135

Useful Functions for Applicative (2)

sequenceA :: (Applicative f) => [f a] -> f [a] sequenceA [] = pure [] sequenceA (x:xs) = (:) <\$> x <*> sequenceA xs

sequenceA :: (Applicative f) => [f a] -> f [a] sequenceA = foldr (liftA2 (:)) (pure [])

10.3 736/135

Chapter 10.4 Kinds of Types and Type Constructors

10.4 737/135

Kinds of Types and Type Constructors

Like values	
	Chap. 4
 types and 	
► type constructors	Chap. 6
	Chap. 7
have types, too.	
	Chap. 9
These types are called	Chap. 10 10.1
These types are called	10.2
► kinds.	10.4
 Kilds. 	Chap. 11
	Chap. 12
	Chap. 13
	Chap. 14
	Chap. 15

Kinds of Types

In GHCi, kinds of types (and type constructors) can be computed and displayed using the command ":k":

```
ghci> :k Int
Int :: *
ghci> :k (Char,String)
Int :: (*.*)
ghci> :k [Float]
[Float] :: [*]
ghci> :k (->)
(->) :: * -> * -> *
```

where * (read as "star" or as "type") indicates that the type is a concrete type.

10.4 739/135

Type Constructors

Type constructors

 take types as parameters to eventually produce concrete types.

Example:

The type constructors Maybe, Either, and Tree

```
data Maybe a = Nothing | Just a
data Either a b = Left a | Right b
data Tree a = Leaf a | Node a (Tree a) (Tree a)
```

produce for a and b chosen to be Int and String, respectively, the concrete types

Maybe Int Either Int String Tree Int

```
10.4
740/135
```

Kinds of Type Constructors

Like concrete types

► type constructors have types, called kinds, as well.

ghci> :k Maybe Maybe :: * -> * ghci> :k Either Either :: * -> * -> * ghci> :k Tree Tree :: * -> * ghci> :k (->) (->) :: * -> * -> *

10.4 741/135

Kinds of Partially Applied Type Constructors

Like functions

also type constructors can be partially applied.

ghci> :k Either Int
Either Int :: * -> *

ghci> :k Either Int String
Either Int String :: *

Contents Chap. 1 Chap. 2 Chap. 3 Chap. 4 Chap. 5 Chap. 6 Chap. 7 Chap. 2

Chap. 9

10.1 10.2 10.3

10.4

Chap. 11

Chap. 12

Chap. 13

Chap. 14

Chap. 15

Type Constructors as Functors

Reconsidering the definition of type class Functor

class Functor f where fmap :: (a -> b) -> f a -> f b

it becomes obvious that only

► type constructors of kind * -> *

can be members of type class Functor.



Chapter 10: Further Reading (1)

- Paul Hudak. The Haskell School of Expression: Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 18.1, The Functor Class)
- Miran Lipovača. Learn You a Haskell for Great Good! A Beginner's Guide. No Starch Press, 2011. (Chapter 7, Making Our Own Types and Type Classes – The Functor Type Class; Chapter 11, Applicative Functors)
- Bryan O'Sullivan, John Goerzen, Don Stewart. Real World Haskell. O'Reilly, 2008. (Chapter 10, Code Case Study: Parsing a Binary Data Format – Introducing Functors, Writing a Functor Instance for Parse, Using Functors for Parsing)

10.4

Chapter 10: Further Reading (2)

- Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer-V., 2006. (Kapitel 11.1, Kategorien, Funktoren und Monaden)
- Fethi Rabhi, Guy Lapalme. Algorithms A Functional Programming Approach. Addison-Wesley, 1999. (Chapter 2.8.3, Type classes and inheritance)

10.4 745/135

Chapter 11 Monads

Chap. 14 746/135

Chap. 11

Contents

Motivation

Monads – A mundane approach for composing functions, for functional composition!
The monad approach succeeds in
 linking and composing functions
whose types are incompatible and thus inappropriate to allow their
 simple functional composition.

Chap. 12

Chap. 11

Chap. 13

Chap. 14 747/135

Monads: A Suisse Knife for Programming

Monadic programming works well for problems involving:

- Global state
 - Updating data during computation is often simpler than making all data dependencies explicit (State Monad).
- Huge data structures
 - No need for replicating a data structure that is not needed otherwise.
- Side-effects and explicit evaluation orders
 - Canonical scenario: Input/output operations (IO Monad).
- Exception and error handling
 - Maybe Monad

Chap. 11

Chap. 13

Illustration

Consider:

a-b -- Evaluation order of a and b is not -- fixed. This is crucial, if input/output -- is involved.

Monads

 allow us to explicitly specify the order, in which operations are applied; this way, they bring an imperative flavour into functional programming.

do a <- getInt -- Evaluation order is
 b <- getInt -- explicitly fixed:
 return (a-b) -- first a, then b.</pre>

Chap. 11 749/135

Chapter 11.1 Motivation

Chap. 13 Chap. 14 750/135

11.1

Setting the Stage

Consider:

- f :: a -> b
- g :: b -> c

Functional composition for f and g works perfectly:

$$(g . f) = g (f v)$$

where

Contents Chap. 1 Chap. 2 Chap. 3 Chap. 4 Chap. 5 Chap. 6 Chap. 7

Chap. 9

Chap. 10

11.1 11.2 11.3 11.4

1.6

Chap. 12

Chap. 13

Chap. 14 751/135

Case Study "Debugging" (1)

Objective:

Empowering f and g such that debug-information in terms of a string is collected and output during computation.

To this end, replace ${\tt f}$ and ${\tt g}$ by two new functions ${\tt f}$ ' and ${\tt g}$ ':

```
type DebugInfo = String
```

f' :: a -> (b,DebugInfo)
g' :: b -> (c,DebugInfo)

Unfortunately:

f' and g' cannot be composed easily: Simple functional composition does not work any longer because of incompatible argument and result types of f' and g'. 11.1

Case Study "Debugging" (2)

The below *ad hoc* composition works:

...but were impractical in practice as it continuously required implementing new specific composition operations.

11.1 753/135 Case Study "Debugging" (3)

Towards a more systematic approach:

• Define a new "link" function.

(gResult,gInfo) = g v in (gResult,s++gInfo)

The function link allows us to compose f' and g' comfortably again:

h' v = f' v 'link' g'

11.1

Making it Practical: link, unit, lift

Introduce a new identity function that is a unit for link, and a new lift function that makes each function working with link:

```
unit v = (v,"")
lift f = unit . f
```

The functions link, unit, and lift can now be applied in concert.

Example:

We obtain:

h 5 ->> (5, "f called. g called. done.") Note that functions are applied "left to right" as desired. 11.1 755/135

Case Study "Random Numbers" (1) The library Data.Random provides a function random :: StdGen -> (a,StdGen)

for computing (pseudo) random numbers.

Ordinary functions can use random numbers, if they can (additionally) manage a value of type StdGen that can be used by the next operation to generate a random number:

Problem:

- How to compose functions f and g?
 - f :: a -> StdGen -> (b,StdGen)
 - g :: b -> StdGen -> (c,StdGen)

11.1 756/135
Case Study "Random Numbers" (2)	
An <i>ad hoc</i> composition:	
h :: a -> StdGen -> (c,StdGen)	
h v gen = let	
(fResult,fGen) = f v gen in g fResult fGen	Chap. 4
More appropriate:	
The trio of functions link, unit, lift.	
link :: (StdGen -> (a,StdGen)) ->	Chap. 9 Chap. 10
(a -> StdGen -> (b,StdGen)) ->	Chap. 11
StdGen -> (b,StdGen)	11.1 11.2
link :: g f gen = let (v,gen') = g gen in f v gen'	11.3 11.4
	11.5 11.6
unit v gen = (v,gen)	11.7 Chap. 12
lift f = unit . f	Chap. 13
	Chap 14

Chap. 14 757/135

Quintessence

The previous examples enjoya common structure.
This common structure can be encapsulated in a▶ new (type) constructor class.
This type class will be the (constructor) class ▶ Monad.

Chap. 13

11.1

Chap. 14 758/135

Prospect: The Constructor Class Monad

data Debug a = D (a,String) data Random a = R (StdGen -> (a,StdGen) class Monad m where -- link (>>=) :: m a -> (a -> m b) -> m b -- link but ignore the result component of the -- first function (>>) :: m a -> m b -> m b -- neutral element wrt (>>=) return :: a -> m a fail :: String -> m a -- default implementation $m \gg k = f \gg = -> k$ fail = error

759/135

11.1

Prospect: Instance Declaration for Random

The instance declaration for type constructor Random:

instance Monad Random where $(R m) \gg f = R$ \gen -> (let (a,gen') = m gen (R b) = f a in b gen')= R \gen -> (x,gen) return x 11.1 760/135

Chapter 11.2 Constructor Class Monad

11.2

Chap. 14 761/135

The Constructor Class Monad

Monads are instances of the constructor class Monad:



...where the implementations of the monad operations (>>=),
(>>), return, fail must satisfy the so-called monad laws.

Chap. 14 762/135

The Laws of Monad

Members of the constructor class Monad must satisfy the following three laws:

return a >>= f = f a
$$(ML1)$$

$$c >>= return = c$$
 (ML2

$$c \rightarrow (x \rightarrow (f x) \rightarrow g) = (c \rightarrow f) \rightarrow g (ML3)$$

Intuitively:

- return passes the value without any other effect; return is unit of (>>=).
- sequencings given by (>>=) do not depend on how they are bracketed; (>>=) is associative.

Note:

It needs to be proven that these laws are satisfied by a concrete instance of class Monad such as trees, lists, etc. This is a proof obligation for the programmer! 11.2 763/135

The Laws of Monad in Terms of (>@>) (1)

The derived operation (>@>) makes the intuitive meaning of the monad laws more obvious; i.e. as obvious as associativity is for the (>>) operation:

$$c1 >> (c2 >> c3) = (c1 >> c2) >> c3$$

(Note: Associativity of (>>) is implied by that of (>>=).)

The operation (>0>) is defined by:

11.2

Chap. 13

The Laws of Monad in Terms of (>@>) (2)

The monad laws in terms of (>@>):

return $>0> f = f$	(ML1')
f >0> return = f	(ML2')
(f >0> g) >0> h = f >0> (g >0> h)	(ML3')

Intuitively

- ► (ML1'), (ML2'): return is unit of (>@>).
- ► (ML3'): (>@>) is associative.

Note: As mentioned before, the above properties need to ensured by the instance declaration. They do not hold *per se*.

11.2

765/135

Syntactic Sugar: The do-Notation

Monadic operations

allow to specify the sequencing of operations explicitly.

This introduces

► an imperative flavour into functional programming.

The syntactic sugar of the so-called

do-notation

makes this flavour more explicit.



Chap. 12

Chap. 13

Chap. 14 766/135

do-Notation: A Useful Notational Variant (1)

The do-notation makes composing monadic operations syntactically more concise.

Four transformation rules

 allow to convert compositions of monadic operations into equivalent (<=>) do-blocks and vice versa.

767/135

do-Notation: A Useful Notational Variant (2)

A special case of the "pattern rule" (R4):

Remarks:

- (R2): If the return value of an operation is not needed, it can be moved to the front.
- (R3): A let-expression storing a value can be placed in front of the do-block.
- (R4): Return values that are bound to a pattern, require a supporting function that handles the pattern matching and the execution of the remaining operations, or that calls fail, if the pattern matching fails.

Note: It is rule (R4) that necessitates fail as a monadic operation in Monad. Overwriting this operation allows a monad-specific exception and error handling.

11.2 768/135

Illustrating the do-Notation

...using the monad laws as example.

- ► The monad laws using the monadic operations: return a >>= f = f a $(ML1)^{Chap. 5}_{Chap. 6}$ c >>= return = c $(ML2)^{Chap. 7}_{Chap. 7}$ c >>= $(\x -> (f x) >>= g) = (c >>= f) >>= g (ML3)^{Chap. 8}_{Chap. 8}$
- The monad laws using the do-notation:
 - do x <- return a; f x = f a $(ML1)_{111}^{Chap.11}$ do x <- c; return x = c $(ML2)_{113}^{112}$ do x <- c; y <- f x; g y = 115do y <- (do x <- c; f x); g y $(ML3)_{117}^{116}$

Chap. 12

Chap. 13

Chap. 14 769/135

Quintessence: The Constructor Class Monad



770/135

Quintessence: Monadic Operations

Intuitively

- (>>=): The sequence operator (read as then (according to Simon Thompson) or bind (according to Paul Hudak)), or – maybe – as link.
- return: Returns a value w/out any other effect.
- (>>): From (>>=) derived sequence operator (read as sequence (according to Paul Hudak)).
- fail: Exception and error handling.

Useful Supporting Functions for Monads

sequence :: Monad m => [m a] -> m [a] = foldr mcons (return []) sequence where mcons pq = do l < -pls <- q return (1:1s) sequence_ :: Monad $m \Rightarrow [m a] \rightarrow m$ () sequence_ = foldr (>>) (return ()) mapM :: Monad $m \Rightarrow (a \rightarrow m b) \rightarrow [a] \rightarrow m [b]$ mapM f as = sequence (map f as) $mapM_{-}$:: Monad m => (a -> m b) -> [a] -> m () mapM_ f as = sequence_ (map f as) (=<<) :: Monad m => $(a \rightarrow m b) \rightarrow m a \rightarrow m b$ f = << x = x >>= f

> Chap. 14 772/135

11.2

A Law linking Classes Monad and Functor

Type constructors that are an instance of both

class Monad and class Functor

must satisfy the law:

11.2 773/135

(MFL)

Chapter 11.3 Predefined Monads

11.7 Chap. 12 Chap. 13 Chap. 14 774/135

11.3

Predefined Monads

A selection of	predefined	monads	in	Has	kell:
----------------	------------	--------	----	-----	-------

► Id	entity	monad	
------	--------	-------	--

- List monad
- Maybe monad
- State monad

Chap. 4
Chap. 6
Chap. 7
Chap. 9
Chap. 11
11.1 11.2
11.3
11.4
11.5 11.6
11.7
Chap. 12
Chap. 13
Chap. 14 775/135

The Identity Monad (1)

The identity monad, conceptually the simplest monad:

newtype Id a = Id a

instance Monad Id where
 (Id x) >>= f = f x
 return = Id

Note:

 (>>) and fail are implicitly defined by their default implementations.



The Identity Monad (2)

Remarks:

- The identity monad maps a type to itself.
- It represents the trivial state, in which no actions are performed, and values are returned immediately.
- It is useful because it allows to specify computation sequences on values of its type.
- The operation (>@>) becomes for the identity monad forward composition of functions, i.e., (>.>):

 Forward composition of functions (>.>) is associative with unit id. 11.3 777/135

The List Monad (1)

The list monad:

```
instance Monad [] where
  xs >>= f = concat (map f xs)
  return x = [x]
  fail s = []
```

where concat is from the Standard Prelude:

```
concat :: [[a]] -> [a]
concat lss = foldr (++) [] lss
```

11.3 778/135

The List Monad (2)

The list monad can equivalently be defined by:

instance Monad [] where
 (x:xs) >>= f = f x ++ (xs >>= f)
 [] >>= f = []
 return x = [x]
 fail s = []

Note:

For the list monad the monadic operations (>>=) and return have the types:

Contents

11.3

779/135

The List Monad (3)

The list monad is closely related to list comprehension:

Hence, the following notations are equivalent:

List comprehension is syntactic sugar for monadic syntax!

11.3 780/135 List comprehension: Syntactic sugar for monadic syntax.

We have:

[f x | x <- xs] <=> do x <- xs; return (f x)
[a | a <- as, p a] <=>
 do a <- as; if (p a) then return a else fail ""</pre>

11.3

781/135

The Maybe Monad (1)	
The Maybe monad: data Maybe a = Nothing Just a	
<pre>instance Monad Maybe where (Just x) >>= k = k x Nothing >>= k = Nothing return = Just fail s = Nothing</pre>	Chap. 4 Chap. 5 Chap. 6 Chap. 7 Chap. 8 Chap. 9
 Remark: The Maybe monad is useful for computation (sequences) that might produce a result, but might also produce an 	Chap. 10 Chap. 11 11.1 11.2 11.3 11.4 11.5 11.6 11.7

error.

Chap. 12

Chap. 13

The Maybe Monad (2)

For the Maybe monad the monadic operations (>>=) and return have the types:

(>>=) :: Maybe a -> (a -> Maybe b) -> Maybe b return :: a -> Maybe a

The Maybe type is also a predefined member of the Functor class:

instance Functor Maybe where
fmap f Nothing = Nothing
fmap f (Just x) = Just (f x)

11.3 783/135

The Maybe Monad (3)

Composing functions like

f	::	${\tt Int}$	->	${\tt Int}$
g	::	${\tt Int}$	->	${\tt Int}$
x	::	Tnt		

in g (f x) while assuming that the evaluation of f and g may fail, is possible by embedding the computation into the Maybe type:

```
case (f x) of
Nothing -> Nothing
Just y -> case (g y) of
Nothing -> Nothing
Just z -> z
```

Though possible, this is "inconvenient."

11.3 784/135

The Maybe Monad (4)

Embedding gets a lot easier by exploiting the membership of the Maybe type in the Maybe monad:

f x >>=
$$y \rightarrow g y >>= z \rightarrow return z$$

which is equivalent to:

...the "nasty" error check is "hidden" in the Maybe monad.

11.3

785/135

The Maybe Monad (5)

Note that

f x >>=
$$y \rightarrow g y >>= z \rightarrow return z$$

can also be simplified to:

This way, g(f x) gets f x >>= g.

11.3 786/135

The Maybe Monad (6)

Another possibility to better cope with $(g \, . \, f) \, x$ were to introduce the function:

Note:

Both this and the previous handling of embedding the function composition of g and f into the Maybe type preserve the original notation of composing g and f in an almost 1-to-1 kind. 11.3 787/135

The State Monad (1)

Objective:

- Modelling of programs with global (internal) state and side effects by means of
 - functions that applied to an initial state yield a final state as part of the overall result of the compution.

	Chap. 6	
The (resp. a) state monad:		
newtype State s a = St (s -> (s,a))	Chap. 8	
••	Chap. 9	
instance Monad (State s) where	Chap. 10	
return x = St ($s \rightarrow (s,x)$) The identity	Chap. 11	
(St m) >>= f = on states!	11.1 11.2 11.3	
St (\s -> let (s1,x) = m s $$ m applied to	11.5	
St f' = f x $$ s yields s1	11.6 11.7	
in f's1) and x to which	Chap. 12	
then f is	Chap. 13	
applied to.	Chap. 14 788/135	

The State Monad (2)

Intuitively

State transformers

- model and transform global (internal) states.
- ► are (in this setting) mappings of the type s → (s,a).
- map an initial state to a pair consisting of a (possibly modified) final state and another result component of type a.

11.3 789/135

The State Monad (3)

A slightly different definition of the state monad for S some suitable type:

```
data SM a = SM (S \rightarrow (S,a))
instance Monad SM where
  return a
     = SM (\s -> (s,a))
  SM smO >>= fsm1
     = SM $ \s0 ->
         let (s1,a1) = sm0 s0
              SM sm1 = fsm1 a1
              (s2,a2) = sm1 s1
          in (s2.a2)
```

11.3 790/135

Predefined Monads

There are many more predefined monads in Haskell:

Writer monad
Reader monad
Failure monad
Input/output monad

Chap. 12

11.3

Chap. 13

Chap. 14 791/135 The Input/Output Monad (1)

The IO monad:

```
instance Monad IO where (>>=) :: IO a -> (a -> IO b) -> IO b return :: a -> IO a
```

Intuitively:

- (>>=): If p and q are commands, then p >>= q is the command that first executes p, yielding thereby the return value x of type a, and then executes q x, thereby yielding the return value y of type b.
- return: Generates a return value w/out any input/output action.

```
11.3
```

792/135
The Input/Output Monad (2)

It is worth noting:

The IO monad is similar in spirit to the state monad: It passes around the "state of the world." In more detail: For a given suitable type World whose values represent the current state of the world the notion of an interactive program, i.e., an IO-program, can be represented by a function of type ► World -> World which may be abbreviated as: type IO = World -> World

11.3 793/135

The Input/Output Monad (3)

In general:

Interactive programs do not only modify the state of the world but may also return a result value, e.g., echoing a character that has been read from a keyboard.

This suggests to change the type of interactive programs to

```
type IO = World -> (a, World)
```

11.3 794/135

Chapter 11.4 Constructor Class MonadPlus

11.4 795/135

The Monad MonadPlus

... for members of Monad with Null and Plus operation:

11.4

796/135

class Monad m => MonadPlus m where
 mzero :: m a
 mplus :: m a -> m a -> m a

The Laws of MonadPlus

Members of the constructor class MonadPlus must satisfy in addition to the monad laws laws for the Null and Plus operations:

Two laws for the Null operation:

m >>= ($x \rightarrow$ mzero)	= mzero	(MPL1)
mzero >>= m	= mzero	(MPL2)

Two laws for the Plus operation:

m 'mplus' mzero = m
mzero 'mplus' m = m

Note:

As for Functor and Monad, proving the validity of the above laws for an instance of class MonadPlus is a proof obligation for the programmer. 11.4 797/135

(MPL3)

(MPL4)

Instances of MonadPlus

Instance declarations for the Maybe and [] types for the class MonadPlus:

instance MonadPlus Maybe where		
mzero	= Nothing	
Nothing 'mplus' y	s = ys	
xs 'mplus' ys = xs		
instance MonadPlus	[] where	
mzero = []		
mplus = (++)		

Note:

- List concatenation (++) is a special case of the mplus operation.
- IO is not an instance of MonadPlus because of the missing null element.

11.4 798/135

Chapter 11.5 Monadic Programming

11.6 11.7 Chap. 12 Chap. 13 Chap. 14 799/135

11.5

Outline

We will consider three case studies for illustration:

- Case study I: Summing labels of a tree.
- Case study II: Replacing the leaf labels of a tree by leaf labels of another type.
- Case study III: Replacing the labels of a tree by the number of occurrences of this label in the tree.

11.5 800/135

Case Study I

Given:

data Tree a = Nil | Node a (Tree a) (Tree a)

Objective:

 Write a function that computes the sum of the values of all labels of a tree of type Tree Int.

Means:

Opposing two different functional approaches:

- ► A classical functional approach w/out monads
- ► A functional approach w/ monads.

11.5 801/135

Illustration



11.5

Chap. 12

Chap. 13

Chap. 14 802/135

A Functional Approach w/out Monads

1st Approach: No monads sTree :: Tree Int -> Int sTree Nil = 0 sTree (Node n t1 t2) = n + sTree t1 + sTree t2

Note:

The order of the evaluation is not fixed (degrees of freedom!)

11.5 803/135

A Functional Approach w/ Monads

```
2nd Approach: Using the identity monad Id
 sumTree :: Tree Int -> Id Int
 sumTree Nil = return 0
 sumTree (Node n t1 t2) = do num <- return n
                                    <- sumTree t1
                                s1
                                s2 <- sumTree t2
                                return (num + s1 + s2)
Note:
  The order of the evaluation is explicitly fixed (no degrees
                                                           11.5
    of freedom!)
```

Chap. 14 804/135

The Identity Monad

Recall the identity monad:

data Id a = Id a

instance Monad Id where
 (>>=) (Id x) f = f x
 return = Id

11.5

805/135

Opposing the Two Approaches

Comparing the two approaches w/ and w/out monads, we observe:

Unlike sTree, function sumTree has an "imperative" flavour very similar to the sequential sequence of (imperative) assignments:

Imperative

```
Monadic
```

num	:= n;	do	num	<-	return n
s1	:= sumTree t1;		s1	<-	sumTree t1
s2	:= sumTree t2;		s2	<-	sumTree t2
retu	urn (num + s1 + s2)	;	retu	ırn	(num + s1 + s2)

```
11.5
```

806/135

Another Functional Approach w/ Monads	
3rd Approach: Using monad Id and an extraction function	
extract :: Id a -> a extract (Id x) = x	
Using extract we get a function of type Tree Int -> Int:	Chap. 4 Chap. 5
extract . sumTree :: Tree Int -> Int	Chap. 6
	Chap. 7 Chap. 8
Example:	
(extract . sumTree)	
(Node 5 (Node 3 Nil Nil) (Node 7 Nil Nil)) ->>	Chap. 11 11.1 11.2 11.3
extract (sumTree (Node 5 (Node 3 Nil Nil) (Node 7 Nil Nil)))	11.5 11.4 11.5 11.6 11.7
->>	Chap. 12
extract (Id 15) ->> 15	Chap. 13 Chap. 14
->> extract (sumTree (Node 5 (Node 3 Nil Nil) (Node 7 Nil Nil)))	11.1 11.2 11.3 11.4 11.5 11.6 11.7 Chap. 12 Chap. 13

Case Study II

Given:

data Tree a = Leaf a | Branch (Tree a) (Tree a)

Objective:

 Replace the labels of the leafs that are supposed to be of type Char by continuous natural numbers. 11.5 808/135

Illustration



Chap. 14 809/135

11.5

A Functional Approach w/out Monads 1st Approach: No monads label :: Tree a -> Tree Int label t = snd (lab t = 0) lab :: Tree a -> Int -> (Int, Tree Int) lab (Leaf a) n = (n+1, Leaf n) lab (Branch t1 t2) n = let (n1,t1') = lab t1 n (n2.t2') = lab t2 n1in (n2, Branch t1', t2')

Note:

Simple but passing the value n through the incarnations of lab is "intricate." 11.5 810/135 A Functional Approach w/ Monads (1) 2nd Approach: Using the state monad newtype Label a = Label (Int -> (Int,a)) ... "matches" the pattern of the state monad SM. We define: instance Monad Label where return a = Label ($\s \rightarrow$ (s,a)) Label $|t0 \rangle = f|t1$ = Label \$ \s0 -> let (s1,a1) = 1t0 s0Label lt1 = flt1 a1 in lt1 s1 Note: The - operator in the definition of >= can be dropped, if

the expression $s0 \rightarrow let \dots$ in lt1 s1 is bracketed.

11.5 811/135

A Functional Approach w/ Monads (2)	
This allows solving the renaming of labels as follows:	
<pre>mlabel :: Tree a -> Tree Int mlabel t = let Label lt = mlab t</pre>	Chap. 1 Chap. 2 Chap. 3 Chap. 4
<pre>mlab :: Tree a -> Label (Tree Int) mlab (Leaf a)</pre>	Chap. 5 Chap. 6 Chap. 7 Chap. 8
return (Leaf n) mlab (Branch t1 t2)	Chap. 9 Chap. 10
= do t1' <- mlab t1 t2' <- mlab t2 return (Branch t1' t2')	Chap. 11 11.1 11.2 11.3 11.4 11.5 11.6
getLabel :: Label Int getLabel = Label (\n -> (n+1,n))	11.7 Chap. 12 Chap. 13 Chap. 14 812/135

A Functional Approach w/ Monads (3)

Let **mtest** be defined by

Then we get:

mlabel applied to Branch (Leaf 'a') (Leaf 'b') yields as desired: Branch (Branch (Leaf 0) (Leaf 1)) (Branch (Leaf 2) (Leaf 3))



Case Study III

Given:

data Tree a = Nil | Node a (Tree a) (Tree a)

Objective:

 Replace labels of equal value that are supposed to be of type String by the same natural number. 11.5 814/135

Illustration



- Chap. 12
- Chap. 13
- Chap. 14 815/135

A Functional Approach w/ Monads (1) Ultimate Goal: A function numTree of type numTree :: Eq a => Tree a -> Tree Int solving this task with monadic programming using the state monad. In order to eventually arrive at this function we start with: numberTree :: Eq a => Tree a -> State a (Tree Int) numberTree Nil = return Nil numberTree (Node x t1 t2) = do num <- numberNode x nt1 <- numberTree t1 nt2 <- numberTree t2 return (Node num nt1 nt2)

11.5 816/135

A Functional Approach w/ Monads (2) Next, we are storing pairs of the form

(< string>, < number of occurrences>)

in a table of type:

type Table a = [a]

In particular:

The table

[True, False]

encodes that the value True is associated with 0 and False with 1.

11.5 817/135 A Functional Approach w/ Monads (3) Defining the state monad we consider: data State a b = State (Table a -> (Table a, b)) instance Monad (State a) where (State st) >>= f= State (\tab -> let (newTab,y) = st tab (State trans) = f y in trans newTab) return x = State ($tab \rightarrow (tab,x)$)

Intuitively:

- Values of type b: Result of the monadic operation.
- Update of the table: Side effect of the monadic operation.

11.5 818/135 A Functional Approach w/ Monads (4) Defining the missing function numberNode: numberNode :: Eq a => a -> State a Int numberNode x = State (nNode x) nNode :: Eq a => a -> (Table a -> (Table a, Int)) nNode x table | elem x table = (table, lookup x table) otherwise = (table++[x], length table) -- nNode yields the position of x in the table: -- via lookup, if stored in the table; after -- adding x to the table via length otherwise 11.5 lookup :: Eq a => a -> Table a -> Int lookup ... (still to complete)

Chap. 12 Chap. 13 Chap. 14 819/135

A Functional Approach w/ Monads (5)

Putting the pieces together, we get for exampleTree :: Eq a => Tree a:

numberTree exampleTree :: State a (Tree Int)

Using an extraction function we get now the desired implementation of the function numTree of type numTree :: Eq a => Tree a -> Tree Int:

```
extract :: State a b -> b
extract (State st) = snd (st [])
```

```
numTree :: Eq a => Tree a -> Tree Int
numTree = extract . numberTree
```

11.5 820/135

Chapter 11.6 Monadic Input/Output

11.6

Chap. 14 821/135

Handling Input/Output so Far

The programs we considered so far, handle input/ouput monolithicly, in a way that resembles

batch processing.



Peter Pepper. *Funktionale Programmierung*. Springer–Verlag, 2003, S.245

In fact, there is no interaction between a program and a user:

- All input data must be provided at the very beginning.
- Once called there is no opportunity for the user to react on a program's response and behaviour.

116 822/135

Handling Input/Output Henthforth

Our Objective:

Modifying the handling of input/ouput such that programs become and behave like

(sequentially) composed dialogue components

while preserving referential transparency as far as possible.



Peter Pepper. Funktionale Programmierung. Springer–Verlag, 2003, S.253



As illustrated by the previous figure, input/output is

a major source for side effects in a program: e.g., each read statement like read will usually yield a different value for each call, i.e. referential transparency is lost. 11.6 824/135

Monadic Input/Output in Haskell

Conceptually, a Haskell program consists of

- a computational core and
- ► an interaction component.



11.6 825/135

Monadic Input/Ouput

The monad concept of Haskell allows to

- distinguish (and conceptually separate) functions that belong to the
 - computational core (pure functions)
 - interaction component (impure functions, i.e. having side effects).

by assigning different types to them:

 \rightsquigarrow Int, Real, String,... vs. IO Int, IO Real, IO String,... where the type constructor IO is an instance of Monad.

specify the evaluation order of functions of the interaction component (i.e., of basic input/output primitives provided by Haskell) by explicitly using the features of monadic programming.



Recall Chapter 11.3

The Input/Output Monad (1)

```
The IO monad:
```

instance Monad IO where
(>>=) :: IO a -> (a -> IO b) -> IO b
return :: a -> IO a

Intuitively:

- (>>=): If p and q are commands, then p >>= q is the command that first executes p, yielding thereby the return value x of type a, and then executes q x, thereby yielding the return value y of type b.
- return: Generates a return value w/out any input/output action.

Chap. 4
Chap. 6
Chap. 7
Chap. 9
Chap. 11
11.1 11.2
11.2
11.4
11.5
11.6
11.7
Chap. 12
Chap. 13
Chap. 14 827/135

1/1219

Recall Chapter 11.3

The Input/Output Monad (2)

It is worth noting:

The IO monad is similar in spirit to the state monad: It passes around the "state of the world."

In more detail:

For a given suitable type World

whose values represent the current state of the world

the notion of an interactive program, i.e., an IO-program, can be represented by a function of type

► World -> World

which may be abbreviated as:

type IO = World -> World

Chap. 4
Chap. 6
Chap. 7
Chap. 9
Chap. 11
11.1
11.2
11.3
11.4
11.5
11.6
11.7
Chap. 12
Chap. 13
Chap. 14 828/135

1/1219
Recall Chapter 11.3

The Input/Output Monad (3)

In general:

Interactive programs do not only modify the state of the world but may also return a result value, e.g., echoing a character that has been read from a keyboard.

This suggests to change the type of interactive programs to

type IO = World -> (a, World)

	Chap. 4
	Chap. 6
	Chap. 7
	Chap. 9
	Chap. 11
	11.1
	11.2 11.3
	11.5
	11.5
	11.6
	11.7
۲.	Chap. 12
	Chap. 13
	Chap. 14 829/135
	025/155

Typical Interaction Examples (1)

A simple question/response interaction with the user:

 116

```
Typical Interaction Examples (2)
 Input/output from/to files:
 type FilePath = String -- file names according
                          -- to the conventions of
                          -- the operating system
 writeFile :: FilePath -> String -> IO ()
  appendFile :: FilePath -> String -> IO ()
 readFile :: FilePath -> IO String
             :: FilePath -> IO Bool
  isEOF
  interAct :: IO ()
  interAct = do
               putStr "Please input a file name: "
               fname <- getLine
                                                       116
               contents <- readFile fname
               putStr contents
```

Typical Interaction Examples (3)				
Note the relationship of the do-notation				
<pre>do writeFile "testFile.txt" "Hello File System!" putStr "Hello World!"</pre>				
and the monadic operations:	Chap. 3 Chap. 4			
writeFile "testFile.txt" "Hello File System!" >> putStr "Hello World!"				
Note also the (subtle) difference in the result types:				
<pre>Main>putStr ('a':('b':('c':[]))) Main>putChar (head ['x' ->> abc :: IO () ->> x :: IO ()</pre>	Chap. 10 , Chap. 11 11.1			
but	11.2 11.3 11.4			
Main>('a':('b':('c':[]))) Main>head ['x','y','z'] ->> "abc" :: [Char] ->> 'x' :: Char				
Main>print "abc" Main>print 'x' ->> "abc" :: IO () ->> 'a' :: IO ()	Chap. 13 Chap. 14 832/135			

More Examples (1)

The output command sequence

do writeFile "testFile.txt" "Hello File System!"
 putStr "Hello World!"

... is equivalent to:

writeFile "testFile.txt" "Hello File System!" >>
putStr "Hello World!"

11.6 833/135

More Examples (2)	
It is worth noting:	Contents
	Chap. 1
From	Chap. 2
	Chap. 3
(>>) :: Monad m => m a -> m b -> m b	Chap. 4
	Chap. 5
and	Chap. 6
anu	Chap. 7
writeFile "testFile.txt"	Chap. 8
"Hello File System!" :: IO ()	Chap. 9
putStr "Hello World!" :: IO ()	Chap. 10 Chap. 11
	11.1
	11.2 11.3
we conclude for our example that $m = IO$, $a = ()$, and $b =$	11.4 11.5
(). Overall, we thus obtain:	11.6 11.7
	Chap. 12
$(>>)$:: IO () \rightarrow IO () \rightarrow IO ()	Chap. 13

Chap. 14 834/135

More Examples (3)

Ilustrating local declarations within do-constructs:

reverse2lines :: IO ()	
reverse2lines	
= do line1 <- getLine	
line2 <- getLine	
let rev1 = reverse line1	
<pre>let rev2 = reverse line2</pre>	
putStrLn rev2	
putStrLn rev1	C
te enviredent ter	C
is equivalent to:	

reve	rseź	2lines	::	IO	()	
reve	rseź	2lines				
=	do	line1	<-	get	Line	
		line2	<-	get	Line	
		putSti	rLn	(re	verse	line2)
		putSti	rLn	(re	verse	line1)

	7
	9
	10
	11
11.1	
11.2	
11.3	
11.4	
11.5	
11.6	
11.7	
Chap.	12
Chap.	13

Summing up (1)

Overall, the monadic handling of input/output in Haskell renders possible:

The shift from

 "batch-like" input/output processing that works exclusively by pure functions of the computational core as illustrated below



Peter Pepper. *Funktionale Programmierung*. Springer–Verlag, 2003, S.245

116

Summing up (2)

...to an interactive, dialogue-oriented input/output processing w/out breaking the functional paradigm (keyword: referential transparency!)



Peter Pepper. *Funktionale Programmierung*. Springer–Verlag, 2003, S.253 11.6

Chap. 12

Chap. 13

Chap. 14 837/135 Stream-based Input/Output (1)

Early versions of Haskell foresaw a stream-based handling of input/output:

Stream-based considering programs functions on streams: IOprog :: String -> String

•••
$$\langle E_3 \rangle \langle E_2 \rangle \langle E_1 \rangle$$
 Programm \rightarrow ••• $\langle A_3 \rangle \langle A_2 \rangle \langle A_1 \rangle$

Peter Pepper. *Funktionale Programmierung*. Springer–Verlag, 2003, S.271

Input/output streams on terminals, file systems, printers,... 11.6 838/135

Stream-based Input/Output (2)

Advantages and disadvantages:

- Stream-based input/output handling for languages with
 - eager semantics:
 - there is no real stream model (the input must completely be provided and consumed at the beginning and must thus be finite); hence, input/output is limited to a batch- or stack-like processing.
 - lazy semantics:
 - Interactions are possible; thanks to lazy evaluation inputs/outputs are always in "proper" order.
 - But: the causal and temporal relationship between input and output is often "obscure"; special synchronization might be used to overcome that.
 - Overall: streambased input/output reaches its limit when switching to graphical user interfaces and random access to files.

11.6 839/135

$\mathsf{ML}\text{-}\mathsf{Style}\ \mathsf{Input}/\mathsf{Output}$

The ML-style of handling input/output is

a Unix-like handling of display, keyboard, etc. as files: std_in, std_out, open_in, open_out, close_in,...

Advantages and disadvantages:

The handling is simple but at the cost of anomalies like those discussed in LVA 185.A03; in particular, referential transparency is lost.

Input/output handling in functional languages is an important research topic:

 Andrew D. Gordon. Functional Programming and Input/Output. British Computer Society Distinguished Dissertations in Computer Science. Cambridge University Press, 1992. 11.6 841/135

Chapter 11.7 A Fresh Look at the Haskell Class Hierarchy

11.7



Fethi Rabhi, Guy Lapalme Algorithms. Addison-Wesley, 1999, Figure 2.4, p.46

mPlus

Chap. 14 843/135

117

A Section of the Haskell Class Hierarchy (2)



A Section of the Haskell Class Hierarchy (3)



Selected Types and their Class Membership

Туре	Instance of	Derivation
0	Read	Eg Ord Enum Bounded
[a]	Read Functor Monad	Eq Ord
(a,b)	Read	Eq Ord Bounded
(->)		
Array	Functor Eq Ord Read	
Bool		Eq Ord Enum Read Bounded
Char	Eq Ord Enum Read	
Complex	Floating Read	
Double	RealFloat Read	
Either		Eq Ord Read
Float	RealFloat Read	
Int	Integral Bounded Ix Read	
Integer	Integral Ix Read	
IO	Functor Monad	
IOError	Eq	
Maybe	Functor Monad	Eq Ord Read
Ordering		Eq Ord Enum Read Bounded
Ratio	RealFrac Read	
		Fethi Rabhi, Guy Lapalme. Algorithms.

11.7

846/135

Addison-Wesley, 1999, Table 2.4, p. 47

Last but not least (1)

Monads – where does the term come from?

Monads, a term that

- has already been used by Gottfried Wilhelm Leibniz as a counterpart to the term "atom."
- has been introduced into programming language theory by Eugenio Moggi in the realm of category theory as a means for describing the semantics of programming languages:

Eugenio Moggi. Computational Lambda Calculus and Monads. In Proceedings of the 4th Annual IEEE Symposium on Logic in Computer Science (LICS'89), 14-23, 1989.

Last but not least (2)

Monads, a term that

- has become popular in the world of functional programming (but w/out the background from category theory), especially because monads (Philip Wadler, 1992)
 - allow to introduce some useful aspects of imperative programming into functional programming,
 - are well suited for integrating input/output into functional programming, as well as for many other application domains,
 - provide a suitable interface between functional programming and programming paradigms with side effects, in particular, imperative and object-oriented programming.
 without breaking the functional paradigm!

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- John Launchbury, Simon Peyton Jones. *State in Haskell*. Lisp and Symbolic Computation 8(4):293-341, 1995.
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- Eugenio Moggi. Computational Lambda Calculus and Monads. In Proceedings of the 4th Annual IEEE Symposium on Logic in Computer Science (LICS'89), 14-23, 1989.
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- Bryan O'Sullivan, John Goerzen, Don Stewart. Real World Haskell. O'Reilly, 2008. (Chapter 7, I/O – The I/O Monad; Chapter 14, Monads; Chapter 15, Programming with Monads; Chapter 16, Using Parsec – Applicative Functors for Parsing; Chapter 18, Monad Transformers; Chapter 19, Error Handling – Error Handling in Monads)
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- Peter Pepper. Funktionale Programmierung in OPAL, ML, Haskell und Gofer. Springer-V., 2. Auflage, 2003. (Kapitel 21.2, Ein kommandobasiertes Ein-/Ausgabemodell; Kapitel 22.2, Kommandos; Kapitel 22.6.4, Anmerkungen zu Monaden)
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11.7 852/135

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117

Chapter 11: Further Reading (8)

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- Philip Wadler. How to Declare an Imperative. ACM Computing Surveys 29(3):240-263, 1997.

11.7

Chapter 12 Arrows

857/135

Chap. 12

Motivation

The higher-order type (constructor) class

generalizes the type class Monad.

and provides an even more general concept for

composing functions.

that is particularly useful for

▶ functional reactive programming (cp. Chapter 15).

Chap. 12 858/135

The Constructor Class Arrow

Arrows are instances of the constructor class Arrows:

class Arrow a where pure :: (b -> c) a b c (>>>) :: a b c -> a c d -> a b d first :: a b c -> a (b,d) (c,d)

Note:

- pure allows embedding of ordinary functions into the constructor class Arrow.
- (>>>) serves the composition of computations.
- ▶ first has as an analogue on the level of ordinary
 functions the function firstfun with
 firstfun f = \(x,y) → (f x, y)



The Laws of Arrow

Members of the constructor class Arrow must satisfy the following nine laws:

<pre>pure id >>> f = f</pre>	(AL1):	identity	
f >>> pure id = f	(AL2):	identity	
$(f \implies g) \implies h = f \implies (g \implies h)$	(AL3):	associa-	
		tivity	
<pre>pure (g . f) = pure f >>> pure g</pre>	(AL4):	functor	
		composition	
<pre>first (pure f) = pure (f × id) first (f >>> g) = first f >>> first g</pre>		evcension	
first f >>> pure (id \times g) = pure (id	× g) >	>> first f	C
	(AL7):	exchange	C
<pre>first f >>> pure fst = pure fst >>> f</pre>	(AL8):	unit	C
<pre>first (first f) >>> pure assoc = pure</pre>	assoc	>>> first f	C
	(AL9):	association	C

Chap. 12

Creating Instances of Class Arrow

Ordinary functions as instance of constructor class Arrow:

instance Arrow (->) where
pure f = f
f >>> g = g . f
first f = f × id

Note:

The function first could also be defined by: first f = \(b,d) -> (f b, d)

Chap. 12 861/135

Useful Supporting Functions (1)

Chap. 12

Chap. 16

Chap. 17

Useful Supporting Functions (2)

...related to the constructor class Arrow:

Chap. 12

Background and Motivation (1)

Notions of computation:

add :: (b -> Int) -> (b -> Int) -> (b -> Int) add f g z = f z + g z Chap. 12 864/135


Chap. 12

Background and Motivation (3)

Generalizing add to non-determinism:

type NonDet i o = i -> [o]

addND :: NonDet b Int -> NonDet b Int -> NonDet b Int addND f g z = [x+y | x <- f z, y <- g z] Chap. 12 866/135

Background and Motivation (4)

Generalizing add to mapping transformers:

type MapTrans s i o = (s \rightarrow i) \rightarrow (s \rightarrow o)

addMT :: MapTrans s b Int -> MapTrans s b Int -> MapTrans s b Int

addMT f g m z = f m z + g m z

Chap. 12

Chap. 17

Background and Motivation (5)

Generalizing add to simple automata:

newtype Auto i o = A (i -> (o, Auto i o))

All together, this

allows modelling of synchronous circuits.

Chap. 12

Background and Motivation (6)

- Functions and programs often contain components that are "function-like" "w/out being just functions."
- Arrows define a common interface for coping with the "notion of computation" of such function-like components.
- Monads are a special case of arrows.
- Like monads, arrows allow to meaningfully structure programs.

Chap. 12

Back to the Examples (1)

- ► The preceding examples have in common that there is a type A →→ B of computations, where inputs of type A are transformed into outputs of type B.
- Arrows yield a sufficiently general interface to describe these commonalities uniformly and to encapsulate them in a class.

Chap. 12

Back to the Examples (2)

Implementing the preceding examples as instances of the class Arrow:

newtype NotDet i o = ND (i -> [o])

newtype MapTrans s i o = MT ((s \rightarrow i) \rightarrow (s \rightarrow o))

newtype Auto i o = A (i -> (o, Auto i o))

Back to the Examples (3)

State transformers:

instance Arrow (State s) where pure f = ST (id x f) ST f >>> ST g = ST (g . f) first (ST f) = ST (assoc . (f x id) . unassoc) unassoc :: (a,(b,c)) -> ((a,b),c) unassoc[~](x,[~](y,z)) = ((x,y),z) Chap. 12

Chap. 17

Back to the Examples (4)

Non-determinism:

instance Arrow NonDet where pure f = ND (\b -> [f b]) ND f >>> ND g = ND (\b -> [d | c <- f b, d <- g c]) first (ND f) = ND (\(b,d) -> [(c,d) | c <- f b]) Chap. 9 Chap. 10 Chap. 10

Chap. 12

Back to the Examples (5)

Mapping transformers:

instance Arrow (MapTrans s) where = MT (f .) pure f MT f >>> MT g = MT (g . f)first (MT f) = MT (zipMap . (f x id) . unzipMap) zipMap :: $(s \rightarrow a, s \rightarrow b) \rightarrow (s \rightarrow (a,b))$ zipMap h s = (fst h s, snd h s)unzipMap :: $(s \rightarrow (a,b)) \rightarrow (s \rightarrow a, s \rightarrow b)$ unzipMap h = (fst . h, snd . h)

Chap. 12

Back to the Examples (6)

Simple automata:

 Chap. 12

CI 17

Chap. 17

Back to the Examples (7)

Generalization

Consider the general combinator:

addA :: Arrow a => a b Int -> a b Int -> a b Int addA f g = f &&& g >>> pure (uncurry (+))

It is worth noting:

Each of the considered variants of add results as a specialization of addA with the corresponding arrow-type. Chap. 12 876/135

Summing up

- Arrow-combinators operate on "computations", not on values. They are point-free in distinction to the "common case" of functional programming.
- Analoguous to the monadic case a do-like notational variant makes programming with arrow-operations often easier and more suggestive (cf. literature hint at the end of the chapter), whereas the pointfree variant is more useful and advantageous for proof-theoretic reasoning.

Chap. 12

Chap. 17

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Chap. 12 878/135

Part V Applications

Chap. 12

Chapter 13 Parsing

Chap. 13

Parsing

Parsing: Lexical and syntactical analysis

- Combinator parsing
- Monadic parsing



Lexical and Syntactical Analysis

... in the following summarized as parsing.

Parsing

- an(other) application of functional programming often used to demonstrate its power and elegance.
- enjoys a long history. As an example of early work see e.g.:
 - William H. Burge. Recursive Programming Techniques. Addison-Wesley, 1975.

Chap. 13

Functional Implementation Approaches for Parsing

Two conceptually different implementation approaches:

- Combinator parsing (higher-order functions parsing)
 ~> recursive descent parsing
 - Graham Hutton. Higher-Order Functions for Parsing. Journal of Functional Programming 2(3):323-343, 1992.
- Monadic parsing
 - Graham Hutton, Erik Meijer. Monadic Parser Combinators. Technical Report NOTTCS-TR-96-4, Dept. of Computer Science, University of Nottingham, 1996.

Chap. 13 883/135

The presentation here

... is based on:

- Chapter 17 Simon Thompson. Haskell – The Craft of Functional Programming, Addison-Wesley/Pearson, 2nd edition, 1999.
- Graham Hutton, Erik Meijer. Monadic Parsing in Haskell. Journal of Functional Programming 8(4):437-444, 1998.

Chap. 13

Parsing informally

The basic problem:

- Read a sequence of objects of type a.
- Extract from this sequence an object or a list of objects of type b.

Chap. 13 885/135 Illustrating Example: Parsing of Expressions Consider:

Expressions

- The parsing task to be solved:
 - Read an expression of the form ((2+3)*5) and yield/"extract" the corresponding expression of type Exp.

(Note: This can be considered the reverse of the show function. It is similar to the derived read function, but differs in the arguments it takes (expressions of the form ((2+3)*5)vs. expressions of the form Op Mul (Add (Lit 2) (Lit 3)) (Lit 5)). Towards the Type of a Parser Function (1) What shall be the type of a parsing function? Naive specification of the type of a parser function: type BSParse1 a b = $[a] \rightarrow b$ -- Parser Input Expected Output bracket "(xyz" ->> '(' "234" ->> 2 or 23 or 234 ? number bracket "234" ->> no result, failure? Open issues to be answered: How shall the parser behave if there are multiple results? ▶ is a failure?

Chap. 13

Towards the Type of a Parser Function (2)

First refinement of the type of a parser function:

type BSParse2 a b = [a] -> [b]

Parser	Input		Expected Output
bracket	"(xyz"	->>	['(']
number	"234"	->>	[2, 23, 234]
bracket	"234"	->>	[]

Open issue to be answered:

What shall the parser do with the remaining input?

Chap. 13

Chap. 15

Chap. 16

The Type of a Parser Function

The final specification of the type of a parser function:

type Parse a b = [a] -> [(b,[a])]

-- Parser Input Expected Output Chap.8 bracket "(xyz" ->> [('(', "xyz")] Chap.9 number "234" ->> [(2,"34"), (23,"4"), (234,"")]Chap.10 bracket "234" ->> [] Chap.11

Chap. 12

Chap. 13 13.1

13.2

Chap. 14

Chap. 15

Chap. 16

Remarks and Conventions

It is worth noting:

 The capability of delivering multiple results enables the analysis of ambiguous grammars

→ list of successes technique

 Each element in the output list represents a successful parse.

Convention:

- Delivery of the empty list: Signals failure of the analysis.
- Delivery of a non-empty list: Signals success of the analysis; each element of the list is a pair, whose first component is the identified object (token) and whose second component is the input not yet considered.



Chapter 13.1 Combinator Parsing

13.1

Basic Parsers (1)

Primitive, input-independent parsing functions:

► The always failing parsing function

```
none :: Parse a b
none inp = []
```

The always successful parsing function succeed :: b -> Parse a b succeed val inp = [(val,inp)]

Remark:

- The none parser always fails. It does not accept anything.
- ► The succeed parser does not consume its input. In BNFnotation this corresponds to the symbol *ε* representing the empty word.

13.1 892/135

Basic Parsers (2)

Primitive, input-dependent parsing functions:

Recognizing single objects (token):

> Recognizing single objects satisfying a particular property: spot :: (a -> Bool) -> Parse a a spot p (x:xs) | p x = [(x,xs)] | otherwise = [] spot p [] = []

13.1 893/135 Simple Applications of Basic Parsers

Application:

bracket = token '(' dig = spot isDigit isDigit :: Char -> Bool isDigit ch = ('0' <= ch) && (ch <= '9')</pre>

Note: token can be defined using spot

token t = spot (== t)

13.1 13.2

Chap. 14

Chap. 15

Chap. 16

Intuition and Motivation for Combining Parsers

...obtaining (more) complex (re-usable) parsing functions:

Combinator Parsing

Objective

Building a library of higher-order polymorphic functions, which are then used to construct parsers.

13.1 895/135

Combining Parsers – Alternatives

1) Composition of parsers as alternatives:

alt :: Parse a b -> Parse a b -> Parse a b alt p1 p2 inp = p1 inp ++ p2 inp

Underlying intuition:

An expression, e.g., is either a literal, or a variable or an operator expression.

Example:

(bracket 'alt' dig) "234" ->> [] ++ [(2,"34")] \rightarrow The alt parser combines the results of the parses given by the parsers p1 and p2.

13.1 896/135

Combining Parsers – Sequential Composition

2) Sequential composition of parsers:

Underlying intuition:

 An operator expression starts with a bracket followed by a number.

13.1 897/135

Combining Parsers – Sequential Composition

Example:

Because of number "24(" ->> [(2,"4("), (24,"(")] we obtain:

Because of bracket "(" ->> [('(', "")] we finally get:

13.1 898/135

Combining Parsers – Transformation

3) Transformation by parsers:

 \rightsquigarrow transform the item returned by the parser, e.g., build something from it.

build :: Parse a b \rightarrow (b \rightarrow c) \rightarrow Parse a c build p f inp = [(f x, rem) | (x,rem) <- p inp]

Example: Note, digList returns a list of numbers and shall be embedded such that the number represented by it is returned.

13.1 899/135

Universal Parser Basis

The Clou:		
The	Chap. 4	
► basic parsers	Chap. 6	
together with the combinators		
together with the combinators		
▶ alt	Chap. 9	
► (>*>)		
	Chap. 11	
▶ build	Chap. 12	
constitute a universal "parser basis," i.e., allow to build any	Chap. 13 13.1 13.2	
parser which might be desired.	Chap. 14	
Example: A Parser for a List of Objects

We suppose to be given a parser recognizing single objects:

Intuition:

- A list can be empty.

 → this is recognized by the parser succeed
 [].
- A list can be non-empty, i.e., it consists of an object followed by a list of objects.

 w this is recognized by the combined parser p >*> list p, where we use build to turn a pair (x,xs) into the list (x:xs).

13.1 901/135

Summing up

...on combining parsers (parser combinators):

- Parsing functions in the above fashion are structurally similar to grammars in BNF-form. For each operator of the BNF-grammar there is a corresponding (higher-order) parsing function.
- These higher-order functions combine simple(r) parsing functions to (more) complex parsing functions.
- They are thus also called combining forms, or, as a short hand, combinators (cf. Graham Hutton. Higher-Order Functions for Parsing. Journal of Functional Programming 2(3):323-343, 1992).

13.1 902/135

Summary of the Universal Parser Basis (1)	
Priority of the sequence operator	
Thomy of the sequence operator	
infixr 5 >*>	
Parser type	
type Parse a b = [a] -> [(b,[a])]	
Input-independent parsing functions	
	Chap.
none :: Parse a b	Chap.
none inp = []	Chap.
	Chap.
succeed :: b -> Parse a b	13.1 13.2
<pre>succeed b > faise a b succeed val inp = [(val,inp)]</pre>	Chap.
	Chap.
	Chap

Summary of the Universal Parser Basis (2)

Recognizing single objects

token :: Eq a => a -> Parse a a
token t = spot (==t)

Recognizing single objects satisfying a particular property

13.1 904/135 Summary of the Universal Parser Basis (3) Alternatives

alt :: Parse a b -> Parse a b -> Parse a b alt p1 p2 inp = p1 inp ++ p2 inp

Sequences

Transformation

build :: Parse a b -> (b -> c) -> Parse a c build p f inp = [(f x, rem) | (x,rem) <- p inp] 13.1 905/135

1st Application of the Universal Parser Basis

Example

Chap. 11 Chap. 12 Chap. 13 13.1 13.2 Chap. 14 Chap. 15 Chap. 16 (906/135)

2nd Application of the Universal Parser Basis

Back to the initial example – a parser for expressions.

We consider expressions of the form:

data Expr = Lit Int | Var Name | Op Ops Expr Expr
data Ops = Add | Sub | Mul | Div | Mod

Op Add (Lit 2) (Lit 3) corresponds to 2+3

where the following convention shall hold:

- \blacktriangleright Literals: 67, ${\sim}89,$ etc., where ${\sim}$ is used for unary minus.
- ▶ Names: the lower case characters from 'a' to 'z'.
- ► Applications of the binary operations ...+, *, -, /, %, where % is used for mod and / for integer division.
- Expressions are fully bracketed; white space is not permitted.

13.1 907/135

A Parser for Expressions (1)

The parser

```
parser :: Parse Char Expr
parser = litParse 'alt' nameParse 'alt' opExpParse
```

... consists of three parts corresponding to the three sorts of expressions.

Part I: Parsing names of variables

```
nameParse :: Parse Char Expr
nameParse = spot isName 'build' Name
```

```
isName :: Char -> Bool
isName x = ('a' <= x && x <= 'z')
```

13.1 908/135

A Parser for Expressions (2)

Part II: Parsing (fully bracketed binary) operator expressions

litParse

= ((optional (token '~')) >*>
 (neList (spot isDigit))
 'build' (charlistToExpr . uncurry (++))

13.1 909/135

A Parser for Expressions (3)

Two further parsers

neList :: Parse a b -> Parse a [b] optional :: Parse a b -> Parse a [b]

such that:

- neList p recognizes a non-empty list of the objects which are recognized by p.
- optional p recognizes an object recognized by p or succeeds immediately.

Note that **neList** and **optional** as well as a number of other supporting functions used such as:

- ▶ isOp
- charlistToExpr

▶ ...

are yet to be defined (\rightsquigarrow homework).

13.1 910/135

The Top-level Parser: Putting it all Together

Converting a string to the expression it represents:

```
topLevel :: Parse a b -> [a] -> b
topLevel p inp
= case results of
   [] -> error "parse unsuccessful"
   _ -> head results
   where
   results = [ found | (found, []) <- p inp ]</pre>
```

It is worth noting:

- The input string is provided by the value of inp.
- The parse is successful, if the result contains at least one parse, in which all the input has been read.

```
13.1
911/135
```

Summing up (1)

Parsers of the form:

type Parse a b = [a] -> [(b,[a])]

```
none :: Parse a b
succeed :: b -> Parse a b
spot :: (a -> Bool) -> Parse a a
alt :: Parse a b -> Parse a b -> Parse a b
>*> :: Parse a b -> Parse a c -> Parse a (b,c)
build :: Parse a b -> (b -> c) -> Parse a c
topLevel :: Parse a b -> [a] -> b
```

...support particularly well the construction of so-called recursive descent parsers.

13.1 912/135

Summing up (2)

The following language features proved invaluable for combinator parsing:

- Higher-order functions: Parse a b is of a functional type; all parser combinators are thus higher-order functions, too.
- Polymorphism: Consider again the type of Parse a b: We do need to be specific about either the input or the output type of the parsers we build. Hence, the above parser combinator can immediately be reused for other (token-) and data types.
- Lazy evaluation: "On demand" generation of the possible parses, automatical backtracking (the parsers will backtrack through the different options until a successful one is found).

13.1 913/135

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- Jan van Eijck, Christina Unger. *Computational Semantics with Functional Programming*. Cambridge University Press, 2010. (Chapter 9, Parsing)
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13.1 914/135

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 - Matthew Might, David Darais, Daniel Spiewak. Parsing with Derivatives – A Functional Pearl. In Proceedings of the 16th ACM International Conference on Functional Programming (ICFP 2011), 189-195, 2011.

13.1 915/135

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- S. Doaitse Swierstra. Combinator Parsing: A Short Tutorial. In Language Engineering and Rigorous Software Development, International LerNet ALFA Summer School 2008, Revised Tutorial Lectures. Springer-V., LNCS 5520, 252-300, 2009.

13.1

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- S. Doaitse Swierstra, Luc Duponcheel. Deterministic, Error Correcting Combinator Parsers. In: Advanced Functional Programming, Second International Spring School, Springer-V., LNCS 1129, 184-207, 1996.
- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 2nd edition, 1999. (Chapter 17.5, Case study: parsing expressions)

Chapter 13.1: Further Reading (5)

- Simon Thompson. Haskell The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 17.5, Case study: parsing expressions)
- Philip Wadler. How to Replace Failure with a List of Successes. In Proceedings of the 4th International Conference on Functional Programming and Computer Architecture (FPCA'85), Springer-V., LNCS 201, 113-128, 1985.

13.1

Chapter 13.2 Monadic Parsing

13.2

Monadic Parsing

The class Monad

class Monad m where return :: a -> m a (>>=) :: m a -> (a -> m b) -> m b

The type of a parser function:

newtype Parser a = Parser (String -> [(a,String)])

We then use the same convention as in Chapter 13.1, i.e.:

- Delivery of the empty list: Signals failure of the analysis.
- Delivery of a non-empty list: Signals success of the analysis; each element of the list is a pair, whose first component is the identified object (token) and whose second component the input still to be examined.

13.2 920/135

A Monad of Parsers

Basic Parsers:

Recognizing single characters

item :: Parser Char
item = Parser (\cs -> case cs of

"" -> [] (c:cs) -> [(c,cs)])

Note:

▶ The functions item and token correspond to each other.

13.2 921/135

The Parser Monad (1)

Parser is a type constructor. This allows:

13.2 922/135

The Parser Monad (2)

Note:

- The parser return a succeeds without consuming any of the argument string, and returns the single value a.
- parse denotes a deconstructor function for parsers defined by parse (Parser p) = p.
- The parser p >>= f first applies the parser p to the argument string cs yielding a list of results of the form (a, cs'), where a is a value and cs' is a string. For each such pair f a is a parser that is applied to the string cs'. The result is a list of lists that is then concatenated to give the final list of results.

13.2 923/135

The Parser Monad (3)

As required for instances of the class Monad, we can show that the 3 monad laws hold:

Chap. 15

Chap. 16

Properties of return and (>>=)

Reminder:

- The above properties are required for each instance of class Monad, not just for the specific instance of the parser monad
 - return is left-unit and right-unit for (>>=)
 allows a simpler and more concise definition of some parsers.
 - ► (>>=) is associative
 → allows suppression of parentheses when parsers are applied sequentially.

13.2 925/135

The Parser Monad

This way we get another two important parsers:

- The always successful parser: return
- ► Sequencing of parsers: (>>=)

Note:

The functions

- return and succeed
- ▶ (>>=) and (>*>)

correspond to each other.

13.2 926/135 Typical Structure of a Parser (1)

Using the sequencing operator (>>=):

```
p1 >>= \a1 ->
p2 >>= \a2 ->
...
pn >>= \an ->
f a1 a2 ... an
```

Contents

Chap. 1

. .

han 5

hap. 6

Chap. 7

han 8

han 0

Chap. 10

Chap. 11

10

hap. 13

13.1 13.2

Chap. 15

Chap. 16

Typical Structure of a Parser (2)

Intuition:

There is a natural operational reading of such a parser:

- Apply parser p1 and denote its result value a1.
- Apply subsequently parser p2 and denote its result value a2.

▶ ...

- Apply concludingly parser pn and denote its result value an.
- Combine finally the intermediate result values by applying some suitable function f.

Typical Structure of a Parser (3)

The do-notation allows a more appealing notation:

do a1 <- p1 a2 <- p2 ... an <- pn f a1 a2 ... an

Alternatively, in just one line:

do {a1 <- p1; a2 <- p2;...; an <- pn; f a1 a2...an}

13.2

Chap. 16

Notational Conventions

Expressions of the form

ai <- pi are called generators (since they generate values for the variables ai)

Remark:

- A generator of the form ai <- pi can be
 - replaced by pi, if the generated value will not be used afterwards.

13.2 930/135

Example: A Simple Parser

Write a parser **p** that

- reads three characters,
- drops the second character of these, and
- returns the first and the third character as a pair.

Implementation:

p :: Parser (Char,Char)

p = do {c <- item; item; d <- item; return (c,d)}</pre>

Parser Extensions (1)

Monads with a zero and a plus are captured by two built-in class definitions in Haskell:

class Monad m => MonadZero m where
 zero :: m a

class MonadZero m => MonadPlus m where
 (++) :: m a -> m a -> m a

13.2

Parser Extensions (2)

The type constructor **Parser** can be made instances of these two classes as follows giving two further parsers:

The parser that always fails: instance MonadZero Parser where zero = Parser (\cs -> [])

► The parser that non-deterministically selects:

instance MonadPlus Parser where
 p ++ q = (\cs -> parse p cs ++ parse q cs)

Simple Properties (1)

We can prove:

Informally:

- zero is left-unit and right-unit for (++)
- (++) is associative

Remark: The above properties are required to hold for each monad with zero and plus.

Contents

13.2

chap. 10

Chap. 16

Simple Properties (2)

Specifically for the parser monad we can additionally prove:

Informally:

- zero is left-zero and right-zero element for (>>=)
- (>>=) distributes through (++)

13.2

Deterministic Selection

The parser that deterministically selects: (+++) :: Parser a -> Parser a -> Parser a p +++ q = Parser (\cs -> case parse (p ++ q) cs of [] -> [] (x:xs) -> [x])

It is worth noting:

- (+++) shows the same behavior as (++), but yields at most one result
- (+++) satisfies all of the previously listed properties of (++)

13.2 936/135
Further Parsers

Recognizing Single objects char :: Char -> Parser Char char c = sat (c ==)Single objects satisfying a particular property sat :: (Char -> Bool) -> Parser Char sat p Chap. 9 = do {c <- item; if p c then return c else zero} Sequences of numbers, lower case and upper case characters, etc. ...analogously to char 13.2 It is worth noting: sat and char correspond to spot and token.

Recursion Combinators (1)

Useful parsers can often recursively be defined:

Parse a specific string string :: String -> Parser String string "" = return "" string (c:cs) = do {char c; string cs; return (c:cs)} Repeated applications of a parser p (Zero or more applications of p) many :: Parser a -> Parser [a] many p = many1 p +++ return [] (One or more applications of p) many1 :: Parser a -> Parser [a] many1 p = do a <- p; as <- many p; return (a:as)</pre>

13.2 938/135

Recursion Combinators (2)

A variant of the parser many with interspersed applications of the parser sep, whose result values are thrown away
 sepby :: Parser a -> Parser b -> Parser [a]
 p 'sepby' sep
 = (p 'sepby1' sep) +++ return []

```
sepby1 :: Parser a -> Parser b -> Parser [a]
p 'sepby1' sep
```

13.2

Recursion Combinators (3)

Repeated applications of a parser p, separated by applications of a parser op, whose result value is an operator that is assumed to associate to the left, and which is used to combine the results from the p parsers chainl :: Parser a -> Parser (a -> a -> a) \rightarrow a \rightarrow Parser a chainl p op a = (p 'chainl1' op) +++ return a chainl1 :: Parser a -> Parser (a -> a -> a) -> Parser a p 'chainl1' op = do {a <- p; rest a}</pre> where rest a = (do f < - opb <- p rest (f a b))

+++ return a

13.2 940/135

Lexical Combinators (1)

Suitable combinators allow suppression of a lexical analysis (token recognition), which traditionally precedes parsing:

Parsing of a string with blanks and line breaks space :: Parser String space = many (sat isSpace)

Parsing of a token by means of parsers p token :: Parser a -> Parser a

token p = do {a <- p; space; return a}</pre>

13.2

Lexical Combinators (2)

Parsing of a symbol token

symb :: String -> Parser String
symb cs = token (string cs)

Application of parser p, removal of initial blanks
apply :: Parser a -> String -> [(a,String)]
apply p = parse (do {space; p})

13.2

Example: Parsing of Expressions (1)

Grammar:

...for arithmetic expressions built up from single digits using the operators +, –, *, /, and parentheses:

expr	::=	expr addop term term
term	::=	term mulop factor factor
factor	::=	digit (expr)
digit	::=	0 1 9
addop	::=	+ -
mulop	::=	* /

13.2 943/135

Example: Parsing of Expressions (2)

Parsing and evaluating expressions (yielding integer values) using the chainl1 combinator to implement the left-recursive production rules for expr and term:

```
expr :: Parser Int
addop :: Parser (Int -> Int -> Int)
mulop :: Parser (Int -> Int -> Int)
expr = term 'chainl1' addop
term = factor 'chainl1' mulop
factor = digit +++
         do {symb "("; n <- expr; symb ")"; return n}</pre>
digit
= do {x <- token (sat isDIgit); return (ord x - ord '0')}_{ap.13}
addop
                                                            13.2
 = do {symb "+"; return (+)} +++ do {symb "-"; return (-))<sup>20.14</sup>
mulop
= do {symb "*"; return (*)} +++ do {symb "/"; return (div)}
```

```
Example: Parsing of Expressions (3)
```

Example:

Evaluating

apply expr " 1 - 2 * 3 + 4 "

gives the singleton list

[(-1,"")] as desired

as desired.

Contents Chap. 1 Chap. 2 Chap. 3 Chap. 4 Chap. 5

hap. 7 hap. 8

lhap. 9

Chap. 10

Chap. 11

Chap. 12

Chap. 13 13.1 13.2

13.2

Chap. 14

Chap. 15

Chap. 16

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13.2 946/135

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13.2 947/135

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13.2 948/135

Chapter 14 Logical Programming Functionally

Chap. 16 Chap. 17 (949/135)

Chap. 14

Logical Programming Functionally

Declarative programming

- Functional style
- Logical style

If each of these two styles is appealing

 a combination of (features of) functional and logical programming

should be even more appealing.

Chap. 14

Sergio Antoy, Michael Hanus. Functional Logic Programming. Communications of the ACM 53(4):74-85, 2010.

...highlights the benefits of combining the paradigm features of both logical and functional programming.

Some of the essence of this article is summarized on the next couple of slides.

Chap. 14

Evolution of Programming Languages

...the stepwise introduction of abstractions hiding the underlying computer hardware and the details of program execution.

- Assembly languages introduce mnemonic instructions and symbolic labels for hiding machine codes and addresses.
- FORTRAN introduces arrays and expressions in standard mathematical notation for hiding registers.
- ALGOL-like languages introduce structured statements for hiding gotos and jump labels.
- Object-oriented languages introduce visibility levels and encapsulation for hiding the representation of data and the management of memory.

Chap. 14 952/135

Evolution of Prog. Lang. (Cont'd)

- Declarative languages, most prominently functional and logic languages hide the order of evaluation by removing assignment and other control statements.
 - A declarative program is a set of logical statements describing properties of the application domain.
 - The execution of a declarative program is the computation of the value(s) of an expression wrt these properties.

This way:

- The programming effort in a declarative language shifts from encoding the steps for computing a result to structuring the application data and the relationships between the application components.
- Declarative languages are similar to formal specification languages but executable.

Chap. 14 953/135

Functional vs. Logic Languages

Functional languages

- are based on the notion of mathematical function
- programs are sets of functions that operate on data structures and are defined by equations using case distinction and recursion
- provide efficient, demand-driven evaluation strategies that support infinite structures

Logic languages

- are based on predicate logic
- programs are sets of predicates defined by restricted forms of logic foumulas, such as Horn clauses (implications)
- provide non-determinism and predicates with multiple input/output modes that offer code reuse

Chap. 14 954/135

Functional Logic Languages: Examples (1)

Curry

Michael Hanus (Ed.). Curry: An Integrated Functional Logic Language (vers. 0.8.2, 2006). http://www.curry-language.org/ (vers. 0.8.3, September 11, 2012), http://www.informatik.uni-kiel.de/~curry/report.html

► TOY

Francisco J. López-Fraguas, Jaime Sánchez-Hernández. TOY: A Multi-paradigm Declarative System. In Proceedings of the 10th International Conference on Rewriting Techniques and Applications (RTA'99), Springer-V., LNCS 1631, 244-247, 1999.

Chap. 14

Functional Logic Languages: Examples (2)

Mercury

Zoltan Somogyi, Fergus Henderson, Thomas Conway. The Execution Algorithm of Mercury: An Efficient Purely Declarative Logic Programming Language. Journal of Logic Programming 29(1-3):17-64, 1996. See also: The Mercury Programming Language

Chap. 14

956/135

http://www.mercurylang.org

Functional Logic Languages: Examples

And there are many more:

- Escher
- ► Oz
- ► HAL

▶ ...

Contents

Chap. 1

Chap. 2

hap. 3

Chap. 4

hap. 5

hap. 6

Chap. 7

Chap. 8

Chap. 9

Chap. 10

Chap. 11

Chap. 12

Chap. 13

Chap. 14

Chap. 15

Chap. 16

Chap. 17

```
A Curry Appetizer
 Regular Expressions
 data RE a = Lit a
              | Alt (RE a) (RE a)
                Conc (RE a) (RE a)
                Star (RE a)
The Semantics of Regular Expressions
  sem :: RE a -> [a]
  sem (Lit c) = [c]
  sem (Alt r s) = sem r ? sem s
  sem (Conc r s) = sem r + sem s
                                                        Chap. 14
  sem (Star r) = [] ? sem (Conc r (Star r))
```

Note: The Curry-operator ? denotes nondeterministic choice.

A Curry Appetizer (Cont'd)

abstar = Conc (Lit 'a') (Star (Lit 'b'))

sem abstar ->> ["a","ab","abb"]

The Curry-operator =:= indicates that an equation is to be solved rather than an operation to be defined; here it checks whether a given word w is in the language of a given regular expression re:

sem re =:= w

The following equation checks whether a string s contains a word generated by a regular expression re (similar to Unix's grep utility):

```
xs ++ sem re ++ ys =:= s
where xs, ys free
```

Chap. 14 959/135

In this chapter

 $\ldots we$ will follow a different approach that has been presented in

 Michael Spivey, Silvija Seres. Combinators for Logic Programming. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 2003.

We will show how to

 integrate features of logical programming into functional programming.

Central means:

Monads and monadic programming.

Chap. 14

Declarative Programming

- Distinguishing: Emphasizes the "what", rather than the "how"
 - Essence: Programs are declarative assertions about a problem rather than imperative solution procedures.
- Variants: functional and logical programming.
- Question: Can functional and logical programming be uniformly combined?

Chap. 14 961/135

Combining Features of Functional and Logical Programming

Basic approaches:

- Classical: Designing new programming languages, which enjoy features of both programming styles (e.g. Curry).
- Simpler: Implementing an interpreter for one style using the other style.
- Still simpler: Write "logical" programs in Haskell using a library of combinators.

 \rightsquigarrow this is the approach taken in the following!

Chap. 14 962/135

Further Reading

...on functional/logical programming languages:

- Michael Hanus, Herbert Kuchen, Juan Jose Moreno-Navarro. Curry: A Truly Functional Logic Language. In Proceedings of the ILPS'95 Workshop on Visions for the Future of Logic Programming, 1995, 95-107.
- Zoltan Somogyi, Fergus J. Henderson, Thomas C. Conway. Mercury: An Efficient Purely Declarative Logic Programming Language. In Proceedings of the 18th Australasian Computer Science Conference, 499-512, 1995.

Chap. 14 963/135

Remarks on the present Combinator Approach

Advantages and disadvantages

- compared to dedicated functional/logical programming languages
 - less costly
 - but less expressive

Key problems

- Modelling logical programs
 - yielding multiple answers
 - with logical variables (no distinction between input and output variables)
- Modelling the evaluation strategy inherent to logical programs

Chap. 14

Running Example: Factoring of Nat. Numbers

Factoring of Natural Numbers: Decomposing a positive integer into the set of pairs of its factors.

Example:
$$\frac{\text{Integer}}{24} | \begin{array}{c} \text{Factor-Pairs} \\ \hline (1,24), (2,12), (3,8), (4,6), \dots, (24,1) \end{array}$$

Obvious Solution:
factor :: Int -> [(Int,Int)]
factor n = [(r,s) | r<-[1..n], s<-[1..n], r*s == n]
In fact, we get:
?factor 24
[(1,24), (2,12), (3,8), (4,6), (6,4), (8,3), (12,2), (24,1)]

965/135

Chap. 14

Chap. 16

It is worth noting

The previous solution exploits:

- Explicit domain knowledge
 - E.g. $r * s = n \Rightarrow r \le n \land s \le n$
 - This renders possible: Restriction to a finite search space
 [1..24]×[1..24]

Often such knowledge is not available; in general:

- The search space cannot be restricted a priori
- In the following thus: Considering the factoring problem as a search problem over an infinite search space
 [1..]×[1..]

Chap. 14

Tackling the 1st Problem: Several Results

Solution: Lists of successes →lazy lists (Phil Wadler)

Idea

- A function of type a -> b can be replaced by a function of type a -> [b].
- Lazy evaluation ensures that the elements of the result list (list of successes) are provided as they are found, rather than as a complete list after termination of the computation.

Chap. 14 967/135

Back to the Example

Realizing this idea in the factoring example (assuming that the search space cannot be bounded a priori):

factor :: Int -> [(Int,Int)] factor n = [(r,s) | r<-[1..], s<-[1..], r*s == n] ?factor 24 [(1,24) ...followed by an infinite wait. \sim This is of no practical value!

Remedy: Fair Order via Diagonalization (1)

Explore the search space of pairs in a fair order:

factor n
 = [(r,s) | (r,s)<-diagprod [1..][1..], r*s == n]
where
diagprod :: [a] -> [b] -> [(a,b)]
diagprod xs ys
 = [(xs!!i, y!!(n-i)) | n<-[0..], i<-[0..n]]</pre>

Effect: Each pair (x,y) is now reached after a finite number of steps:

 $[(1,1),(1,2),(2,1),(1,3),(2,2),(3,1),(1,4), (2,3),(3,2),\ldots]$

Chap. 14 969/135

Remedy: Fair Order via Diagonalization (2)

Applied to our running example, we obtain:

?factor 24
[(4,6),(6,4),(3,8),(8,3),(2,12),(12,2),(1,24),(24,1)

...this means, we obtain all results; followed again, however, by an infinite wait.

Of course, this was expected, since the search space is infinite.

Chap. 14

Systematic Remedy: Using Monads

Reminder:

class Monad m where
 return :: a -> m a
 (>>=) :: m a -> (a -> m b) -> m b

Notational conventions for the following development:

- Stream a ...for (potentially) infinite lists
- [a] ...for finite lists
- Note: The distinction between Stream a for infinite lists and [a] for finite lists is only conceptually; the following definition makes this explicit:

type Stream a = [a]

Chap. 14 971/135

List Monad

The monad of (potentially infinite) lists Definition of the monad operations return (yields the singleton list): return :: a -> Stream a return $x = \lceil x \rceil$ binding operator (>>=): (>>=) :: Stream a -> (a -> Stream b) -> Stream b xs >>= f = concat (map f xs)

Other monad operations are irrelevant in our context.

Chap. 14 972/135
Benefit

The monad operations return and (>>=) allow us to model/replace list comprehension:

The meaning of the expression, for example, [(x,y) | x <- [1..], y <- [10..]] ... using list comprehension is equivalent to concat (map (\x -> [(x,y) | y <- [10..]])[1..]) ...that itself is equivalent to concat (map ($x \rightarrow$ concat (map (\y -> [(x,y)])[10..]))[1..]) Using return and (>>=) this can concisely be expressed by: $[1..] >>= (\langle x -> [10..] >>= (\langle y -> return (x,y)))$

Chap. 14 973/135

Benefit (Cont'd)

Haskell's do-notation allows an even more compact equivalent representation:

do x <- [1..]; y <- [10..]; return (x,y) Recalling the general rule: The expression do x1 <- e1: x2 <- e2: ... : xn <- en: e is a shorthand for e1 >>= ($x1 \rightarrow e2$ >>= ($x2 \rightarrow ...$ >>= ($xn \rightarrow e$)...)

Chap. 14

974/135

Fairness: Adapting the binding op. (>>=) (1)

Are we done? Not yet, since:

Exploring the pairs of the search space is still not fair.

The expression

do x <- [1..]; y <- [10..]; return (x,y)

yields the stream

[(1,10),(1,11),(1,12),(1,13),(1,14),..

This problem is going to be tackled next.

Chap. 14

975/135

Fairness: Adapting the binding op. (>>=) (2)

Idea: Embedding diagonalization into (>>=)

Implementation

Introducing a new type Diag a:

newtype Diag a = MkDiag (Stream a) deriving Show

...together with an auxiliary function for stripping off the type constructor MkDiag:

unDiag (MkDiag xs) = xs

Chap. 14 976/135

Fairness: Adapting the binding op. (>>=) (3)

Diag is made an instance of the constructor class Monad:

```
instance Monad Diag where
return x = MkDiag [x]
MkDiag xs >>= f
= MkDiag (concat (diag (map (unDiag . f) xs)))
```

where diag rearranges the values into a fair order:

```
Chap. 14
977/135
```

Fairness: Adapting the binding op. (>>=) (4) where $lzw :: (a \rightarrow a \rightarrow a) \rightarrow Stream a \rightarrow$ Stream a -> Stream a lzw f [] ys = ys lzw f xs [] = xslzw f (x:xs) (y:ys) = (f x y) : (lzw f xs ys)

It is worth noting:

 lzw equals zipWith except that the non-empty remainder of a non-empty argument list is attached, if one of the argument lists gets empty.

Chap. 14

978/135

Fairness: Adapting the binding op. (>>=) (5)

Intuition:

- return yields the singleton list.
- undiag strips off the constructor added by the function f :: a -> Diag b.
- diag arranges the elements of the list into a fair order (and works equally well for finite and infinite lists).
- Izw reminds to "like zipWith."

Fairness: Adapting the binding op. (>>=) (6) The idea underlying diag:

Transform an infinite list of infinite lists
 [[x11,x12,x13,..],[x21,x22,..],[x31,x32,..],..]
 ...into an infinite list of finite diagonals

[[x11],[x12,x21],[x13,x22,x31],..]

This way:

Summing up

- ▶ We have achieved: The pairs are delivered in a fair order!
- Chap. 14 980/135

Back to the Factoring Problem (1)

Current state of our solution:

- Generating pairs (in a fair order): done.
- Selecting (those pairs being part of the solution): still open.

Approach for solving the selection problem, i.e., filtering out the pairs (r, s) satisfying the equality $r \times s = n$:

Filtering with conditions!

Chap. 14

981/135

Back to the Factoring Problem (2)

For that purpose:

It is worth noting:

The value zero allows to express an empty answer set.

Chap. 14 982/135

Back to the Factoring Problem (3)	
In detail:	Contents
The instance declaration for ordinary lazy lists:	Chap. 1 Chap. 2
instance Bunch [] where	Chap. 3
zero = []	Chap. 4
alt xs ys = xs ++ ys	Chap. 5
wrap xs = xs	Chap. 6 Chap. 7
and for the monad Diag:	Chap. 8
instance Bunch Diag where	Chap. 9
zero = MkDiag[]	Chap. 10
alt (MkDiag xs)(MkDiag ys) = MkDiag (shuffle xs ys	Chap. 11) Chap. 12
wrap xm = xm	Chap. 13
shuffle [] ys = ys	Chap. 14
shuffle (x:xs) ys = x : shuffle ys xs	Chap. 15
	Chap. 16 Chap. 17
(Remark: alt and wrap will be used later.)	983/135

Back to the Factoring Problem (4)

By means of zero, the function test yields the key for filtering:

test :: Bunch m => Bool -> m()
test b = if b then return() else zero

This does not look useful, but it provides the key to filtering:

?do x <- [1..]; () <- test (x 'mod' 3 == 0); return [3,6,9,12,15,18,21,24,27,30,33,..

?do x <- MkDiag [1..]; test (x 'mod' 3 == 0); return
MkDiag[3,6,9,12,15,18,21,24,27,30,33,..</pre>

```
Chap. 10
 Chap. 14
 984/135
```

Are we done? (1) Not yet! Consider: ?do r <- MkDiag[1..]; s <- MkDiag[1..]; test(r*s==24); return (r,s) MkDiag[(1,24) ...followed by an infinite wait. What are the reasons for that? do r <- MkDiag[1..]; s <- MkDiag[1..];</pre> test(r*s==24): return (r.s) is equivalent to do x <- MkDiag[1..]</pre> (do y <- MkDiag[1..]; test(x*y==24);</pre> return (x,y))

Chap. 14 985/135

Are we done? (2)

I.e., the generator for y is merged with the subsequent test to the following (sub-) expression:

Intuition:

- This expression yields for a given value of x all values of y with x * y = 24.
- For x = 1 the answer (1, 24) will be found, in order to search in vain for further values of y.
- For x = 5 we thus do not observe any output.

Chap. 14 986/135

Solution Approach

The deeper reason for this undesired behaviour: The missing associativity of (>>=) for Diag, i.e.,

 $(xm \rightarrow f) \rightarrow g = xm \rightarrow (x \rightarrow f x \rightarrow g)$

...does not hold for (>>=) and Diag!

Remedy: Explicit grouping of generators to ensure fairness

...all results, subsequently followed by an infinite wait.

Chap. 14 987/135

Remarks

- All results, subsequently followed by an infinite wait
 this is the best we can hope for if the search space is infinite.
- Explicit grouping

 \rightsquigarrow required only because of missing associativity of (>>=), otherwise both expressions would be equivalent.

In the following

 \rightsquigarrow avoid infinite waiting by indicating that a result has not (yet) been found.

Chap. 14 988/135

Indicating that no solution is found

To this purpose: Introducing a new type Matrix together with breadth search.

Intuition

- Type Matrix: Infinite list of finite lists.
- Goal: A program that yields a matrix of answers, where row *i* contains all answers that can be computed with costs c(*i*).
- Solving the indication problem: By returning the empty list in a row (means "nothing found").

Chap. 14

989/135

Implementation (1)

The new type Matrix

newtype Matrix a
= MkMatrix (Stream [a]) deriving Show

...with an auxiliary function for stripping off the constructor:

unMatrix (MkMatrix xm) = xm

Chap. 14 990/135

Implementation (2)

Preliminary definitions for making Matrix an instance of class Bunch:

(>>=) :: Matrix a -> (a -> Matrix b) -> Matrix b
(MkMatrix xm) >>= f = MkMatrix (bindm xm (unMatrix . f))

bindm :: Stream[a] -> (a -> Stream[b]) -> Stream[b] bindm xm f = map concat (diag (map (concatAll . map f)

concatAll :: [Stream [b]] -> Stream [b] concatAll = foldr (lzw (++)) [] Chap. 13 xm)) Chap. 14 991/135

Implementation (3)

In total we are now ready to make Matrix an instance of the classes Monad and Bunch:

```
instance Monad Matrix where
                     = MkMatrix[[x]]
 return x
  (MkMatrix xm) >>= f = MkMatrix(bindm xm (unMatrix . f))
instance Bunch Matrix where
                                = MkMatrix[]
  zero
 alt(MkMatrix xm)(MkMatrix ym) = MkMatrix(lzw (++) xm ym)<sup>30.8</sup>
  wrap(MkMatrix xm)
                                = MkMatrix([]:xm)
intMat = MkMatrix[[n] | n <- [1..]]
Example:
?do r <- intMat; s <- intMat; test(r*s==24); return (r,s)Chap.14
MkMatrix[[],[],[],[],[],[],[],[],[],[4,6),(6,4)],
  [[], [], [], [], [], [], [], (1, 24), (24, 1)], [], [], [], ...
                                                        992/135
```

A Variety of Search Strategies

(i) Breadth search (MkMatrix[[n] |n<-[1..]]), (ii) depth search ([1..]), (iii) diagonalization:

...by means of additional functions that allow us to fix the strategy of interest at the time of calling ("just in time").

Control via a monad type:

choose :: Bunch m => Stream a -> m a choose (x:xs) = wrap (return x 'alt' choose xs) factor :: Bunch m => Int -> m(Int, Int) factor n = do r <- choose[1..]; s <- choose[1..]; test(r*s==n); return (r,s)

Chap. 14 993/135

Selecting a Search Strategy

This allows:

- Usage of factor with different search strategies.
- The specified type of factor determines the search monad (and thus the search strategy).

```
?factor 24 :: Stream(Int,Int)
[(1,24)
```

Chap. 14 994/135

Summary of Progress

Recall:

The 3 key problems we had/have to deal with:

- Modelling logical programs with
 - multiple results: done (essentially by means of lazy lists)
 - Iogical variables: still open
 - Common for logical programs: not a pure simplification of an initially completely given expression, but a simplification of an expression containing variables, for which appropriate values have to be determined. In the course of the computation, variables can be replaced by other subexpressions containing variables themselves, for which then appropriate values have to be found.
 - Modelling of the evaluation strategy inherent to logical programs: done
 - implicit search of logical programming languages has been made explicit.
 - by means of type classes of Haskell even different search strategies were conveniently be realizable.

Chap. 14 995/135

Tackling the Final Problem: Terms, Substitu-	
tions & Predicates (1)	
Towards the modeling in Haskell:	
Terms will describe values of logical variables:	Chap. 3 Chap. 4 Chap. 5
data Term = Int Int	Chap. 6
Nil Cons Term Term	
Var Variable deriving Eq	Chap. 9 Chap. 10
Named variables will be used for formulating queries, genera-	Chap. 11 Chap. 12
ted variables evolve in the course of the computation:	Chap. 13
data Variable = Named String	Chap. 14 Chap. 15
Generated Int deriving (Show, Eq)	Chap. 16
, demetated int deriving (bnow, Eq)	Chap. 17
	996/135

Terms, Substitutions & Predicates (2)

Some auxiliary functions

► for transforming a string into a named variable

var :: String -> Term
var s = Var (Named s)

▶ for constructing a term representation of a list of integers

list :: [Int] -> Term
list xs = foldr Cons Nil (map Int xs)

Chap. 14 997/135

Terms, Substitutions & Predicates (3)

Substitution and unification:

-- Substitution is essentially a mapping -- from variables to terms (details later) newtype Subst

Further support functions:

apply :: Subst -> Term -> Term
idsubst :: Subst
unify :: (Term, Term) -> Subst -> Maybe Subst

Chap. 14 998/135

Terms, Substitutions & Predicates (4)

Logical programs (in our Haskell environment) with m of type bunch:

-- Logical programs have type Pred m type Pred m = Answer -> m Answer

-- Answers; the integer-component controls -- the generation of new variables newtype Answer = MkAnswer (Subst, Int) Chap. 14 999/135

Terms, Substitutions & Predicates (5)

```
-- "Initial answer"
initial :: Answer
initial = MkAnswer (idsubst, 0)
run :: Bunch m => Pred m -> m Answer
run p = p initial
-- "Program run of a predicate as query", where
-- p is applied to the initial answer
run p :: Stream Answer
```

Chap. 14 1000/13 Writing logical programs Example: append(a,b,c) where a,b denote lists and c the concatenation of the lists a and b. Implementation as a function of terms on predicates: append :: Bunch m => (Term, Term, Term) -> Pred m -- The implementation of append (will follow!) and -- of appropriate Show-Functions is supposed: ?run(append(list[1,2],list[3,4],var "z")) :: Stream Answer [z=[1,2,3,4]]-- Note: Equivalent to the above list but more -- accurate would be: Cons 1 (Cons 2 (Cons 3 (Cons 4 Nil)))

9001/13

Chap. 14

Combinators for logical programs (1)

Simple predicates are formed by means of the operators (=:=) (equality of terms):

?run(var "x" =:= Int 3) :: Stream Answer
[{x=3}]

Implementation of (=:=) by means of unify:

```
(=:=) :: Bunch m => Term -> Term -> Pred m
(t=:=u)(MkAnswer(s,n)) =
   case unify(tu) s of
    Just s' -> return(MkAnswer(s',n))
    Nothing -> zero
```

Chap. 14 1002/13 Combinators for logical programs (2)

Conjunction of predicates by means of the operator (&&&) (conjunction):

[]

Implementation by means of the operator (>>=) of type bunch:

(&&&) :: Bunch m => Pred m -> Pred m -> Pred m (p &&& q) s = p s >>= q

-- equivalent and highlighting the -- sequentiality would be do t <- p s; u <- q t; return u</pre> Chap. 14 1003/13 Combinators for logical programs (3)

Disjunction of predicates by means of the operator (|||) (Disjunction):

Implementation by means of the operator alt of type bunch:

(|||) :: Bunch m => Pred m -> Pred m -> Pred m (p ||| q) s = alt (p s) (q s) Chap. 14 1004/13

Combinators for logical programs (4)

Introducing new variables in predicates (exploiting the integercomponent of answers)

...on the construction of local variables in recursive predicates:

exists :: Bunch m => (Term -> Pred m) -> Pred m
exists p (MkAnswer (s,n)) =
 p (Var(Generated n)) (MkAnswer(s,n+1))

Also for handling recursive predicates ...ensures that in connection with Matrix the costs per recursion unfolding increase by 1:

Chap. 14

1005/13

Example

Examples of applications of wrap and step:

?run (var "x" =:= Int 0) :: Matrix Answer
MkMatrix[[{x=0}]]

?run(step(var "x" =:= Int 0)) :: Matrix Answer
MkMatrix[[],[{x=0}]]

Chap. 14 1006/13 Recursive Programs (1)

This allows us to provide the implementation of append:

Chap. 14 9007/13 Recursive Programs (2)

As common for logical programs, also the following application of append is possible:

The concatenation of which lists equals the list [1,2,3]?

Chap. 14 1008/13
A More Complex Example (1)

Constructing "good" sequences consisting of 0s and 1s.

Definition:

- 1. The sequence [0] is good.
- If the sequences s1 and s2 are good, then also the sequence [1] ++ s1 ++ s2.
- 3. Except of the sequences according to 1. and 2., there are no other good sequences.

Chap. 14 1009/13

A More Complex Example (2)

Implementation as a predicate:

Chap. 14 9010/13

Applications (1)

1) Test of being "good":

It is worth noting:

 "empty answer" and "no answer" correspond to "yes" and "no" of a Prolog system. Chap. 14 9011/13

Applications (2)

2) Constructing "good" lists

```
-- With an unfair bunch-type: Some answers

-- are missing

?run(good(var "s")) :: Stream Answer

[s=[0],

    s=[1,0,0],

    s=[1,0,1,0,0],

    s=[1,0,1,0,1,0,0],...
```

Chap. 14

Applications (3)

```
-- For comparison: With a fair bunch-type
?run(good(var "s")) :: Diag Answer
Diag[s=[0]]
  s=[1.0.0].
  s = [1, 0, 1, 0, 0].
  s = [1.0.1.0.1.0.0].
  s=[1,1,0,0,0].
  s=[1,0,1,0,1,0,1,0,0]
  s = [1, 1, 0, 0, 1, 0, 0].
  s=[1.0.1.1.0.0.0].
  s=[1,1,0,0,1,0,1,0,0],...
```

Chap. 14

Applications (4)

. .

```
-- For comparison: With a breadth-first search
-- bunch-type. Effect: The output of results is
-- more "predictable".
?run(good(var "s")) :: Matrix Answer
MkMatrix[[].
   [s=[0]],[],[],[],
   [s=[1,0,0]],[],[],[],
   [s=[1,0,1,0,0]],[],
   [s=[1,1,0,0,0]],[],
   [s=[1,0,1,0,1,0,0]],[],
   [s=[1,0,1,1,0,0,0]],s=[1,1,0,0,1,0,0]],[],
```

Chap. 14

Delivering Missing Definitions (1)

Priorities of new infix operators:

infixr 4 =:=
infixr 3 &&&
infixr 2 |||

Substitution:

newtype Subst = MkSubst [(Var, Term)]
unSubst(MkSubst s) = s

```
idsubst = MkSubst[]
extend x t (MkSubst s) = MkSubst ((x,t):s)
```

Chap. 14

Delivering Missing Definitions (2)

```
Application of substitution:
```

```
apply :: Subst -> Term -> Term
apply s t =
  case deref s t of
   Cons x xs -> Cons (apply s x) (apply s xs)
              -> t'
    t.'
deref :: Subst -> Term -> Term
deref s (Var v) = 
  case lookup v (unSubst s) of
    Just t -> deref s t
    Nothing -> Var v
deref s t = t
```

Chap. 14 1016/13

Delivering Missing Definitions (3) Unification:

```
unify :: (Term, Term) -> Subst -> Maybe Subst
unify (t,u) = 
  case (deref s t, deref s u) of
    (Nil. Nil) -> Just s
    (Cons x xs, Cons y ys) ->
                         unify (x,y) s >>= unify (xs, ys)
    (Int n, Int m) | (n==m) \rightarrow Just s
    (Var x, Var y) | (x==y) \rightarrow Just s
    (Var x, t)
                              -> if occurs x t s
                                  then Nothing
                                  else Just (extend x t s)
    (t. Var x)
                              -> if occurs x t s
                                                             Chap. 14
                                  then Nothing
                                  else Just (extend x t s)
    (\_,\_)
                              -> Nothing
```

Delivering Missing Definitions (4)

Chap. 14 1018/13

Summing up

Current functional logic languages aim at balancing

- generality (in terms of paradigm integration)
- efficient implementations

Functional logic programming offers

- support of specification, prototyping, and application programming within a single language
- terse, yet clear, support for rapid development by avoiding some tedious tasks, and allowance of incremental refinements to improve efficiency

Overall: Functional logic programming

an emerging paradigm with appealing features

Chap. 14 1019/13

Chapter 14: Further Reading (1)

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Chap. 14

Chapter 14: Further Reading (2)

- Michael Hanus (Ed.). Curry: An Integrated Functional Logic Language. Vers. 0.8.2, 2006. www.curry-language.org/ Vers. 0.8.3, September 11, 2012: http://www.informatik.uni-kiel.de/~curry/report.html
- Michael Hanus. The Integration of Functions into Logic Programming: From Theory to Practice. Journal of Functional Programming 19&20:583-628, 1994.
- Michael Hanus. Multi-paradigm Declarative Languages. In Proceedings of the 23rd International Conference on Logic Programming (ICLP 2007), Springer-V., LNCS 4670, 45-75, 2007.

Chap. 14

Chapter 14: Further Reading (3)

- Michael Hanus, Herbert Kuchen, Juan Jose Moreno-Navarro. Curry: A Truly Functional Logic Language. In Proceedings of the ILPS'95 Workshop on Visions for the Future of Logic Programming, 95-107, 1995.
- Francisco J. López-Fraguas, Jaime Sánchez-Hernández. TOY: A Multi-paradigm Declarative System. In Proceedings of the 10th International Conference on Rewriting Techniques and Applications (RTA'99), Springer-V., LNCS 1631, 244-247, 1999.
- John W. Lloyd. Programming in an Integrated Functional and Logic Language. Journal of Functional and Logic Programming 1999(3), 49 pages, MIT Press, 1999.

Chap. 14 1022/13

Chapter 14: Further Reading (4)

- Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer-V., 2006. (Kapitel 22, Integration von Konzepten anderer Programmiersprachen)
- Zoltan Somogyi, Fergus Henderson, Thomas Conway. The Execution Algorithm of Mercury: An Efficient Purely Declarative Logic Programming Language. Journal of Logic Programming 29(1-3):17-64, 1996.
- Zoltan Somogyi, Fergus J. Henderson, Thomas C. Conway. Mercury: An Efficient Purely Declarative Logic Programming Language. In Proceedings of the 18th Australasian Computer Science Conference, 499-512, 1995.

Chap. 14 1023/13

Chapter 14: Further Reading (5)

- Silvija Seres, Michael Spivey. Embedding Prolog in Haskell. In Proceedings of the 1999 Haskell Workshop (Haskell'99), 25-38, 1999.
- Michael Spivey, Silvija Seres. Combinators for Logic Programming. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 177-199, 2003.

Chap. 14 1024/13

Chapter 15 Pretty Printing

Chap. 15

Motivation

Pretty Printing is

 like lexical and syntactical analysis another typical application used for demonstrating the elegance of functional programming. Chap. 15 1026/13

What's it all about?

A pretty-printer is

a tool (often a library of routines) designed for converting a tree into plain text.

Essential goal of pretty printing:

Preserving and reflecting the structure of the tree by indentation while using a minimum number of lines.

Hence

 Pretty printing can be considered the converse problem to parsing. Chap. 15

A "Good" Pretty-Printer

... is distinguished by properly balancing

- Simplicity of usage
- Flexibility of the format
- "Prettiness" of output

Chap. 15

The presentation in this chapter

... is based on:

 Philip Wadler. A Prettier Printer. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 2003.

It shall improve (see end of chapter) on the below pretty printer library proposed by John Hughes that is widely recognized as a standard:

John Hughes. The Design of a Pretty-Printer Library. In Johan Jeuring, Erik Meijer (Eds.), Advanced Functional Programming, First International Spring School on Advanced Functional Programming Techniques. Springer-V., LNCS 925, 53-96, 1995. Chap. 15 1029/13

A Simple Pretty Printer: Basic Approach

Requirement: For each document there shall be only one possible layout (e.g., no attempt is made to compress structure onto a single line).

The basic operators needed are:

:: Doc -> Doc -> Doc	associative concate-	
	nation of documents	
:: Doc	The empty document:	
	Right and left unit	
	for (<>)	
:: String -> Doc	Conversion function:	Chap.
	Converts a string to	Chap.
	a document	Chap.
:: Doc	Line break	Chap
:: Int -> Doc -> Doc	Adding indentation	Chap
:: Doc -> String	· · · · · · · · · · · · · · · · · · ·	Chap
0	document to a string	Chap
	<pre>:: Doc :: String -> Doc :: Doc</pre>	<pre>nation of documents :: Doc The empty document: Right and left unit for (<>) :: String -> Doc Conversion function: Converts a string to a document :: Doc Line break :: Int -> Doc -> Doc Adding indentation :: Doc -> String Output: Converts a</pre>

Chap. 11 Chap. 12 Chap. 13 Chap. 14 Chap. 15 Chap. 16 Chap. 17 G1030/f3

Convention

Arguments of text are free of newline characters.

Chap. 15 9031/13

A Simple Implementation

Implement

doc as strings (i.e. as data type String)

with

- (<>) as concatenation of strings
- nil as empty string
- text as identity on strings
- line as new line
- nest i as indentation: adding *i* spaces (after each line break by means of line) ~> essential difference to Hughes' pretty printer that also allows inserting spaces in front of strings allowing here to drop one concatenation operator
- layout as identity on strings

Chap. 15 1032/13

Example

Converting trees into documents (here: Strings) which are output as text (here: Strings).

Consider the following type of trees: data Tree = Node String [Tree] A concrete value B of type Tree: Node "eee" [], Node "ffff" [Node "gg" [], Node "hhh" [], Node "ii" [] Chap. 15]

...and its desired output

A text, where indentation reflects the structure of tree B:

```
aaa[bbbbbb[ccc,
dd],
eee,
ffff[gg,
hhh,
ii]]
```

It is worth noting:

Sibling trees start on a new line, properly indented.

Chap. 15 1034/13

Implementation

The below implementation achieves this:

data Tree = Node String [Tree]

```
showTree :: Tree -> Doc
showTree (Node s ts) = text s <>
```

nest (length s) (showBracket ts)

```
showTrees :: [Tree] -> Doc
showTrees [t] = showTree t
showTrees (t:ts) = showTree t <> text "," <>
line <> showTrees ts
```

Chap. 15 1035/13

Another possibly wanted output of B



each subtree starts on a new line, properly indented.

An implementation producing the latter output

```
data Tree = Node String [Tree]
showTree' :: Tree -> Doc
showTree' (Node s ts) = text s <> showBracket' ts
showBracket' :: [Tree] -> Doc
showBracket' [] = nil
showBracket' ts = text "[" <> nest 2 (line <>
                  showTrees' ts) <> line <> text "]"
showTrees' :: [Tree] -> Doc
showTrees' [t] = showTree t
showTrees' (t:ts) = showTree t <> text "," <> line
                                       <> showTrees ts
```

Chap. 15 9037/13

Normal Form of Documents

Documents can always be reduced to normal form.

Normal form

Text alternating with line breaks nested to a given indentation:

where

- each s_j is a (possibly empty) string
- each ij is a (possibly zero) natural number

Chap. 15

Example on Normal Forms 1(2)

A document

```
text "bbbbb" <> text "[" <>
 nest 2 (
       line <> text "ccc" <> text "," <>
       line <> text "dd"
 ) <>
  line <> text "]"
...and how it is output:
  bbbbb
    ccc,
    dd
```

Chap. 15 G1039/13

Example on Normal Forms 2(2)

The same document

```
text "bbbbb" <> text "[" <>
 nest 2 (
       line <> text "ccc" <> text "." <>
       line <> text "dd"
 ) <>
  line <> text "]"
...and its normal form:
 text "bbbbb[" <>
 nest 2 line <> text "ccc," <>
 nest 2 line <> text "dd" <>
```

```
nest 0 line <> text "]"
```

Chap. 15 9040/13

Why does it work?

...because of the properties (laws) the functions enjoy.

In more detail

... because of the fact that

- (<>) is associative with unit nil
- the laws summarized on the next slide.

Note:

 All of these laws except of the last one are paired; they are paired with a corresponding law for their units. Chap. 15 1041/13 Properties of the Functions/Laws 1(2)We have the following (pairs of) laws (except for the last one): text (s ++ t) = text s <> text t -- text is a homomortext "" = nil -- phism from string -- concatenation to -- document concate--- nation nest (i+j) x = nest i (nest j x) -- nest is a homomor $\frac{Chap.7}{2}$ -- phism from addition nest 0 x = x -- to composition nest i (x <> y) = nest i x <> nest i y -- nest distributes 11 nest i nil = nil -- through document^{ap. 12} -- concatenation nest i (text s) = text s -- Nesting is absorbed by text; Chap. 15 -- different to Hughes' pretty -- printer)

Properties of the Functions/Laws 2(2)

Relevance and Impact

The above laws are sufficient to ensure that documents can always be transformed into normal form

Chap. 15

- First four laws: applied from left to right
- Last three laws: applied from right to left

Further Properties/Laws

...that relate documents to their layouts:

layout	(x <>	y)	=	layc	ut	x ++ layout y	
layout	nil	•	=	""		layout is a homomorphism	
·						from document concate-	
						nation to string conca-	
						tenation	
layout	(text	s)	=	s		layout is the inverse	
Lujouo	(00110	27		2		of text	
						OI UCAU	
1 200011+	(nost	i lino)	_	<i>i</i> \n,'		copy i ''	
Iayout	(Hest	T TIUE)	-	/11			Chap
						layout of a nested line	Chap
						is a newline followed by	Chap

- -- one space for each level
- -- of indentation

Chap. 15 9044/13
The Implementation of Doc

Intuition

Represent documents as a concatenation of items, where each item is a text or a line break indented to a given amount.

This is realized as a sum type (the algebra of documents):

The constructors relate to the document operators as follows:

Ni	.1		=	nil				
s	'Text'	х	=	text	s	<> x		
i	'Line'	х	=	nest	i	line	<>	х

Chap. 15 1045/13

Example

Using this new algebraic type Doc, the normal form (considered previously)

```
text "bbbbb[" <>
nest 2 line <> text "ccc," <>
nest 2 line <> text "dd" <>
nest 0 line <> text "]"
```

... is represented by the following value of Doc:

```
"bbbbb[" 'Text' (
2 'Line' ("ccc," 'Text' (
2 'Line' ("dd," 'Text' (
0 'Line' ("]," 'Text' Nil)))))
```

Chap. 15 1046/13

Derived Implementations 1(2)

Implementations of the document operators can easily be derived from the above equations:

nil = Nil
text s = s 'Text' Nil
line = 0 'Line' Nil
(s 'Text' x) <> y = s 'Text' (x <> y)
(i 'Line' x) <> y = i 'Line' (x <> y)
Nil <> y = y

Chap. 15

Derived Implementations 2(2)

nest i (s 'Text' x) = s 'Text' nest i x nest i (j 'Line' x) = (i+j) 'Line' nest i x nest i Nil = Nil layout (s 'Text' x) = s ++ layout x layout (i 'Line' x) = '\n' : copy i ' ' ++ layout x layout Nil = ""

Chap. 15 9048/13

Correctness of the derived Implementations

...can be shown for each of them, e.g.:

•	Derivation of (s 'Text' x) <> y = s 'Text' (x <> y)
	<pre>(s 'Text' x) <> y = { Definition of Text }</pre>
	(text s <> x) <> y
	<pre>= { Associativity of <> }</pre>
	text s <> (x <> y)
	<pre>= { Definition of Text }</pre>
	s 'Text' (x <> y)

The remaining equations can be shown using similar reasoning.

Chap. 15

Documents with Multiple Layouts

Adding Flexibility:

- Up to now: Documents were equivalent to a string (i.e., they have a fixed single layout)
- Next: Documents shall be equivalent to a set of strings (i.e., they may have multiple layouts)
 where each string corresponds to a layout.

This can be rendered possible by just adding a new function:

```
group :: Doc -> Doc
```

Informally:

Given a document, representing a set of layouts, group returns the set with one new element added that represents the layout in which everything is compressed on one line: Replace each newline (plus indentation) by a single space. Chap. 15 1050/13

Preferred Layouts

"Beauty" needs to be specified/defined:

> pretty replaces layout

pretty :: Int -> Doc -> String

and picks the prettiest layout depending on the preferred maximum line width argument.

Remark: pretty's integer-argument specifies the preferred maximum line length of the output (and hence the prettiest layout out of the set of alternatives at hand). Chap. 15 1051/13

Example

Using the modified **showTree** function based on group:

...the call of pretty 30 (once ompletely specified) will yield the output:

```
aaa[bbbbbb[ccc, dd],
    eee,
    ffff[gg, hhh, ii]]
```

This ensures:

- ► Trees are fit onto one line where possible (i.e., length ≤ 30).
- Insertion of sufficiently many line breaks in order to avoid exceeding the given maximum line length.

Chap. 15 1052/13

Implementation of the new Functions

The following supporting functions are required:

-- Forming the union of two sets of layouts (<|>) :: Doc -> Doc -> Doc

-- Replacement of each line break (and its -- associated indentation) by a single space flatten :: Doc -> Doc Chap. 15 9053/13

Implementation of the new Functions (Cont'd)

- Observation: A document always represents a non-empty set of layouts.
- Requirements:
 - In (x <|> y) all layouts of x and y enjoy the same flat layout (mandatory invariant of <|>).
 - Each first line in x is at least as long as each first line in y (second invariant).
- Note: <|> and flatten are not directly exposed to the user (only via group and other supporting functions).

Chap. 15 1054/13

Properties/Laws of (<|>)

Operators on simple documents are extended pointwise through union:

Chap. 15 9055/13

Properties/Laws of flatten

The interaction of flatten with other document operators:

flatten (x <|> y) = flatten x -- distribution law

flatten (nest i x) = flatten x

Chap. 15

Implementation of group

...by means of flatten and (<>), the implementation of group can be given:

group x = flatten x < > x

Intuitively: group adds the flattened layout to a set of layouts.

Note: A document always represents a non-empty set of layouts where all layouts in the set flatten to the same layout.

Chap. 15 1057/13 Based on the previous laws each document can be reduced to a normal form of the form

x1 <|> ... <|> xn

where each xi is in the normal form of simple documents (which was introduced previously).

Selecting a "best" Layout out of a Set of Layouts

...by defining an ordering relation on lines in dependence of the given maximum line length.

Out of two lines

- which do not exceed the maximum length, select the longer one
- of which at least one exceeds the maximum length, select the shorter one

Note: Sometimes we have to pick a layout where some line exceeds the limit (a key difference to the approach of Hughes). However, this is done only, if this is unavoidable.

Chap. 15 1059/13

The Adapted Implementation of Doc

The new implementation of Doc as algebraic type. It is similar to the previous one except for the new construct representing the union of two documents:

```
data Doc = -- As before: The first 3 alternatives
   Nil
   String 'Text' Doc
   Int 'Line' Doc
   -- New: We add a construct representing
      the union of two documents
   Doc 'Union' Doc
```

1060/13

Chap. 15

Relationship of Constructors and Document Operators

The following relationships hold between the constructors and the document operators:

Nil = nil
s 'Text' x = text s <> x
i 'Line' x = nest i line <> x
x 'Union' y = x <|> y

Chap. 15

Chap. 16

Chap. 17

Example 1(8)

The document group(group(group(group(text "hello" <> line <> text "a") <> line <> text "b") <> line <> text "c") <> line <> text "d")

Chap. 15

Example 2(8)

...has the following 5 possible layouts:

hello a b c d hello a b c hello a b hello a hello a hello a hello a hello a hello a c b a Chap. 7 d c b a Chap. 8 d c b Chap. 9

d

1063/13

Chap. 15

c d

Example 3(8)

Task: Print the above document under the constraint that the maximum line width is 5.

 \rightsquigarrow the right-most layout of the previous slide is requested.

Initial (performance) considerations:

Factoring out "hello" of all the layouts in x and y
"hello" 'Text' ((" " 'Text' x) 'Union' (0 'Line'

 Defining additionally the interplay of (<>) and nest with Union

(x 'Union' y) $\langle \rangle z = (x \langle \rangle z)$ 'Union' (y $\langle \rangle z$) nest k (x 'Union' y) = nest k x 'Union' nest k y

(hap) (hap) (hap. 10 Chap. 15 1064/13

Example 4(8)

Implementations of group and flatten can easily be derived:

group Nil = Nil group (i 'Line' x) = (" " 'Text' flatten x) 'Union' (i 'Line' x) group (s 'Text' x) = s 'Text' group x group (x 'Union' y) = group x 'Union' y flatten Nil = Nil flatten (i 'Line' x) = " " 'Text' flatten x flatten (s 'Text' x) = s 'Text' flatten x flatten (x 'Union' y) = flatten x

Chap. 9 Chap. 10 Chap. 11 Chap. 12 Chap. 13 Chap. 14 Chap. 16 Chap. 16 Chap. 17 **G1065/f3**

Example 5(8)

Considerations on correctness (similar reasoning as earlier):

Derivation of group (i 'Line' x) (see line two) (preserving the invariant required by union)

group (i 'Line' x)

- = { Definition of Line }
 group (nest i line <> x)
- = { Definition of group }
 flatten (nest i line <> x) <|> (nest i line s <> x)
 chap.10
 chap.11
- = { Definition of flatten }
 (text " " <> flatten x) <|> (nest i line <> x)
- = { Definition of Text, Union, Line }
 (" " 'Text' flatten x) 'Union' (i 'Line' x)

Chap. 15

Example 6(8)Correctness considerations (cont'd): Derivation of group (s 'Text' x) (see line three) group (s 'Text' x) = { Definition Text } group (text s <> x) = { Definition group } flatten (text s $\langle x \rangle$ x) $\langle | \rangle$ (text s $\langle \rangle$ x) = { Definition flatten } $(text s \iff flatten x) \ll (text s \iff x)$ = { <> distributes through <|> } text s \langle (flatten x $\langle \rangle$ x) = { Definition group } text s <> group x = { Definition Text } s 'Text' group x

Chap. 15 1067/13

Example 7(8)

Selecting the "best" layout:

Remark:

- best: Converts a "union"-afflicted document into a "union"-free document.
- Argument w: Maximum line width.
- Argument k: Already consumed letters (including indentation) on current line.

Chap. 15 1068/13

Example 8(8)

Check, if the first document line stays within the maximum line length w:

fits w x w<0	= False		cannot fit		
fits w Nil	= True		fits trivially		
fits w (s 'Text' x)					
= fits (w - length	ns) x		fits if x fits into		
			the remaining space		
			after placing s		
fits w (i 'Line' x)	= True		yes, it fits		

Last but not least, the output routine (layout remains unchanged):

Select the best layout and convert it to a string:

pretty w x = layout (best w 0 x)

Chap. 15 1069/13

Enhancing Performance: A More Efficient Variant

Sources of inefficiency:

- 1. Concatenation of documents might pile up to the left.
- 2. Nesting of documents adds a layer of processing to increment the indentation of the inner document.

Problem fix:

- For 1.): Add an explicit representation for concatenation, and generalize each operation to act on a list of concatenated documents.
- For 2.): Add an explicit representation for nesting, and maintain a current indentation that is incremented as nesting operators are processed.

Chap. 15 1070/13 Enhancing Performance: A More Efficient Variant (Cont'd)

Implementing this fix by means of a new implementation of documents:

```
data DOC = NIL -- Here is one constructor Ch
| DOC :<> DOC -- corresponding to each Ch
| NEST Int DOC -- operator that builds a Ch
| TEXT String -- document Ch
| LINE
| DOC :<|> DOC
```

Remark:

 In distinction to the previous document type we here use capital letters in order to avoid name clashes with the previous definitions Chap. 15 9071/13

Implementing the Document Operators

Defining the operators to build a document are straightforward:

nil			=	NIL
x <>	у		=	х :<> у
nest	i	х	=	NEST i x
text	ន		=	TEXT s
line			=	LINE

Chap. 15

Implementing group and flatten

As before, we require the following invariants:

- In (x :<|> y) all layouts in x and y flatten to the same layout.
- ► No first line in x is shorter than any first line in y.

Definitions of group and flatten are then straightforward:

group x		=	flatten x :< > x
flatten	NIL	=	NIL
flatten	(x :<> y)	=	flatten x:<> flatten y
flatten	(NEST i x)	=	NEST i (flatten x)
flatten	(TEXT s)	=	TEXT s
flatten	LINE	=	TEXT " "
flatten	(x :< > y)	=	flatten x

Chap. 15 1073/13

Representation Function

Generating the document from an indentation-afflicted document ("indentation-document pair"):

Chap. 15 1074/13

Selecting the "best" Layout

Generalizing the function "best" by composing the old function with the representation function to work on lists of indentation-document pairs:

be w k z = best w k (rep z) (Hypothesis)
best w k x = be w k [(0,x)]

where the definition is derived from the old one:

be w k [] = Nil be w k ((i,NIL):z) = be w k z be w k ((i,x :<> y) : z) = be w k ((i,x) : (i,y) : be w k ((i,NEST j x) : z) = be w k ((i+j),x) : z) be w k ((i,TEXT s) : z) = s 'Text' be w (k+length s) z be w k ((i,LINE) : z) = i 'Line' be w i z be w k ((i.x :<|> y) : z) = better w k (be w k ((i.x) : z))

(Za) 11 Chap. 15 9075/13 Preparing the XML-Application 1(3)

First some useful supporting functions:

x <+> y = x <> text " " <> y x </> y = x <> line <> y

folddoc f [] = nil
folddoc f [x] = x
folddoc f (x:xs) = f x (folddoc f xs)

spread = folddoc (<+>)
stack = folddoc (</>)

Chap. 15

Preparing the XML-Application 2(3) Further supportive functions: -- An often recurring output pattern bracket l x r = group (text l <> nest 2 (line <> x) <> line <> text r) -- Abbreviation of the alternative tree -- layout function showBracket' ts = bracket "[" (showTrees' ts) "]" -- Filling up lines (using words out of the -- Haskell Standard Lib.) x <+/> y = x <> (text " " :<|> line) <> y Chap. 15 fillwords = folddoc (<+/>) . map text . words

Preparing the XML-Application 3(3)

Chap. 15 1078/13

Application

Printing XML-documents (simplified syntax):

data XML	= Elt String [Att] [XML] Txt String				
data Att	= Att String String				
showXML x	= folddoc (<>) (showXMLs x)				
<pre>showXMLs (Elt n a []) = [text "<" <> showTag n a <> text "/>" showXMLs (Elt n a c) = [text "<" <> showTag n a <> text ">" <> showFill showXMLs c <> text "<!--" <--> text n <> text ">"] showXMLs (Txt s) = map text (words s)</pre>					
showAtts (Att n v)					

= [text n <> text "=" <> text (quoted v)]

Chap. 15 9079/13

```
Application (Cont'd)
```

Continuation:

quoted s = "\"" ++ s ++ "\""
showTag n a = text n <> showFill showAtts a
showFill f [] = nil
showFill f xs
 = bracket "" (fill (concat (map f xs))) ""

Chap. 15
1st XML Example

...for a given maximum line length of 30 letters:

```
<p
  color="red" font="Times"
  size="10"
>
  Here is some
  <em> emphasized </em> text.
  Here is a
  <a
    href="http://www.eg.com/"
  > link </a>
  elsewhere.
```

Chap. 15 G1081/13

2nd XML Example

...for a given maximum line length of 60 letters:

Here is some emphasized text. Here is a
 link elsewhere .chap.9

Chap. 12 Chap. 13 Chap. 14 Chap. 15

Chap. 16

Chap. 17

3rd XML Example

...after dropping of flatten in fill:

```
  Here is some <em>
    emphasized
  </em> text. Here is a <a
    href="http://www.eg.com/"
    link </a> elsewhere.
```

...start and close tags are crammed together with other text \rightsquigarrow less beautifully than before.

Chap. 15 1083/13

Summing up: Why "prettier" than "pretty"?

The below pretty printer library proposed by John Hughes is widely recognized as a standard:

 John Hughes. The design of a pretty-printer library. In Johan Jeuring, Erik Meijer (Eds.), Advanced Functional Programming, Springer-V., LNCS 925, 53-96, 1995.

From a technical perspective, the library of John Hughes enjoys the following characteristics:

- There are two ways (horizontal and vertical) to concatenate documents, one of which
 - without unit (vertical)
 - with right-unit but no left-unit (horizontal)

Chap. 15 1084/13

Summing up (Cont'd)

Philip Wadler considers his "Prettier Printer" an improvement of John Hughes' pretty printer library.

From a technical perspective, a distinguishing feature of the "Prettier Printer" proposed by Philip Wadler is:

- There is only a single way to concatenate documents that is
 - associative
 - with a left-unit and a right-unit.

Moreover, John Hughes' pretty printer library

- consists of ca. 40% more code,
- ▶ is ca. 40% slower

as the "prettier printer" of Philip Wadler's proposal.

Chap. 15 1085/13

Summary of the Code 1(12)

Source: Philip Wadler. A Prettier Printer. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 2003.

```
infixr 5:</>
infixr 6:<>
infixr 6 \iff
data DOC = NIL
            | DOC :<> DOC
             NEST Int DOC
             TEXT String
             LINE
            | DOC :<|> DOC
data Doc = Nil
            String 'Text' Doc
              Int 'Line' Doc
```

Chap. 15 9086/13

Summary of the Code 2(12)

nil	= NIL	
x <> y	= x :<> y	
nest i x	= NEST i x	
text s	= TEXT s	Chap. 4
line	= LINE	
11110		
aroun v	= flatten x :< > x	
group x		
	NTT	Chap. 9
	= NIL	Chap. 10
flatten (x :<> y)	= flatten x:<> flatten y	Chap. 11
<pre>flatten (NEST i x)</pre>	= NEST i (flatten x)	Chap. 12
flatten (TEXT s)	= TEXT s	Chap. 13
flatten LINE	= TEXT " "	Chap. 14
flatten (x :< > y)		Chap. 15
		Chap. 16

Chap. 17

Summary of the Code 3(12)

layout Nil = ""
layout (s 'Text' x) = s ++ layout x
layout (i 'Line' x) = '\n': copy i ' ' ++ layout x
copy i x = [x | _ <- [1..i]]
</pre>

Chap. 15 1088/13

Summary of the Code 4(12)

best w k x = be w k [(0,x)] be w k [] = Nil be w k ((i,NIL):z) = be w k z be w k ((i,x :<> y) : z) = be w k ((i,x) : (i,y) : z) be w k ((i,NEST j x) : z) = be w k ((i+j),x) : z) be w k ((i, TEXT s) : z)= s 'Text' be w (k+length s) z be w k ((i,LINE) : z) = i 'Line' be w i z be w k ((i.x :<|> y) : z) = better w k (be w k ((i.x) : z)) (be w k (i,y) : z)) better w k x y

= if fits (w-k) x then x else y

Chap. 15 1089/13

Summary of the Code 5(12)

fits w x | w<0 = False fits w Nil = True fits w (s 'Text' x) = fits (w - length s) x fits w (i 'Line' x) = True = layout (best $w \ 0 \ x$) pretty w x -- Utility functions = x <> text " " <> y x <+> v x </> y = x <> line <> y folddoc f [] = nil folddoc f [x] = x folddoc f (x:xs) = f x (folddoc f xs)

Chap. 15

G1090/13

Summary of the Code 6(12)

= folddoc (<+>)spread stack = folddoc $(\langle \rangle)$ bracket l x r = group (text l <> nest 2 (line $\langle \rangle$ x) $\langle \rangle$ line <> text r) x <+/> y = x <> (text " " :<|> line) <> y fillwords = folddoc (<+/>) . map text . words fill [] = nil fill [x] = x fill (x:y:zs) = (flatten x <+> fill (flatten y : zs)) || < || > (x </> fill (y : zs))

Chap. 15 9091/13

Summary of the Code 7(12)

-- Tree example data Tree = Node String [Tree] showTree (Node s ts) = group (text s <> nest (length s) (showBracket ts)) showBracket [] = nil showBracket ts = text "[" <> nest 1 (showTrees ts) <> text "]" showTrees [t] = showTree t showTrees (t:ts) = showTree t <> text "," <> line <> showTrees ts

Chap. 15 1092/13

Summary of the Code 8(12)

```
showTree' (Node s ts) = text s <> showBracket' ts
showBracket' [] = nil
showBracket' ts
= bracket "[" (showTrees' ts) "]"
showTrees' [t] = showTree t
showTrees' (t:ts)
= showTree t <> text "," <> line <> showTrees ts
```

Chap. 15 1093/13

Summary of the Code 9(12)

```
= Node "aaa" [ Node "bbbb" [ Node "ccc" [],
tree
                                         Node "dd"[]
                           ],
                           Node "eee"[],
                           Node "ffff" [ Node "gg" [],
                                         Node "hhh"[],
                                         Node "ii"[]
                           ]
              ٦
testtree w = putStr(pretty w (showTree tree))
testtree' w = putStr(pretty w (showTree' tree))
                                                        Chap. 15
```

Summary of the Code 10(12)

-- XML Example

- data XML = Elt String [Att] [XML] | Txt String
- data Att = Att String String
- showXML x = folddoc (<>) (showXMLs x)

showXMLs (Elt n a [])
= [text "<" <> showTag n a <> text "/>"
showXMLs (Elt n a c)
= [text "<" <> showTag n a <> text ">" <>

showFill showXMLs c <>
 text "</" <> text n <> text ">"]
showXMLs (Txt s) = map text (words s)

Chap. 15 1095/13

Summary of the Code 11(12)

showAtts (Att n v) = [text n <> text "=" <> text (quoted v)] = "\"" ++ s ++ "\"" quoted s showTag n a = text n <> showFill showAtts a showFill f [] = nilshowFill f xs = bracket "" (fill (concat (map f xs))) ""

Chap. 15 1096/13

Summary of the Code 12(12)

```
xm] =
 Elt "p"[Att "color" "red",
          Att "font" "Times",
          Att "size" "10"
        ] [ Txt "Here is some",
             Elt "em" [] [ Txt "emphasized"],
             Txt "text.",
             Txt "Here is a",
             Elt "a" [ Att "href" "http://www.eg.com/"]<sup>ap.10</sup>
                      [ Txt "link" ],
             Txt "elsewhere."
         ٦
                                                          Chap. 15
testXML w = putStr (pretty w (showXML xml))
```

Chap. 17

Background Reading

On an early imperative "Pretty Printer:"

 Derek Oppen. Pretty-printing. ACM Transactions on Programming Languages and Systems 2(4):465-483, 1980.

...and a functional realization of it:

 Olaf Chitil. Pretty Printing with Lazy Dequeues. In Proceedings of the ACM SIGPLAN Haskell Workshop (Haskell 2001), Universiteit Utrecht UU-CS-2001-23, 183-201, 2001. Chap. 15 1098/13

Background Reading (Cont'd)

Overview on the evolution of a Pretty Printer Library and origin of the development of the Prettier Printers proposed by Philip Wadler:

John Hughes. The Design of a Pretty-Printer Library. In Johan Jeuring, Erik Meijer (Eds.), Advanced Functional Programming, First International Spring School on Advanced Functional Programming Techniques. Springer-V., LNCS 925, 53-96, 1995.

...a variant is implemented in the Glasgow Haskell Compiler:

Simon Peyton Jones. Haskell pretty-printer library. 1997.
 www.haskell.org/libraries/#prettyprinting

Chap. 15 1099/13

Chapter 15: Further Reading (1)

- Manuel M.T. Chakravarty, Gabriele Keller. Einführung in die Programmierung mit Haskell. Pearson Studium, 2004. (Kapitel 13.1.2, Ausdrücke formatieren; Kapitel 13.2.1, Formatieren und Auswerten in erweiterter Version)
- Olaf Chitil. Pretty Printing with Lazy Dequeues. In Proceedings of the ACM SIGPLAN 2001 Haskell Workshop (Haskell 2001), Universiteit Utrecht UU-CS-2001-23, 183-201, 2001.

John Hughes. The Design of a Pretty-Printer Library. In Johan Jeuring, Erik Meijer (Eds.), Advanced Functional Programming, First International Spring School on Advanced Functional Programming Techniques. Springer-V., LNCS 925, 53-96, 1995. Chap. 15 91100/13

Chapter 15: Further Reading (2)

- Derek Oppen. Pretty-printing. ACM Transactions on Programming Languages and Systems 2(4):465-483, 1980.
- Tillmann Rendel, Klaus Ostermann. *Invertible Syntax Descriptions: Unifying Parsing and Pretty Printing*. In Proceedings of the 3rd ACM Haskell Symposium on Haskell (Haskell 2010), 1-12, 2010.
- Bryan O'Sullivan, John Goerzen, Don Stewart. Real World Haskell. O'Reilly, 2008. (Chapter 5, Writing a Library: Working with JSON Data – Pretty Printing a String, Fleshing Out the Pretty-Printing Library)

Chap. 15

Chapter 15: Further Reading (3)

- Simon Peyton Jones. Haskell pretty-printer library. 1997. www.haskell.org/libraries/#prettyprinting
- Philip Wadler. A Prettier Printer. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 223-243, 2003.

Chap. 15 1102/13

Chapter 16 Functional Reactive Programming

Chap. 16

Motivation

Hybrid systems are systems that are composed of

- continuous and
- ► discrete

components.

Chap. 16 1104/13

Mobile Robots

Mobile robots are special hybrid systems:

- From a physical perspective:
 - Continuous components: Voltage-controlled motors, batteries, range finders,...
 - Discrete components: Microprocessors, bumper switches, digital communication,...
- From a logical perspective:
 - Continuous notions: Wheel speed, orientation, distance from a wall,...
 - Discrete notions: Running into another object, receiving a message, achieving a goal,...

Chap. 16

16.3 1105/13

Objective of this Chapter

Desiging and implementing two

imperative-style languages for controlling robots which will be done in terms of a simulation (in order to allow running the simulations at home without having to buy (possibly expensive) robots first).

This will deliver two examples of a

domain specific language (DSL).

Simultaneously, it yields a nice application of the

- higher-order type (constructor) classes
 - Functor
 - Monad
 - Arrows

Chap. 16 1106/13 Reading for this Chapter

For Chapter 16.1:

 Paul Hudak. The Haskell School of Expression – Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 19, An Imperative Robot Language)

For Chapter 16.2:

Paul Hudak, Antony Courtney, Herik Nilsson, John Peterson. Arrows, Robots, and Functional Reactive Programming. Summer School on Advanced Functional Programming 2002, Springer-V., LNCS 2638, 159-187, 2003.

Remark:

Chapter 16.1 and 16.2 are independent of each other; they do not build on each other. Chap. 16

Chapter 16.1 An Imperative Robot Language

16.1 16.2 16.3 1108/13



The World of Robots – Illustration (2)

In more detail:

The world the robots live in

- ► is a finite two-dimensional grid of square form
 - equipped with walls
 - that might form rooms and might have doors
 - with placed gold coins on some grid points

The preceding illustration shows an example of a

- robot's world with one room full of gold coins: Eldorado!
- and a robot sitting in the centre of the world ready for exploring it!

16.1 1110/13

The World of Robots – Illustration (3) A robot's job:



...exploring the world, collecting treasures, leaving footprints!

16.1

The World of Robots – Illustration (4)

In more detail:

A robot's job

- is to explore its world, to collect the treasures in it, and to leave footprints of its exploration, i.e.,
 - to systematically stroll through its world, e.g., in the form of an outward-oriented spiral
 - picking up the gold coins it finds and saving them in its pocket
 - dropping gold coins at some grid points
 - marking its way with a colored pen

	4
	6
	7
	9
	10
	11
Chap.	12
Chap.	13
Chap.	14
Chap.	15
Chap.	16
16.1	
16.2	
16.3	
1112	/13

Objective

...enabling the robots to explore and shape their world!

In other words, we would like to write programs such as:

(1) drawSquare = (2) moveToWall = while (isnt blocked) do penDown do move move turnRight move turnRight (3) getRich = while (isnt blocked) \$ move turnRight do move checkAndPickCoin move

16.1 1113/13

Modeling the World

Modeling the world our robots live and act in:

type Grid = Array Position [Direction]

type Position = (Int,Int)

data Direction = North | East | South | West deriving (Eq, Show, Enum) 16.1 1114/13

Modeling the Robots (1)

The internal states of the robots are made up by:

- 1. Robot position
- 2. Robot orientation
- 3. Pen status (up or down)
- 4. Pen color
- 5. Placement of gold coins on the grid
- 6. Number of coins in the robot's pocket



Modeling the Robots (2)	
Modeling the internal states of the robots:	
data RobotState	
= RobotState	
{position :: Position	
, facing :: Direction	
, pen :: Bool	Chap. 6
, color :: Color	
, treasure :: [Position] , pocket :: Int	Chap. 8 Chap. 9 Chap. 10
}	Chap. 11
deriving Show	Chap. 12
where	Chap. 13
	Chap. 14
data Color = Black Blue Green Cyan	Chap. 15
Red Magenta Yellow White deriving (Eq, Ord, Bounded, Enum, Ix, Show, Read)	Chap. 16 16.1 16.2 16.3 1116/13
Remarks (1)

Note that the above definition takes advantage of Haskell's field-label syntax:

Field labels (here position, facing, pen, color, treasure, pocket) allow access to components by names instead of position without necessitating specific selector functions.

16.1

Remarks (2)

Robot states could have been equivalently be defined without referring to field label syntax:

...losing the advantage of accessing fields by names.

16.1

Remarks (3)

Illustrating the usage of field labels: Generating, accessing, modifying values of state components.

Example 1: Generating field values

The definition

s1 = RobotState (0,0) East True Green
 [(2,3),(7,9),(12,42)] 2 :: RobotState

is equivalent to

6.1 1119/13

Remarks (4)

Advantages of using field label syntax:

- It is more "informative."
- The order of fields gets irrelevant.

For example: The definition of s3

- s3 = RobotState
 - $\{ position = (0,0) \}$
 - , pocket = 2
 - , pen = True
 - , color = Green
 - , treasure = [(2,3),(7,9),(12,42)]
 - , facing = East
 - } :: RobotState

is equivalent to that of s2.

16.1 1120/13

Remarks (5)

Example 2: Accessing field values

position s2 ->> (0,0)
treasure s3 ->> [(2,3),(7,9),(12,42)]
color s3 ->> Green

Example 3: Modifying field values

Remarks (6)

Example 4: Using field names in patterns

jump (RobotState { position = (x,y) }) = (x+2,y+1)

Robots as a Member of Type Class Monad

Defining Robot as an algebraic data type

```
newtype Robot a
= Robot (RobotState -> Grid
                              -> Window -> IO (RobotState,a))
```

...allows making Robot an instance of type class Monad:

16.1 1123/13

Remarks (1)

Note that

requires function application "\$", not function composition "." (For clarity, Robot has been replaced by Rob (cp. next slide)). 16.1 1124/13

Remarks (2)

The Window argument

newtype Robot a = Rob (RobotState -> Grid -> Window -> IO (RobotState,a))

...allows to specify the window, in which the graphics is displayed.

16.1 1125/13

Robots – Simulation and Control

The implementation environment:

module Robot where import Array import List import Monad import SOEGraphics import Win32Misc (timeGetTime) import qualified GraphicsWindows as GW (getEvent)

Note:

- Graphics, SOEGraphics are two commonly used graphics libraries being Windows-compatible.
- Double-check the SOE homepage at haskell.org/soe regarding the availability of the modules SOEGraphics and GraphicsWindows.

16.1 1126/13

IRL – The Imperative Robot Language (1)

Key insight:

- Taking state as inputPossibly querying the state in some way
 - Returning a possibly modified state

...makes the imperative nature of IRL commands obvious.

16.1 1127/13

IRL – The Imperative Robot Language (2)

IRL commands and their implementation:

Commands not related to graphics:

right, left :: Direction -> Direction

right d = toEnum (succ (mod (fromEnum d) 4))
left d = toEnum (pred (mod (fromEnum d) 4))

Supporting functions for updating and querying states: updateState :: (RobotState -> RobotState) -> Robot () updateState u = Robot (\s _ -> return (u s, ())) augueryState :: (RobotState -> a) -> Robot a

queryState q = Robot (\s _ _ -> return (s, q s))

16.1 1128/13

The Type Class Enum (1)

... of the Standard Prelude:

Cha
Cha
Cha
Cha
Cha
Cha

toEnum, fromEnum =

... implementation is type-dependent

The Type Class Enum (2)		
The following equivalences hold:		
enumFrom n~ [n]enumFromThen n n'~ [n,n']enumFromTo n m~ [nm]enumFromThenTo n n' m~ [n,n'm]	Chap. 1 Chap. 2 Chap. 3 Chap. 4 Chap. 5	
Example: data Color = Red Orange Yellow Green	Chap. 6 Chap. 7 Chap. 8 Chap. 9	
Blue Indigo Violet instance Enum Color where 		
<pre>[RedGreen] ->> [Red, Orange, Yellow, Green] [Red, Yellow] ->> [Red, Yellow, Blue, Violet] fromEnum Blue ->> 4 toEnum 3 ->> Green</pre>	Chap. 13 Chap. 14 Chap. 15 Chap. 16 16.1 16.2 16.3 1130/13	

IRL – The Imperative Robot Language (3)

```
Commands for robot orientation:
```

```
turnLeft :: Robot ()
turnLeft =
 updateState (\s \rightarrow s {facing = left (facing s)})
turnRight :: Robot ()
turnRight =
 updateState (\s -> s {facing = right (facing s)})<sup>(ap) 9</sup></sup></sup>
turnTo :: Direction -> Robot ()
turnTo d = updateState (\s -> s {facing = d})
direction :: Robot Direction
direction = queryState facing
                                                        16.1
```

IRL – The Imperative Robot Language (4)

Chap. 2 Chap. 3

Commands for blockade checking:

blocked :: Robot Bool blocked = Robot \$ \s g _ -> return(s, facing s 'notElem' (g 'at' position s))¹⁰

Chap. 9 **S**) 10 Chap. 11 Chap. 12 Chap. 13 Chap. 14 Chap. 15 Chap. 16 16.1 16.2 16.3 1132/13

IRL – The Imperative Robot Language (5)

```
Commands for moving a robot:
  move :: Robot ()
  move =
   cond1 (isnt blocked)
    (Rob $ \s _ w -> do
      let newPos = movePos (position s) (facing s)
      graphicsMove w s newPos
      return (s {position = newPos}, ())
  movePos :: Position -> Direction -> Position
  movePos (x,y) d
           = case d of
                North \rightarrow (x,y+1)
                South \rightarrow (x,y-1)
                East \rightarrow (x+1,y)
                                                           16.1
                West \rightarrow (x-1,y)
                                                           1133/13
```

IRL – The Imperative Robot Language (6)

```
Commands for using the pen:
  penUp :: Robot ()
  penUp = updateState (\s -> s {pen = False})
  penDown :: Robot ()
  penDown = updateState (\s -> s {pen = True})
  setPenColor :: Color -> Robot ()
  setPenColor c = updateState (\s \rightarrow s \{color = c\})<sub>Chap.12</sub>
```

16.1

IRL – The Imperative Robot Language (7)

Commands for handling coins:
<pre>onCoin :: Robot Bool onCoin = queryState (\s -></pre>
<pre>coins :: Robot Int coins = queryState pocket</pre>

Contents

16.1 16.2 16.3 1135/13

IRL – The Imperative Robot Language (8)

```
More commands for handling coins:
  pickCoin :: Robot ()
  pickCoin =
   cond1 onCoin
    (Robot $ \s _ w ->
       do eraseCoin w (position s)
          return (s {treasure =
                       position s 'delete' treasure s,
                      pocket = pocket s+1}, ())
    )
                                                          16.1
```

IRL – The Imperative Robot Language (9)

```
More commands for handling coins:
  dropCoin :: Robot ()
  dropCoin =
   cond1 (coins >* return 0)
    (Robot $ \s _ w ->
       do drawCoin w (position s)
          return (s {treasure =
                         position s : treasure s,
                      pocket = pocket s-1}, ())
    )
```

16.1 1137/13 Logic and Control (1)

Logic and control functions: cond :: Robot Bool -> Robot a -> Robot a -> Robot a cond p c a = do pred <-pif pred then c else a cond1 p c = cond p c (return ())while :: Robot Bool -> Robot () -> Robot () while p b = cond1 p (b >> while p b)(||*) :: Robot Bool -> Robot Bool -> Robot Bool b1 ||* b2 = do p <- b1 if p then return True else b2

Chap. 15 Chap. 16 16.1 16.2 16.3 1138/13

Logic and Control (2)

Logic and control functions (cont'd): (&&*) :: Robot Bool -> Robot Bool -> Robot Bool b1 &&* b2 = do p <- b1 if p then b2 else return False isnt :: Robot Bool -> Robot Bool isnt = liftM not (>*) :: Robot Int -> Robot Int -> Robot Bool (>*)= liftM2 (>) (<*) :: Robot Int -> Robot Int -> Robot Bool (<*) = liftM2 (<)

16.1 16.2 16.3 1139/13

Logic and Control (3)

The higher-order functions liftM and liftM2 are defined in the library Monad (as well as liftM3,...,liftM5):

16.1 1140/13 Logic and Control (4)

It is worth noting:

- Basing the implementations of isnt, (>*) and (<*) on liftM and liftM2 allows to dispense the usage of special lift functions.
- No basing of the implementations of (||*) and (&&*) on liftM2 in order to avoid (unnecessary) strictness in their second arguments.

16.1

Further Data Structures

```
colors :: Array Int Color
 colors = array (0,7)
            [(0,Black),(1,Blue),(2,Green),(3,Cyan),
             (4,Red),(5,Magenta),(6,Yellow),(7,White)]
where (as a reminder!)
 data Color = Black | Blue | Green | Cyan
             | Red | Magenta | Yellow | White
   deriving (Eq, Ord, Bounded, Enum, Ix, Show, Read)
Note:
  Color is defined as in the library Graphics.
  Equivalently we could have defined more concisely:
```

colors :: Array Int Color colors = array (0,7) (zip [0..7] [Black..White])

16.1

Shaping the Robots' Initial World g0 The robots' world is a grid of type Array: type Grid = Array Position [Direction] We can access the grid points using: at :: Grid -> Position -> [Direction] at = (!)The size of the initial grid g0 is given by: size :: Int size = 20with \blacktriangleright centre (0,0) and corners (size,size), ((-size),size), 16 1 ((-size), (-size)) and (size, (-size)).

The Initial World g0 (1)

...and the 4 surrounding walls (no walls inside):

- Inner points of g0 are given by: interior = [North, South, East, West]
- Extremal points on the grid borders (north border, northeast corner, etc.) are given by:

16.1 1144/13

The Initial World g0 (2)

This allows:

...enumerating inner and border grid points using a list comprehension:

16.3 1145/13

The new World g1 that extends World g0 (1)

...evolves from building new walls using the array library functions (//):

(//) :: Ix a => Array a b -> [(a,b)] -> Array a b

Example: Application of (//)

Reversing the positions of "black" und "white" in colors:

```
colors//[(0,White),(7,Black)]
->> array (0,7)
       [(0,White),(1,Blue),(2,Green),(3,Cyan),
       (4,Red),(5,Magenta),(6,Yellow),
       (7,Black)] :: Array Integer Color
```

16.1 1146/13 The new World g1 that extends World g0 (2) Supporting functions for building new walls: -- Building horizontal and vertical walls mkHorWall, mkVerWall :: Int -> Int -> [(Position, [Direction])] -- Building west/east-oriented walls -- leading from (x1,y) to (x2,y)mkHorWall x1 x2 y = [((x,y), nb) | x < [x1..x2]] ++[((x,y+1), sb) | x < [x1..x2]]-- Building north/south-oriented walls -- leading from (x,y1) to (x,y2)mkVerWall y1 y2 x = [((x,y), eb) | y <- [y1..y2]] ++ [((x+1,y), wb) | y < - [y1..y2]]16.1

The new World g1 that extends World g0 (3)

World g1 evolves from world g0 by

building a west/east-oriented wall leading from (-5,10) to (5,10):

The World g2 that extends g0 (1)
Supporting functions for building a "room:"
mkBox :: Position -> Position
-> [(Position, [Direction])]
mkBox (x1, y1) (x2, y2)
= mkHorWall (x1+1) x2 y1 ++
mkHorWall (x1+1) x2 y2 ++
mkVerWall (y1+1) y2 x1 ++
mkVerWall (y1+1) y2 x2

Note:

- The above function creates two field entries for each of the four inner corners.
- After creation the value of these entries are still undefined.
- Using the function accum allows initializing these entries on-the-fly of their creation:

accum :: (Ix a) => (b -> c -> b)

-> Array a b -> [(a,c)] -> Array a b

The World g2 that extends g0 (2)

Recall the function accum:

accum :: (Ix a) => (b -> c -> b) -> Array a b -> [(a,c)] -> Array a b

The function accum

- is quite similar to the function (//).
- in case of replicated entries the function of the first argument is used for resolving conflicts.
- the List-library function intersect is suitable for this for the case of our example:

Example:

[South, East, West] 'intersect' [North, South, West] ->> [South, West] which corresponds to a northeast corner.

The World g2 that extends g0 (3)

Example: Building a room with (-10,5) as lower left corner and (-5,10) as upper right corner

using accum und intersect.

World g_2 then extends world g_0 :

g2 :: Grid g2 = accum intersect g0 (mkBox (-15,8) (2,17)) 16.1

The World g3 that extends g2

Continuing the example: Adding a door (to the middle of the top wall of the room)

using accum und union.

World g2 evolves to world g3:

16.1
Animation: Robot Graphics (1)

Animation

by means of incrementally updating the world.

To this end we make use of the function:

which makes use of the Graphics-library function drawInWindowNow.

16.1 1153/13

Animation: Robot Graphics (2)

The incremental update of the world must ensure

absence of interferences of graphics actions.

To this end we assume:

- 1. Grid points are 10 pixels apart.
- 2. Wall are drawn halfway between grid points.
- 3. Lines drawn by a robot's pen directly connects two grid points.
- 4. Coins are drawn as yellow circles just to the above and to to the left of a grid point.
- Erasing coins is done by drawing black circles over already existing yellow ones.

16 1 1154/13

Animation: Robot Graphics (3)

Using the below top level constants ensures the absence of interferences:

d d		Int 5	half the distance between grid points
wc, cc wc cc	=	Blue	color of walls color of coins
xWin, yWin xWin yWin	=	Int 600 500	

16.1 1155/13

Animation in Action (1)

Putting it all together.

User-control of program progress by the program's awaiting the user's hitting the spacebar:

16.1 1156/13

Animation in Action (2)

Running an IRL program:

```
runRobot :: Robot () -> RobotState -> Grid -> IO ()
runRobot (Robot sf) s g =
runGraphics $
do w <- openWindowEx "Robot World" (Just (0,0))
          (Just (xWin, yWin)) drawGraphic (Just 10)
    drawGrid w g
    drawCoins w s
    spaceWait w
    sfsgw
    spaceClose w
```

16.1

16.3 1157/13

Animation in Action (3)

Chap.
Chap. 9
Chap. 1
Chap. 1
Chap. 1
Chap. 1

Chap. 15 Chap. 16

16.1 16.2

16.3 1158/13

Animation in Action (4) Fixing a suitable starting state: s0 :: RobotState s0 = RobotState {position = (0,0) , pen = False . color = Red , facing = North , treasure = tr, pocket = 0} tr :: [Position] [(x,y) | x <- [-13,-11..1], y <- [9,11..15]] tr =

...i.e., all coins are placed inside of the room of grid g3.

16.1 1159/13

Animation in Action (5)

Last but not least:

```
main = runRobot spiral s0 g0
```

...leads to the "spiral" example discussed at the beginning of this chapter:



16.1

1160/13

```
Additional Supporting Functions (1)
 For drawing a grid:
  drawGrid :: Window -> Grid -> TO ()
  drawGrid w wld =
   let (low@(xMin,yMin),hi@(xMax,yMax))
                                         = bounds wld
       (x1, y1)
                                         = trans low
       (x2, y2)
                                         = trans hi
   in
    do
     drawLine w wc (x1-d,y1+d) (x1-d,y2-d)
     drawLine w wc (x1-d,y1+d) (x1+d,y2+d)
     sequence_ [drawPos w (trans (x,y)) (wld 'at' (x,y))
            | x <- [xMin..xMax], y <- [yMin..yMax]]</pre>
```

Chap. 16 16.1 16.2 16.3 1161/13

Additional Supporting Functions (2)

drawPos :: Window -> Point -> [Direction] -> IO ()
drawPos x (x,y) ds
= do if North 'notElem' ds
 then drawLine w wc (x-d,y-d) (x+d,y-d)
 else return ()
 if East 'notElem' ds
 then drawLine w wc (x+d,y-d) (x+d,y+d)
 else return ()

16.1

1162/13

Additional Supporting Functions (3) For dropping and erasing coins:

```
drawCoins
           :: Window \rightarrow RobotState \rightarrow IO ()
drawCoins w s = mapM_ (drawCoin w) (treasure s)
             :: Window -> Position -> IO ()
drawCoin
drawCoin w p
             =
let (x,y) = trans p
 in drawInWindowNow w
    (withColor cc (ellipse (x-5,y-1) (x-1,y-5)))
eraseCoin
            :: Window -> Position -> IO ()
eraseCoin w p
 let (x,y) = trans p
 in drawInWindowNow w
     (withColor Black (ellipse (x-5,y-1) (x-1,y-5))
```

16.3 1163/13

Further Supporting Functions (4)

```
graphicsMove :: Window -> RobotState
                              -> Position -> IO ()
graphicsMove w s newPos
 = do
    if pen s
       then
        drawLine w (color s) (trans (position s))
                               (trans newPos)
       else return ()
    getWindowTick w
                                                       16.1
```

1164/13

Further Supporting Functions (5)

trans :: Position -> Point trans (x,y) = (div xWin 2+2*d*x, div yWin 2-2*d*y) getWindowTick :: Window -> IO () -- causes a short delay after each robot move bounds :: Ix a => Array a b -> (a,a) -- from the Array-library; yields the bounds -- of an array argument 16.1 1165/13

Chapter 16.2 Robots on Wheels

16.2 1166/13

Outline

- A second simulation of
 - mobile robots by means of functional reactive programming.
- This time we will make use of
 - the type class Arrows that is another example of a higher-order type class that generalizes the concept of a monad.

16.2 1167/13

The Scenario (1)

Mobile robots are assumed to be configured as follows:

"Roboter haben zwei Räder, die von je einem Motor unabhängig voneinander angetrieben werden. Die relative Geschwindigkeit der Räder zueinander legt die Richtung fest, in die sich der Roboter bewegt. Bewegen sich beide Räder gleich schnell, fährt der Roboter geradeaus.

Roboter verfügen über unterschiedliche Sensoren wie etwa einen Berührungssensor, ob der Roboter auf ein Hindernis trifft, Entfernungssensor, um die Entfernung zum nächstgelegenen Objekt in einer bestimmten Richtung zu bestimmen (in der Folge nur für vorwärts, rückwärts, rechts und links), einen Objektsensor, der die aktuelle Position aller anderen Roboter liefert und ggf. die Position weiterer beweglicher Objekte wie z.B. von Bällen innerhalb einer bestimmten Entfernung vom Roboter (Objektsensoren etwa reali16.2 1168/13 siert durch visuelle Subsysteme oder Kommunikationssysteme zum Austausch von Koordinaten).

Roboter haben eine eindeutige Kennung (ID) und ggf. weitere (bei Bedarf) eingeführte Sensoren." 16.2 1169/13

Motivation of the Scenario: Robot Soccer

Robot soccer provides a motivation for such a scenario:

"Schreibe ein Programm "robocup soccer" wie folgt:

Erzeuge mithilfe von Wandsegmenten zwei Tore an jedem Spielfeldende.

Bestimme die Anzahl von Spielern pro Mannschaft und schreibe Steuerungsprogramme für diese Spieler. Zweckmäßigerweise sind die Steuerungsprogramme generisch für unterschiedliche Spielertypen, etwa für Torhüter, Stürmer, Verteidiger.

Erzeuge eine initiale Welt, in der der Ball am Anstoßpunkt im Mittelkreis liegt und jeder der Spieler strategisch günstig in der jeweils eigenen Spielhälfte und außerhalb des Mittelkreises positioniert ist. Jede Mannschaft mag die gleichen oder auch unterschiedliche Steuerungsprogramme nutzen."

Simulation Code for "Robots on Wheels"

...can be down-loaded at the Yampa homepage at

www.haskell.org/yampa

In the following we will consider some code snippets.

16.2 1171/13

Structure of the Program

```
module MyRobotShow where
 import AFrob
 import AFrobRobotSim
 main :: IO ()
 main = runSim (Just world) rcA rcB
 world :: WorldTemplate
 world = \dots
 rcA :: SimbotController -- controller for simbot A'shap 12
 rcA = ...
rcB :: SimbotController -- controller for simbot B's<sup>chap.15</sup>
 rcB = \ldots
                                                            16.2
                                                            1172/13
```

The World

type WorldTemplate = [ObjectTemplate]

```
data ObjectTemplate =
  OTBlock
             otPos :: Position2
                                 -- Square obstacle
  OTVWall
            otPos :: Position2
                                 -- Vertical wall
  OTHWall
          otPos :: Position2
                                 -- Horizontal wall
  OTBall otPos
                    :: Position2
                                 -- Ball
  OTSimbotA otRId
                    :: RobotId.
                                 -- Simbot A robot
             otPos
                    :: Position2.
             otHdng :: Heading
  OTSimbotB
            otRId :: RobotId,
                                 -- Simbot B robot
             otPos
                    :: Position2,
             otHdng :: Heading
```

16.2 1173/13

Robot Control

```
type SimbotController =
     SimbotProperties -> SF SimbotInput SimbotOutput
Class HasRobotProperties i where
rpType :: i -> RobotType -- Type of robot
rpId :: i -> RobotId
                               -- Identity of robot
rpDiameter :: i -> Length -- Distance between wheels
rpAccMax :: i -> Acceleration -- Max translational acchap.10
rpWSMax :: i -> Speed
                               -- Max wheel speed
type RobotType = String
type RobotId = Int
                                                     16.2
```

```
1174/13
```

Robot Simulation in Action

Chap. 9
Chap. 1

Chap. 11 Chap. 12 Chap. 13 Chap. 14 Chap. 14 Chap. 15 Chap. 16 16.1 16.2 16.3 1175/13

Robot Control

```
rcA :: SimbotController
rcA rProps =
  case rrpId rProps of
    1 -> rcA1 rProps
    2 -> rcA2 rProps
    3 -> rcA3 rProps
rcA1, rcA2, rcA3 :: SimbotController
rcA1 = \ldots
rcA2 = ...
rcA3 = \dots
```

Contents

16.2 16.3 1176/13

```
Robot Actions: Control Programs (1)
A stationary robot:
 rcStop :: SimbotController
 rcStop _ = constant (mrFinalize ddBrake)
A blind robot moving at constant speed:
 rcBlind1 =
    constant (mrFinalize $ ddVelDiff 10 10)
A blind robot moving at half the maximum speed:
 rcBlind2 rps =
    let max = rpWSMax rps
    in constant (mrFinalize $
                      ddVelDiff (max/2) (max/2))
                                                          16.2
                                                          1177/13
```

Robot Actions: Control Programs (2)

A robot rotating at a pre-given speed:

rcTurn :: Velocity -> SimbotController rcTurn vel rps = let vMax = rpWSMax rps rMax = 2 * (vMax - vel) / rpDiameter rps in constant (mrFinalize \$ ddVelTR vel rMax) 16.2 1178/13

Classes of Robots (1)

- Usually, there are different types of robots with different features (2 wheels, 3 wheels, camera, sonar, speaker, blinker, etc.)
- The kind of a robot is fixed by its input and output types.

The kind of robots is encoded in input and output classes together with the functions operating on them.

16.2 1179/13

Kinds of Robots (2)

Input classes and functions operating on them:

class HasRobotStatus i where rsBattStat :: i -> BatteryStatus -- Current battery -- status rsIsStuck :: i -> Bool -- Currently stuck -- or not stuck data BatteryStatus = BSHigh | BSLow | BSCritical deriving (Eq, Show) -- derived event sources: rsBattStatChanged :: HasRobotStatus i => SF i (Event BatteryStatus) ()^C)^{ap. 14} rsBattStatLow :: HasRobotStatus i => SF i (Event ()^{Chap. 15} rsBattStatCritical :: HasRobotStatus i => SF i (Event $O_{2}^{Chap. 16}$:: HasRobotStatus i => SF i (Event rsStuck 16.2

1180/13

Classes of Robots (3)

```
class HasOdometry where
  odometryPosition :: i -> Position2 -- Current
                                     -- position
  odometryHeading :: i -> Heading -- Current
                                     -- heading
class HasRangeFinder i where
  rfRange :: i -> Angle -> Distance
  rfMaxRange :: i -> Distance
-- derived range finders:
rfFront :: HasRangeFinder i => i -> Distance
rfBack :: HasRangeFinder i => i -> Distance
rfLeft :: HasRangeFinder i => i -> Distance
rfRight :: HasRangeFinder i => i -> Distance
```

16.1 16.2 1181/13

Classes of Robots (4)

```
class HasAnimateObjectTracker i where
 aotOtherRobots :: i -> [(RobotType, Angle, Distance)] ap 4
                :: i -> [(Angle, Distance)]
 aotBalls
class HasTextualConsoleInput i where
tciKey :: i -> Maybe Char
tciNewKeyDown :: HasTextualConsoleInput i =>
                   Maybe Char -> SF i (Event Char)
tciKeyDown :: HasTextualConsoleInput i =>
                   SF i (Event Char)
```

16.2 16.3 1182/13

Classes of Robots (5)

Output classes and functions operating on them:

```
class MergeableRecord o => HasDiffDrive o where
 ddBrake :: MR o -- Brake both wheels
ddVelDiff :: Velocity -> Velocity
                             \rightarrow MR o -- Set wheel
                                     -- velocities
 ddVelTR :: Velocity -> RotVel
                             -> MR o -- Set veloc.
                                     -- and rotat.
class MergeableRecord o =>
  HasTextConsoleOutput o where
    tcoPrintMessage :: Event String -> MR o
```

16.2 1183/13

Arrows and Mobile Robots

SF is an instance of class Arrow: SF a b = Signal a -> Signal b Signal a = Time -> a type Time = Double

Note:

Values of type SF are signal transformers resp. signal functions; therefore the name SF. 16.2 1184/13

Chapter 16.3 More on the Background of FRP

16.3 1185/13

Origins of FRP

The origins of functional reactive programming (FRP) lie in functional reactive animation (FRAn):

- Conal Elliot, Paul Hudak. Functional Reactive Animation. In Proceedings of the 2nd ACM SIGPLAN 1997 International Conference on Functional Programming (ICFP'97), 263 - 273, 1997.
- Conal Elliot. Functional Implementations of Continuous Modeled Animation. In Proceedings of PLILP/ALP'98, Springer-Verlag, 1998.

16.3 1186/13

Seminal Works on FRP

Seminal works on function reactive programming (FRP):

 Zhanyong Wan, Paul Hudak. Functional Reactive Programming from First Principles. In Proceedings of the ACM SIGPLAN 2000 Conference on Programming Languages Design and Implementation (PLDI 2000), ACM Press, 2000.

http://www.haskell.org/frp/manual.html

- John Peterson, Zhanyong Wan, Paul Hudak, Henrik Nilsson. Yale FRP User's Manual. Department of Computer Science, Yale University, January 2001.
- Henrik Nilsson, Antony Courtney, John Peterson. Functional Reactive Programming, Continued. In Proceedings of the ACM SIGPLAN'02 Haskell Workshop, October 2002.

Applications of FRP (1)

On Functional Animation Languages (FAL):

- Paul Hudak. The Haskell School of Expression Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 15, A Module of Reactive Animations)
- On Functional Reactive Robotics (FRob):
 - Izzet Pembeci, Henrik Nilsson, Gregory Hager. Functional Reactive Robotics: An Exercise in Principled Integration of Domain-Specific Languages. In Proceedings of the International Conference on Principles and Practice of Declarative Programming (PPDP'02), October 2002.
 - John Peterson, Gregory Hager, Paul Hudak. A Language for Declarative Robotic Programming. In Proceedings of the International Conference on Robotics and Automation, 1999.

16.3 1188/13
Applications of FRP (2)

On Functional Vision Systems (FVision):

 Alastair Reid, John Peterson, Gregory Hager, Paul Hudak. Prototyping Real-Time Vision Systems: An Experiment in DSL Design. In Proceedings of the International Conference on Software Engineering, May 1999.

On Functional Reactive User Interfaces (FRUIt):

 Antony Courtney, Conal Elliot. Genuinely Functional User Interfaces. In Proceedings of the 2001 Haskell Workshop, September 2001. 16.3 1189/13

Applications of FRP (3)

Towards Real-Time FRP (RT-FRP):

- Zhanyong Wan, Walid Taha, Paul Hudak. Real-Time FRP. In Proceedings of the 6th ACM SIGPLAN'01 International Conference on Functional Programming (ICFP 2001), ACM Press, 2001.
- Zhanyong Wan. Functional Reactive Programming for Real-Time Embedded Systems. PhD thesis. Department of Computer Science, Yale University, December 2002.

Towards Event-Driven FRP (ED-FRP):

 Zhanyong Wan, Walid Taha, Paul Hudak. Event-Driven FRP. In Proceedings of the 4th International Symposium on Practical Aspects of Declarative Languages (PADL 2002), ACM Press, January 2002. 16.3 1190/13

Chapter 16: Further Reading (1)

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- Antony Courtney, Conal Elliot. *Genuinely Functional User Interfaces*. In Proceedings of the 2001 Haskell Workshop (Haskell 2001), September 2001.
- Conal Elliot. Functional Implementations of Continuous Modeled Animation. In Proceedings of the 10th International Symposium on Principles of Declarative Programming, held jointly with the International Conference on Algebraic and Logic Programming (PLILP/ALP'98), Springer-V., LNCS 1490, 284-299, 1998.

16.3 1191/13

Chapter 16: Further Reading (2)

- Conal Elliot, Paul Hudak. Functional Reactive Animation. In Proceedings of the 2nd ACM SIGPLAN 1997 International Conference on Functional Programming (ICFP'97), 263-273, 1997.
- David Harel, Assaf Marron, Gera Weiss. Behavioral Programming. Communications of the ACM 55(7):90-100, 2012.
- Paul Hudak. The Haskell School of Expression Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 15, A Module of Reactive Animations; Chapter 18, Higher-Order Types; Chapter 19, An Imperative Robot Language)

16.3 1192/13

Chapter 16: Further Reading (3)

- Paul Hudak, Antony Courtney, Henrik Nilsson, John Peterson. Arrows, Robots, and Functional Reactive Programming. In Johan Jeuring, Simon Peyton Jones (Eds.) Advanced Functional Programming – Revised Lectures. Springer-V., LNCS Tutorial 2638, 159-187, 2003.
- John Hughes. *Generalising Monads to Arrows*. Science of Computer Programming 37:67-111, 2000.
- Henrik Nilsson, Antony Courtney, John Peterson. Functional Reactive Programming, Continued. In Proceedings of the ACM SIGPLAN Workshop on Haskell (Haskell 2002), 51-64, 2002.
 - Johan Nordlander. *Reactive Objects and Functional Programming*. PhD thesis. Chalmers University of Technology, 1999.

16.3 1193/13

Chapter 16: Further Reading (4)

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- Ross Paterson. Arrows and Computation. In Jeremy Gibbons, Oege de Moor (Eds.), The Fun of Programming. Palgrave MacMillan, 201-222, 2003.
- Izzet Pembeci, Henrik Nilsson, Gregory D. Hager. Functional Reactive Robotics: An Exercise in Principled Integration of Domain-Specific Languages. In Proceedings of the 4th International ACM SIGPLAN Conference on Principles and Practice of Declarative Programming (PPDP 2002), 168-179, 2002.

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Chapter 16: Further Reading (5)

- John Peterson, Gregory D. Hager, Paul Hudak. A Language for Declarative Robotic Programming. In Proceedings of the IEEE International Conference on Robotics and Automation (ICRA'99), Vol. 2, 1144-1151, 1999.
- John Peterson, Paul Hudak, Conal Elliot. Lambda in Motion: Controlling Robots with Haskell. In Proceedings of the 1st International Workshop on Practical Aspects of Declarative Languages (PADL'99), Springer-V., LNCS 1551, 91-105, 1999.
- John Peterson, Zhanyong Wan, Paul Hudak, Henrik Nilsson. Yale FRP User's Manual. Department of Computer Science, Yale University, January 2001. www.haskell.org/frp/manual.html

16.3 1195/13

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- Alastair Reid, John Peterson, Gregory Hager, Paul Hudak. Prototyping Real-Time Vision Systems: An Experiment in DSL Design. In Proceedings of the 1999 International Conference on Software Engineering (ICSE'99), 484-493, 1999.
- Zhanyong Wan. Functional Reactive Programming for Real-Time Embedded Systems. PhD Thesis, Department of Computer Science, Yale University, December 2002.
 - Zhanyong Wan, Paul Hudak. Functional Reactive Programming from First Principles. In Proceedings of the ACM SIGPLAN 2000 Conference on Programming Language Design and Implementation (PLDI 2000), 242-252, 2000.

16.3 1196/13

Chapter 16: Further Reading (7)

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- Zhanyong Wan, Walid Taha, Paul Hudak. Event-Driven FRP. In Proceedings of the 4th International Symposium on Practical Aspects of Declarative Languages (PADL 2002), Springer-V., LNCS 2257, 155-172, 2002.

16.3 1197/13

Part VI

Extensions and Prospectives

16.3 1198/13

Chapter 17

Extensions to Parallel and "Real World" Functional Programming

Chap. 16 Chap. 17 17.1 1199/13

Chapter 17.1 Parallelism in Functional Languages

17.1 1200/13

Motivation

Recall:

 Konrad Hinsen. The Promises of Functional Programming. Computing in Science and Engineering 11(4):86-90, 2009.

...adopting a functional programming style could make your programs more robust, more compact, and **more** easily parallelizable. 17.11201/13

Reading for this Chapter

Kapitel 21, Massiv Parallele Programme Peter Pepper, Petra Hofstedt. Funktionale Programmierung, Springer-V., 2006. (In German).

17.1 1202/13

Parallelism in Imperative Languages

Predominant:

- Data-parallel Languages (e.g. High Performance Fortran)
- ► Libraries (PVM, MPI) ~→ Message Passing Model (C, C++, Fortran)

17.1 1203/13

Parallelism in Functional Languages

Predominant:

- Implicit (expression) parallelism
- Explicit parallelism
- Algorithmic skeletons

ap. 1 ap. 2 ap. 3 ap. 4

Chap. 5

Chap. 6

Chap. 7

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. ...

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Thop 13

ban 14

Chap 16

Chap. 17

17.1 1204/13

Implicit Parallelism

...also known as expression parallelism.

Let f(e1,...,en) be a functional expression:

Then

- Arguments (and functions) can be evaluated in parallel.
- Most important advantage: Parallelism for free! No effort for the programmer at all.
- Most important disadvantage: Results often unsatisfying; e.g. granularity, load distribution, etc. is not taken into account.

Summing up, expression parallelism is

easy to detect (i.e., for the compiler) but hard to fully exploit. 17.11205/13

Explicit Parallelism

By means of

- Introducing meta-statements (e.g. to control the data and load distribution, communication)
- Most important advantage: Often very good results thanks to explicit hands-on control of the programmer.
- Most important disadvantage: High programming effort and loss of functional elegance.

17.11206/13

Algorithmic Skeletons

- ...a compromise between
 - explicit imperative parallel programming
 - implicit functional expression parallelism

17.1 1207/13

In the following

We assume a scenario with

- Massively parallel systems
- Algorithmic skeletons

17.1 1208/13

Massively Parallel Systems

...characterized by

- large number of processors with
 - local memory
 - communication by message exchange
- MIMD-Parallel Processor Architecture (Multiple Instruction/Multiple Data)

Here we restrict ourselves to:

 SPMD-Programming Style (Single Program/Multiple Data) 17.11209/13

Algorithmic Skeletons

Algorithmic skeletons

- represent typical patterns for parallelization (Farm, Map, Reduce, Branch&Bound, Divide&Conquer,...)
- are easy to instantiate for the programmer
- allow parallel programming at a high level of abstraction

17.11210/13

Implementation of Algorithmic Skeletons

... in functional languages

- by special higher-order functions
- with parallel implementation
- embedded in sequential languages

Advantages:

- Hiding of parallel implementation details in the skeleton
- Elegance and (parallel) efficiency for special application patterns.

17.1 1211/13

Example: Parallel Map on Distributed List

Consider the higher-order function map on lists:

Observation:

 Applying f to a list element does not depend on other list elements.

Obviously:

Dividing the list into sublists followed by parallel application of map to the sublists: parallelization pattern Farm. 17.1 1212/13

Parallel Map on Distributed Lists Illustration:



[b1,...,bk, bk+1,...,bm, bm+1,...bm]

Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer, 2006, S. 445. 17.1 1213/13

On the Implementation

Implementing the parallel map function requires

 special data structures, which take into account the aspect of distribution (ordinary lists are inefficient for this purpose).

Skeletons on distributed data structures

so-called data-parallel skeletons.

Note the difference:

- Data-parallelism: Supposes an a priori distribution of data on different processors.
- Task-parallelism: Processes and data to be distributed are not known a priori, hence dynamically generated.

17.11214/13

Programming of a Parallel Application

...using algorithmic skeletons:

- Recognizing problem-inherent parallelism.
- Selecting an adequate data distribution (granularity).
- Selecting a suitable skeleton from a library.
- Instantiating a problem-specific skeleton.

Remark:

 Some languages (e.g. Eden) support the implementation of skeletons (in addition to those which might be provided by a library). 17.11215/13

Data Distribution on Processors

... is crucial for

- the structure of the complete algorithm
- efficiency

The hardness of the distribution problems depends on

- Independence of all data elements (like in the map-example): Distribution is easy.
- Independence of subsets of data elements.
- Complex dependences of data elements: Adequate distribution is challenging.

Auxiliary means:

So-called covers (investigated by various researchers).

17.11216/13

Covers

...describe the

decomposition and communication pattern of a data structure.

17.1 1217/13

Illustration of a Simple List Cover

Distributing a list on 3 processors p_0 , p_1 , and p_2 :



Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer, 2006, S. 446. 17.1

1218/13

Illustration of a List Cover with Overlapping Elements



Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer, 2006, S. 446.

17.1 1219/13

General Cover Structure

Cover =	
Type S a Whole object	
C b Cover	
U c Local sub-objects	
split :: S a \rightarrow C (U a) Decomposing the	
original object	
glue :: C (U a) \rightarrow S a $$ Composing the	
original object	Chap.

It is required:

glue . split = id

Note: The above code snippet is not (valid) Haskell.



Implementation in a Programming Language

Implementing covers requires support for

- the specification of covers.
- ▶ the programming of algorithmic skeletons on covers.
- the provision of often used skeletons in libraries.

lt is

currently a hot research topic in functional programming.

17.11221/13

Last but not least

Implementing skeletons

by message passing via skeleton hierarchies.

17.1 1222/13

Chapter 17.1: Further Reading (1)

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17.11223/13

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- Murray Cole. Algorithmic Skeletons: Structured Management of Parallel Computation. The MIT Press, 1989.
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17.11224/13
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- Bryan O'Sullivan, John Goerzen, Don Stewart. Real World Haskell. O'Reilly, 2008. (Chapter 24, Concurrent and Multicore Programming)
- Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer-V., 2006. (Kapitel 21, Massiv Parallele Programme)
- Simon Peyton Jones, Andrew Gordon, Sigbjorn Finne. Concurrent Haskell. In Conference Record of the 23rd ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages (POPL'96), 295-308, 1996.

17.11225/13

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- Robert F. Pointon, Philip W. Trinder, Hans-Wolfgang Loidl. The Design and Implementation of Glasgow Distributed Haskell. In Proceedings of the 12th International Workshop on Implementation of Functional Languages (IFL 2000), LNCS 2011, Springer-V., 53-70, 2000.
- Fethi Rabhi, Guy Lapalme. Algorithms A Functional Programming Approach. Addison-Wesley, 1999. (Chapter 10.3, Parallel Algorithms)

17.11226/13

Chapter 17.1: Further Reading (5)

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- Philip W. Trinder, Hans-Wolfgang Loidl, Robert F. Pointon. Parallel and Distributed Haskells. Journal of Functional Programming 12(4&5):469-510, 2002.

17.1 1227/13

Chapter 17.2 Haskell for "Real World Programming"

Chap. 12 Chap. 13 Chap. 14 Chap. 15 Chap. 16 Chap. 17 17.1 1228/13

"Real World" Haskell (1)

Haskell these days provides considerable, mature, and stable support for:

 Systems Programming (Network) Client and Server Programming Data Base and Web Programming Multicore Programming Foreign Language Interfaces Graphical User Interfaces ► File I/O and filesystem programming Automated Testing, Error Handling, and Debugging Performance Analysis and Tuning

1/229/13

"Real World" Haskell (2)

This support, which comes mostly in terms of

sophisticated libraries

makes Haskell a reasonable choice for addressing and solving

Real World Problems

since such a choice depends much on the ability and support a programming language (environment) provides for linking and connecting to the "outer world."

17.1 1230/13

Chapter 17.2: Further Reading (1)

- Magnus Carlsson, Thomas Hallgren. Fudgets A Graphical User Interface in a Lazy Functional Language. In Proceedings of the 6th ACM International Conference on Functional Programming Languages and Computer Architecture (FPCA'93), 321-330, 1993.
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Chapter 17.2: Further Reading (2)

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- General Community." Hackage: A Repository for Open Source Haskell Libraries. hackage.haskell.org
- "Haskell community." Haskell wiki.
 haskell.org/haskellwiki/Applications_and_libraries^{Chap. 10}
- Useful search engines: Hoogle and Hayoo. www.haskell.org/hoogle, holumbus.fh-wedel.de/hayoo/hayoo.html

Chap. 15

Chap. 16

Chap. 17 17.1 12233/13

Chapter 18 Conclusions and Prospectives

G12934 /13

C1235/43

Research Venues, Research Topics, and More

...for functional programming and functional programming languages:

- Research/publication/dissemination venues
 - Conference and Workshop Series
 - Archival Journals
 - Summer Schools
- Research Topics
- ► Functional Programming in the Real World

Relevant Conference and Workshop Series

For functional programming:

- Annual ACM SIGPLAN International Conference on Functional Programming (ICFP) Series, since 1996.
- Annual Symposium on Functional and Logic Programming (FLPS) Series, since 2000.
- Annual ACM SIGPLAN Haskell Workshop Series, since 2002.
- HAL workshop series, since 2006.

For programming in general:

- Annual ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages and Systems (POPL), since 1973.
- Annual ACM SIGPLAN Conference on Programming Language Design and Implementation PLDI), since 1988 (resp. 1973).

G1236/13

Relevant Archival Journals

For functional programming:

► Journal of Functional Programming, since 1991.

For programming in general:

- ACM Transactions on Programming Languages and Systems (TOPLAS), since 1979.
- ► ACM Computing Surveys, since 1969.

G1237 /13

Focused on functional programming:

 Summer School Series on Advanced Functional Programming. Springer-V., LNCS series. G1238/43

Hot Research Topics (1)

...in theory and practice of functional programming considering the 2012 Call for Papers of the Haskell Symposium:

"The purpose of the Haskell Symposium is to discuss experiences with Haskell and future developments for the language.

Topics of interest include, but are not limited to:

- Language Design, with a focus on possible extensions and modifications of Haskell as well as critical discussions of the status quo;
- Theory, such as formal treatments of the semantics of the present language or future extensions, type systems, and foundations for program analysis and transformation;
- Implementations, including program analysis and transformation, static and dynamic compilation for sequential, parallel, and distributed architectures, memory management as well as foreign function and component interfaces;

G1239/13

Hot Research Topics (2)

- Tools, in the form of profilers, tracers, debuggers, pre-processors, testing tools, and suchlike;
- Applications, using Haskell for scientific and symbolic computing, database, multimedia, telecom and web applications, and so forth;
- Functional Pearls, being elegant, instructive examples of using Haskell;
- Experience Reports, general practice and experience with Haskell, e.g., in an education or industry context.

More on Haskell 2012, Copenhagen, DK, 13 Sep 2012: http://www.haskell.org/haskell-symposium/2012/ G1240/13

Hot Research Topics (3)

...in theory and practice of functional programming considering the 2012 Call for Papers of ICFP:

"ICFP 2012 seeks original papers on the art and science of functional programming. Submissions are invited on all topics from principles to practice, from foundations to features, and from abstraction to application. The scope includes all languages that encourage functional programming, including both purely applicative and imperative languages, as well as languages with objects, concurrency, or parallelism.

Topics of interest include (but are not limited to):

Language Design: concurrency and distribution; modules; components and composition; metaprogramming; interoperability; type systems; relations to imperative, object-oriented, or logic programming G12491/13

Hot Research Topics (4)

- Implementation: abstract machines; virtual machines; interpretation; compilation; compile-time and run-time optimization; memory management; multi-threading; exploiting parallel hardware; interfaces to foreign functions, services, components, or low-level machine resources
- Software-Development Techniques: algorithms and data structures; design patterns; specification; verification; validation; proof assistants; debugging; testing; tracing; profiling
- Foundations: formal semantics; lambda calculus; rewriting; type theory; monads; continuations; control; state; effects; program verification; dependent types
- Analysis and Transformation: control-flow; data-flow; abstract interpretation; partial evaluation; program calculation

G1242/13

Hot Research Topics (5)

- Applications and Domain-Specific Languages: symbolic computing; formal-methods tools; artificial intelligence; systems programming; distributed-systems and web programming; hardware design; databases; XML processing; scientific and numerical computing; graphical user interfaces; multimedia programming; scripting; system administration; security
- Education: teaching introductory programming; parallel programming; mathematical proof; algebra
- Functional Pearls: elegant, instructive, and fun essays on functional programming
- Experience Reports: short papers that provide evidence that functional programming really works or describe obstacles that have kept it from working"

G1243/13

Contest Announcement at ICFP 2012 (1)

The ICFP Programming Contest 2012 is the 15th instance of the annual programming contest series sponsored by The ACM SIGPLAN International Conference on Functional Programming. This year, the contest starts at 12:00 July 13 Friday UTC and ends at 12:00 July 16 Monday UTC. There will be a lightning division, ending at 12:00 July 14 Saturday UTC.

The task description will be published at icfpcontest2012.wordpress.com/task when the contest starts. Solutions to the task must be submitted online before the contest ends. Details of the submission procedure will be announced along with the contest task.

This is an open contest. Anybody may participate except for the contest organisers and members of the same group as the contest chairs. No advance registration or entry fee is required.

G12444 /13

Contest Announcement at ICFP 2012 (2)

Any programming language(s) may be used as long as the submitted program can be run by the judges on a standard Linux environment with no network connection. Details of the judges environment will be announced later.

There will be cash prizes for the first and second place teams, the team winning the lightning divison, and a discretionary judges prize. There may also be travel support for the winning teams to attend the conference. (The prizes and travel support are subject to the budget plan of ICFP 2012 pending approval by ACM.)...

More on ICFP 2012, Copenhagen, DK, 10-12 Sep 2012: http://icfpconference.org/icfp2012/cfp.html G1245/13

Contest Announcement at ICFP 2013

- This year's contest will take place from August 8, 2013 to August 11, 2013.
- Detailed information on it will be announced soon.
- Stay tuned for news on this year's contest at research.microsoft.com/en-us/events/icfpcontest2013.g

More on ICFP 2013, Boston, MA, 25-27 Sep 2013: http://icfpconference.org/icfp2013

G12476/493

Functional Programming in the Real World

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G1247/43

Recall Edsger W. Dijkstra's Prediction

The clarity and economy of expression that the language of functional programming permits is often very impressive, and, but for human inertia, functional programming can be expected to have a brilliant future.^(*)

> Edsger W. Dijkstra (11.5.1930-6.8.2002) 1972 Recipient of the ACM Turing Award

^(*) Quote from: Introducing a course on calculi. Announcement of a lecture course at the University of Texas at Austin, 1995.

G1248/13

In the Words of John Carmack

Sometimes, the elegant implementation is a function. Not a method. Not a class. Not a framework. Just a function.

John Carmack

G12409/493

Chapter 18: Further Reading (1)

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G1250/13

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G1252/13

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Reading

... for deepened and independent studies.

Textbooks

- II Monographs
- III Volumes
- IV Articles
- ► V Haskell 98 Language Definition
- ► V The History of Haskell

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Appendix

Mathematical Foundations

Α

A.1 Sets and Relations

Sets and Relations (1)

Definition (A.1.1)

Let M be a set and R a relation on M, i.e. $R \subseteq M \times M$. Then R is called

- reflexive iff $\forall m \in M. m R m$
- ▶ transitive iff $\forall m, n, p \in M$. $m R n \land n R p \Rightarrow m R p$
- ▶ anti-symmetric iff $\forall m, n \in M$. $m R n \land n R m \Rightarrow m = n$

Related notions (though less important for us here):

Definition (A.1.2)

Let M be a set and $R \subseteq M \times M$ a relation on M. Then R is called

- ▶ symmetric iff $\forall m, n \in M$. $m R n \iff n R m$
- ▶ total iff $\forall m, n \in M$. $m R n \lor n R m$

A.2

Partially Ordered Sets

Partially Ordered Sets

Definition (A.2.1, Quasi-Order, Partial Order) A relation R on M is called a quasi-order iff R is reflexive and transitive partial order iff R is reflexive, transitive, and anti-symmetric For the sake of completeness we recall: Definition (A.2.2, Equivalence Relation) A relation R on M is called an equivalence relation iff R is reflexive, transitive, and symmetric

...a partial order is an anti-symmetric quasi-order, an equivalence relation a symmetric quasi-order.

Remark: We here use terms like "partial order" as a short hand for the more accurate term "partially ordered set."

Bounds, least and greatest Elements

Definition (A.2.3, Bounds, least/greatest Elements) Let (Q, \sqsubseteq) be a quasi-order, let $q \in Q$ and $Q' \subseteq Q$. Then q is called

- upper (lower) bound of Q', in signs: Q' ⊑ q (q ⊑ Q'), if for all q' ∈ Q' holds: q' ⊑ q (q ⊑ q')
- least upper (greatest lower) bound of Q', if q is an upper (lower) bound of Q' and for every other upper (lower) bound q̂ of Q' holds: q ⊑ q̂ (q̂ ⊑ q)
- ▶ greatest (least) element of Q, if holds: $Q \sqsubseteq q$ ($q \sqsubseteq Q$)

Existence and Uniqueness of Bounds

We have:

- Given a partial order, least upper and greatest lower bounds are uniquely determined, if they exist.
- Given existence (and thus uniqueness), the least upper (greatest lower) bound of a set P' ⊆ P of the basic set of a partial order (P, ⊑) is denoted by ∐ P' (□P'). These elements are also called supremum and infimum of P'.
- Analogously this holds for least and greatest elements.
 Given existence, these elements are usually denoted by ⊥ and ⊤.

A.3 Lattices

Lattices and Complete Lattices

Definition (A.3.1, (Complete) Lattice) Let (P, \sqsubseteq) be a partial order. Then (P, \sqsubseteq) is called a

- lattice, if each finite subset P' of P contains a least upper and a greatest lower bound in P
- complete lattice, if each subset P' of P contains a least upper and a greatest lower bound in P

...(complete) lattices are special partial orders.

Complete Partially Ordered Sets

A.4

Complete Partial Orders

...a slightly weaker notion that, however, is often sufficient in computer science and thus often a more adequate notion:

- Definition (A.4.1, Complete Partial Order) Let (P, \sqsubseteq) be a partial order.
- Then (P, \sqsubseteq) is called
 - complete, or shorter a CPO (complete partial order), if each ascending chain C ⊆ P has a least upper bound in P.

Remark

We have:

A CPO (C, ⊑) (more accurate would be: "chain-complete partially ordered set (CCPO)") has always a least element. This element is uniquely determined as the supremum of the empty chain and usually denoted by ⊥:
 ⊥=_{df} □ Ø.

Chains

Definition (A.4.2, Chain)

Let (P, \sqsubseteq) be a partial order.

- A subset $C \subseteq P$ is called
 - chain of P, if the elements of C are totally ordered. For C = {c₀ ⊑ c₁ ⊑ c₂ ⊑ ...} ({c₀ ⊒ c₁ ⊒ c₂ ⊒ ...}) we also speak more precisely of an ascending (descending) chain of P.

A chain C is called

▶ finite, if *C* is finite; infinite otherwise.

Finite Chains, finite Elements

Definition (A.4.3, Chain-finite)

A partial order (P, \sqsubseteq) is called

 chain-finite (German: kettenendlich) iff P does not contain infinite chains

Definition (A.4.4, Finite Elements)

An element $p \in P$ is called

- ▶ finite iff the set $Q =_{df} \{q \in P \mid q \sqsubseteq p\}$ is free of infinite chains
- Finite relative to r ∈ P iff the set
 Q=_{df} {q ∈ P | r ⊑ q ⊑ p} does not contain infinite chains

(Standard) CPO Constructions (1)

Flat CPOs.

Let (C, \sqsubseteq) be a CPO. Then (C, \sqsubseteq) is called

▶ flat, if for all $c, d \in C$ holds: $c \sqsubseteq d \Leftrightarrow c = \bot \lor c = d$



G1332/13
(Standard) CPO Constructions (2)

Product construction.

Let $(P_1, \sqsubseteq_1), (P_2, \sqsubseteq_2), \dots, (P_n, \sqsubseteq_n)$ be CPOs. Then

- the non-strict (direct) product ($\times P_i$, \sqsubseteq) with
 - ► $(X P_i, \sqsubseteq) = (P_1 \times P_2 \times \ldots \times P_n, \bigsqcup)$ with $\forall (p_1, p_2, \ldots, p_n),$ $(q_1, q_2, \ldots, q_n) \in X P_i. (p_1, p_2, \ldots, p_n) \sqsubseteq$ $(q_1, q_2, \ldots, q_n) \Leftrightarrow \forall i \in \{1, \ldots, n\}. p_i \sqsubseteq_i q_i$
- ▶ and the strict (direct) product (smash product) with
 - $(\bigotimes P_i, \sqsubseteq) = (P_1 \otimes P_2 \otimes \ldots \otimes P_n, \sqsubseteq)$, where \sqsubseteq is defined as above under the additional constraint:

$$(p_1, p_2, \ldots, p_n) = \bot \Leftrightarrow \exists i \in \{1, \ldots, n\}. p_i = \bot_i$$

are CPOs, too.

(Standard) CPO Constructions (3)

Sum construction.

Let
$$(P_1, \sqsubseteq_1), (P_2, \sqsubseteq_2), \dots, (P_n, \sqsubseteq_n)$$
 CPOs. Then

• the direct sum
$$(\bigoplus P_i, \sqsubseteq)$$
 with

►
$$(\bigoplus P_i, \sqsubseteq) = (P_1 \cup P_2 \cup ... \cup P_n, \sqsubseteq)$$
 disjoint union of P_i ,
 $i \in \{1, ..., n\}$ and $\forall p, q \in \bigoplus P_i$. $p \sqsubseteq q \Leftrightarrow \exists i \in \{1, ..., n\}$. $p, q \in P_i \land p \sqsubseteq_i q$

is a CPO.

Note: The least elements of (P_i, \sqsubseteq_i) , $i \in \{1, \ldots, n\}$, are usually identified, i.e., $\perp =_{df} \perp_i$, $i \in \{1, \ldots, n\}$

(Standard) CPO Constructions (4)

Function-space construction.

Let (C, \sqsubseteq_C) and (D, \sqsubseteq_D) be two CPOs and $[C \rightarrow D] =_{df} \{f : C \rightarrow D \mid f \text{ continuous}\}$ the set of continuous functions from C to D.

Then

 the continuous function space ([C → D], ⊑) is a CPO where

►
$$\forall f, g \in [C \rightarrow D]$$
. $f \sqsubseteq g \iff \forall c \in C$. $f(c) \sqsubseteq_D g(c)$

Monotonic, Continuous Functions on CPOs

Definition (A.4.5, Monotonic, Continuous Function) Let (C, \sqsubseteq_C) and (D, \sqsubseteq_D) be two CPOs and let $f : C \to D$ be a function from C to D.

Then f is called

 monotonic iff ∀ c, c' ∈ C. c ⊑_C c' ⇒ f(c) ⊑_D f(c') (Preservation of the ordering of elements)
 continuous iff ∀ C' ⊆ C. f(□_C C') =_D □_D f(C') (Preservation of least upper bounds)

Properties

Using the notations introduced before, we have:

Lemma (A.4.6) f is monotonic iff $\forall C' \subseteq C$. $f(\bigsqcup_C C') \sqsupseteq_D \bigsqcup_D f(C')$

Corollary (A.4.7)

A continuous function is always monotonic, i.e. f continuous implies f monotonic.

Inflationary Functions on CPOs

Definition (A.4.8, Inflationary Function) Let (C, \sqsubseteq) be a CPO and let $f : C \rightarrow C$ be a function on C. Then f is called

• inflationary (increasing) iff $\forall c \in C. \ c \sqsubseteq f(c)$

A.5 Fixed Point Theorem

G1339/13

Least and Greatest Fixed Points (1)

Definition (A.5.1, (Least/Greatest) Fixed Point) Let (C, \sqsubseteq) be a CPO, $f : C \to C$ be a function on C and let c be an element of C, i.e., $c \in C$.

Then c is called

• fixed point of f iff f(c) = c

A fixed point c of f is called

- ▶ least fixed point of f iff $\forall d \in C$. $f(d) = d \Rightarrow c \sqsubseteq d$
- greatest fixed point of f iff $\forall d \in C$. $f(d) = d \Rightarrow d \sqsubseteq c$

Notation:

The least resp. greatest fixed point of a function f is usually denoted by μf resp. νf.

Least and Greatest Fixed Points (2)

Definition (A.5.2, Conditional Fixed Point) Let (C, \sqsubseteq) be a CPO, $f : C \to C$ be a function on C and let $d, c_d \in C$.

Then c_d is called

► conditional (German: bedingter) least fixed point of f wrt d iff c_d is the least fixed point of C with d ⊑ c_d, i.e. for all other fixed points x of f with d ⊑ x holds: c_d ⊑ x.

Fixed Point Theorem

Theorem (A.5.3, Knaster/Tarski, Kleene) Let (C, \sqsubseteq) be a CPO and let $f : C \rightarrow C$ be a continuous function on C.

Then f has a least fixed point μf , which equals the least upper bound of the chain (so-called Kleene-Chain) $\{\perp, f(\perp), f^2(\perp), \ldots\}$, i.e.

$$\mu f = \bigsqcup_{i \in IN_0} f^i(\bot) = \bigsqcup \{\bot, f(\bot), f^2(\bot), \ldots\}$$

Proof of Fixed Point Theorem A.5.3 (1)

We have to prove:

 μf

- 1. exists
- 2. is a fixed point
- 3. is the least fixed point

of *f* .

Chap. 17

Proof of Fixed Point Theorem A.5.3 (2)

1. Existence

- It holds $f^0 \perp = \perp$ and $\perp \sqsubseteq c$ for all $c \in C$.
- By means of (natural) induction we can show: fⁿ⊥ ⊑ fⁿc for all c ∈ C.
- Thus we have fⁿ⊥ ⊑ f^m⊥ for all n, m with n ≤ m. Hence, {fⁿ⊥ | n ≥ 0} is a (non-finite) chain of C.

Proof of Fixed Point Theorem A.5.3 (3) 2. Fixed point property

$$f(\bigsqcup_{i \in IN_{0}} f^{i}(\bot))$$

$$(f \text{ continuous}) = \bigsqcup_{i \in IN_{0}} f(f^{i}\bot)$$

$$= \bigsqcup_{i \in IN_{1}} f^{i}\bot$$

$$(K \text{ chain} \Rightarrow \bigsqcup K = \bot \sqcup \bigsqcup K) = (\bigsqcup_{i \in IN_{1}} f^{i}\bot) \sqcup \bot$$

$$(f^{0}\bot = \bot) = \bigsqcup_{i \in IN_{0}} f^{i}\bot$$

Proof of Fixed Point Theorem A.5.3 (4)

3. Least fixed point

- Let c be an arbitrarily chosen fixed point of f. Then we have ⊥ ⊑ c, and hence also fⁿ⊥ ⊑ fⁿc for all n ≥ 0.
- Thus, we have fⁿ⊥ ⊑ c because of our choice of c as fixed point of f.
- Thus, we also have that c is an upper bound of {fⁱ(⊥) | i ∈ IN₀}.

Conditional Fixed Points

Theorem (A.5.4, Conditional Fixed Points) Let (C, \sqsubseteq) be a CPO, let $f : C \rightarrow C$ be a continuous, inflationary function on C, and let $d \in C$.

Then f has a unique conditional fixed point μf_d . This fixed point equals the least upper bound of the chain $\{d, f(d), f^2(d), \ldots\}, d.h.$

$$\mu f_d = \bigsqcup_{i \in IN_0} f^i(d) = \bigsqcup \{d, f(d), f^2(d), \ldots \}$$

Finite Fixed Points

Theorem (A.5.5, Finite Fixed Points) Let (C, \sqsubseteq) be a CPO and let $f : C \rightarrow C$ be a continuous function on C.

Then we have: If two elements in a row occurring in the Kleene-chain of f are equal, e.g. $f^{i}(\bot) = f^{i+1}(\bot)$, then we have: $\mu f = f^{i}(\bot)$.

Existence of Finite Fixed Points

Sufficient conditions for the existence of finite fixed points e.g. are

- Finiteness of domain and range of f
- F is of the form f(c) = c ⊔ g(c) for monotone g on some chain-complete domain

A.6 Cones and Ideals

Cones und Ideals

Definition (A.6.1, Directed Set, Cone, Ideal)

Let (P, \sqsubseteq) be a partial order and Q be a subset of P, i.e., $Q \subseteq P$.

Then Q is called

- directed set (German: gerichtet (gerichtete Menge)), if each finite subset R ⊆ Q has a supremum in Q, i.e. ∃ q ∈ Q. q = ∐ R
- ► cone (German: Kegel), if *Q* is downward closed, i.e. $\forall q \in Q \ \forall p \in P. \ p \sqsubseteq q \Rightarrow p \in Q$
- ► ideal (German: Ideal), if Q is a directed cone, i.e. if Q is downward closed and each finite subset has a supremum in Q.

Note: If Q is a directed set, then, we have because of $\emptyset \subseteq Q$ also $\bigcup \emptyset = \bot \in Q$ and thus $Q \neq \emptyset$.

Completion of Ideals

Theorem (A.6.2, Completion of Ideals)

Let (P, \sqsubseteq) be a partial order and let I_P be the set of all ideals of P. Then we have:

•
$$(I_P, \subseteq)$$
 is a CPO.

Induced "completion:"

Identifying each element p ∈ P with its corresponding ideal I_p=_{df} {q | q ⊑ p} yields an embedding of P into I_P with p ⊑ q ⇔ I_P ⊆ I_Q

Corollary (A.6.3, Extensibility of Functions)

Let (P, \sqsubseteq_P) be a partial order and let (C, \sqsubseteq_C) be a CPO. Then we have: All monotonic functions $f : P \to C$ can be extended to a uniquely determined continuous function $\hat{f} : I_P \to C$.

Summing up

The preceding result implies:

- Streams constitute a CPO.
- Recursive equations and functions on streams are welldefined
- The application of a function to the finite prefixes of a stream yields the chain of approximations of the application of the function to the stream itself; it is thus correct.

Appendix A: Further Reading (1)

- Paul Hudak. The Haskell School of Expression: Learning Functional Programming through Multimedia. Cambridge University Press, 2000. (Chapter 11, Proof by Induction; Chapter 14.6, Inductive Properties of Infinite Lists)
- Hanne Riis Nielson, Flemming Nielson. Semantics with Applications: A Formal Introduction. Wiley, 1992. (Chapter 4, Denotational Semantics)
- Hanne Riis Nielson, Flemming Nielson. Semantics with Applications: An Appetizer. Springer-V., 2007. (Chapter 5, Denotational Semantics)
- Peter Pepper, Petra Hofstedt. Funktionale Programmierung. Springer-V., 2006. (Kapitel 10, Beispiel: Berechnung von Fixpunkten)

Appendix A: Further Reading (2)

- Simon Thompson. Haskell: The Craft of Functional Programming. Addison-Wesley/Pearson, 2nd edition, 1999. (Chapter 8, Reasoning about Programs; Chapter 17.9, Proof revisited)
- Simon Thompson. Haskell: The Craft of Functional Programming. Addison-Wesley/Pearson, 3rd edition, 2011. (Chapter 9, Reasoning about Programs; Chapter 17.9, Proof revisited)